

## Virginia Commonwealth University VCU Scholars Compass

Capstone Design Expo Posters

College of Engineering

2015

## Robotic Inspection of Geometrically Complex Tank Systems

James Dinsmore Virginia Commonwealth University

Jay Kim Virginia Commonwealth University

Randolph Snook Virginia Commonwealth University

Thanh Tran Virginia Commonwealth University

Trenton Wilhelmi Virginia Commonwealth University

Follow this and additional works at: https://scholarscompass.vcu.edu/capstone Part of the Mechanical Engineering Commons, and the Nuclear Engineering Commons

© The Author(s)

Downloaded from https://scholarscompass.vcu.edu/capstone/56

This Poster is brought to you for free and open access by the College of Engineering at VCU Scholars Compass. It has been accepted for inclusion in Capstone Design Expo Posters by an authorized administrator of VCU Scholars Compass. For more information, please contact libcompass@vcu.edu.

Team Members: James Dinsmore, Jay Kim, Randolph Snook, Than Tran, Trenton Wilhelmi

Faculty Advisor: Dr. John E. Speich

**Robotic Inspection** of Geometrically Complex Tank Systems

CAPSTONE DESIGN EXPO 2015

Sponsor: Newport News Shipbuilding Sponsor Advisor: Richard Hillyer, Allen

## Introduction

Collaboration between Newport News Shipbuilding and VCU School of Engineering

MECHANICAL AND NUCLEAR

- Continuation of 2013-2014 Senior Design Project
- Automated robotic inspection system to move within confined tanks to reduce manned entry work hours
- Tank system contains individual bays with an average size of 47" X 35"
- Lightening holes for entry are approximately 20" in diameter, but range in size and shape



Mock-up of Bay System

## Design Objectives

- Invert the rail system to allow for manned entry without the necessity to remove the railings
- · Redesign the carriage system to accommodate the inverted rail system
- · Ability to traverse corner bays to allow for continuous inspection
- Remotely operated motorized control system to move carriage throughout the bay system







Modeling of Rail System

- · Utilizes magnets to support the rail system
- · Down rod with turnbuckle to allow for height adjustment
- · Hanger Bars connect the down rods to the PVC railings
- Two hanging systems per bay to provide support for robotic arm operations
- · Curved pipe with radii of 6" and 14" for corner bays





Built Hanger System





Carriage Design

- Solid plate foundation that supports the UR-5 Robotic Arm and attachments
- Pivoting wheel housing group allowing for the carriage to navigate the curved rail
- Independent drive system consisting of four servo motors to reduce slip around the curved rail
- Wheel housing group mounted above carriage deck to allow for the inverted rail design





Displacement of Carriage Deck with UR-5 Fully Extend

Future Development

- Increase stability of the rail system to allow for future applications such as blasting and coating of tanks
- · Precise motorized control for exact position locating in the bay system
- · Improvement in rail material for increased durability
- Further research on end effectors





Special Thanks To Newport News Shipbuilding for Guidance and Support

Make it real.

VIRGINIA COMMONWEALTH UNIVERSITY