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MODELING VEGETATION EFFECTS ON BARRIER ISLAND EVOLUTION WITH SEA LEVEL RISE

A thesis submitted in partial fulfillment of the requirements for the degree of Master of Science at Virginia Commonwealth University.

by

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Master of Science

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I would like to thank my parents and brother, who have shown endless patience and support throughout my life while managing to imprint upon me an appreciation for the arts, a love of science, and a desire to see more and learn more about all things.

Table of Contents

Acknowledgements	iii
List of Figures	vii
List of Tables	viii
Abstract	ix
1 Introduction	1
2 The Model	5
2.1 Plant Populations	6
2.2 Aeolian Transport	10
2.3 Avalanche	12
2.4 Marine Processes	13
3 Results	17
3.1 Experiment Design	17
3.2 Parameterization	20
3.3 Results - Variations on Initial Plant Conditions and Sea Level Rise	26
3.3.1 No Sea Level Rise	27
3.3.2 Constant Sea Level Rise	28
3.3.3 Accelerating Sea Level Rise	29

4 Conclusion	32
Bibliography	35
A Notation Index	39
B MATLAB code	42
B.1 Main code	42
B.2 Aeolian Transport code	65
B.3 Avalanche code	82
B.4 Plant Propagation code	92
B.5 Shoreline code	103
B.6 Marine Processes code	106

List of Figures

2.1	Flow chart of the model pathway	6
2.2	8 cell neighborhood	12
2.3	A moving window transect considering the impact of vegetation on the yearly migration of the shoreline for row i (given by the dashed line). Equation (2.9) takes into consideration all of the values of PC which fall within the red lines. The left image is the elevation map, while the right image is the total population density scaled by erosion inhibiting factors, PC)	15
3.1	Original, color-coded images of Virginia barrier islands	18
3.2	Elevation maps for Smith and Parramore Island	19
3.3	Illustration of island evolution spanning 27 years	20
3.4	Plots of the elevation map for Smith island before and after 27 years of evolution.	22
3.5	Close up of the elevation map with contours for areas around the centroid of Smith island before and after 27 years of evolution.	22
3.6	Plots of percent plant cover for each P_k at areas focused around the centroid of Smith island before and after 27 years of evolution.	23

3.7 A progression of contours plots of elevation map taken at 0, 12, and 27 years compared to similarly timed contours of Smith island. The dots represent the centroid of the island for that year.	24
3.8 A progression of contour plots of elevation map taken at 0, 12, and 27 years compared to similarly timed contours of Parramore island. The dots represent the centroid of the island for that year.	25
3.9 Evolution of Smith island in the absence of sea level rise, $M_a = 0$, taken at varying percentages of initial and maximum plant cover.	27
3.10 Evolution of Smith island with constant sea level rise, $M_a = 1$, taken at varying percentages of initial and maximum plant cover.	28
3.11 Evolution of Smith island with accelerating sea level rise, $M_a = 1.0075$, taken at varying percentages of initial and maximum plant cover.	30

List of Tables

2.1	Elevation ranges of each plant species.	7
2.2	The number of cells that sediment may be moved downwind corresponding to different possible wind speed values. The presence of plants may reduce the distance moved by sediment. High wind events will be the focus of later research.	10
2.3	Reduction values for ranges of scaled total percent cover	16
3.1	Select parameters optimized during this study, along with the migration rate reduction values given in Table 2.3.	21
A.1	Model constant and parameter notion and values, * values are for Smith, Parramore respectively.	40
A.2	Model arrays and variables	41

Abstract

Barrier islands play a significant role in protecting coastlines and harboring coastal habitats. In an effort to study and better understand the evolution of barrier island systems, a cellular model capturing various meteorological and environmental processes is proposed. Erosion due to wind, gravity, and marine processes are coupled with plant population effects. We demonstrate the inhibition of plant cover on sediment mobility, island migration, and erosion in the presence of sea level rise.

Chapter 1

Introduction

Barrier islands are chains of land masses that form offshore from many coastal regions around the world, and often serve as a defensive formation against the impact of adverse weather systems [26]. These formations play a critical role in defending mainland shorelines and protecting inhabitants from storm surge and erosion, and additionally act as shelter protecting nearby habitats in the marshes and estuaries, many of which support fishing economies [15]. As home to diverse biological ecosystems, it is all the more critical that we understand the processes which govern their evolution. Barrier island geomorphology is affected by climate change, which may increase the duration and frequency of storms and escalate the rate of sea level rise [5]. A model for predicting the evolution of barrier islands in response to changing climatic conditions and local plant ecology is critical in aiding policy makers in regulating coastal regions.

The evolution of barrier island geography is largely dependent upon the erosive effects of wind and wave activity [12]. Stable barrier islands migrate landward as sea level rises [3]. Island migration is a response to long-term processes like regular tidal dynamics and wind erosion, coupled with more dramatic overwashing events where large amounts of sediment are moved from the foredune onto the backbarrier marsh portions of the island [16]. When keeping insufficient pace with sea level rise, overwashing and

tidal deposition can result in the flattening and eventual drowning of the island [21]. The likelihood of overwashing events is closely tied to island characteristics like transectional width and maximum dune height [19].

The interactions between vegetation and sediment transport are critical elements governing the dynamical evolution of coastal dune landscapes [1]. There is a positive correlation between plant density and sediment retention [11]. Plants are sensitive to changing island topography, physical impacts of waves, groundwater, nutrients and exposure to sea spray [30]. Furthermore, overwash events may reduce, or potentially eliminate, vegetative cover by exposing plants to lower elevations, or by destroying protective dune barriers, subjecting the plants to the stresses of saltwater flooding and sand burial [2]. Loss of dune cover, and subsequently the loss of dune-building plant life, have long term effects on the elevation of the island.

Multiple models have been created to demonstrate a variety of evolutionary behaviors exhibited by barrier islands. In 1995, B.T. Werner introduced a cellular model, where dunes are constructed with slabs of sediment and the elevation taken to be proportional to the number of slabs present at any location in the domain. Slabs of sediment are then transported about the domain, subject to natural erosive properties [29]. The algorithm in the model successfully recreates the effect of wind erosion and deposition, or “aeolian transportation,” of sediment. Werner’s model omits any effects of vegetation of sediment transport, and deposition is dependent only on wind speed and the angle of repose between neighboring sediment slabs. The model also includes the gravitational response of sediment collapse from higher elevations to lower elevations, termed “avalanching”.

The ISLAND model developed by E.B. Rastetter in 1991 incorporated plant populations with annual changes in vegetation, geomorphology, water table depth and groundwater salinity on cross-sectional transects of barrier islands [23]. Plant development is considered in life stages by repeatedly calculating the probability of successfully progressing to the next stage in order to determine overall survival. Plants are divided by

classification as grasses, annuals, and perennials to establish life stage conditions and duration.

In 2002, Andres Baas proposed a cellular dune landscaping model, DECAL, which incorporated vegetation into the algorithm, capturing the richer dynamics brought about by the interaction between vegetation and sand transport processes [1]. This model reproduced many elements from Werner's work, including wind erosion and avalanching processes. The work's greatest achievement lies in successfully incorporating plant populations into a cellular domain and establishing dune formation dependence upon the existence of vegetation. The model does not incorporate any marine processes, sea level rise, or other beach profile dynamics.

Keijser, DeGroot, and Riksen presented the DUBEVEG model in 2016. The cellular automaton incorporates three primary components: aeolian transportation, living plant populations, and the effects of regular marine processes. The DUBEVEG model did not encompass the entire island domain, only extending as far as the initial foredune. Additionally, the effect of wind transportation was of limited practical application as the model employed only unidirectional wind forces at constant rates [12].

Many two-dimensional models have sought to capture the dynamical behavior of shoreline slopes on a single transect of the island (see [13], [14], [10], [7], [6]). These models track cross-shore evolution and primarily focus on the active shoreface region. The basis of these models is typically some modification or extension upon the "Bruun Rule." In 1962, Bruun proposed a relationship between sea-level rise and shoreline recession based on the profile of the beach [4]. Maurice Schwartz tested this relationship in laboratory settings before giving it the eponymous moniker it is known by today in his 1964 publication [25].

Two dimensional barrier island models typically only consider the shore profile and do not extend into the subaerial portions of the island beyond the initial dune ridge. In 2010, Rosati et al. developed the 2DMCO model, a cross-shore model that is situated

over top of a compressible substrate, resulting in the eventual inundation of the island with the progression of landward migration [24]. The BRIE model given by Nienhuis et al. in 2019 details alongshore sediment transport, as opposed to limiting such transport to cross-shore fluxes, as well as inlet dynamics and flood tidal delta depositions [19]. An algorithm outlined by Lorenzo-Trueba et al. in 2014 presented four different responses to sediment fluxes: height drowning, width drowning, constant landward retreat, and periodic retreat [13]. These examples treat overwash of sediment as the primary driver of island migration, and assume little or no activity in the absence of storm events.

We present a comprehensive model capturing geomorphology via meteorological processes while accounting for living plant populations. The weathering processes in our model were partly inspired by the DECAL [1] and DUBEVEG [12] models proposed by Nield and Baas and Keijser et al., respectively. We include four species of plants and examine their effect on island evolution under various sea level rise scenarios.

Chapter 2

The Model

The primary model framework is an array, H , composed of numbers of slabs of sediment. Each block of sediment has dimensions $\delta \times L \times L$, where δ is the thickness or height of the slab, and L is the width and length of each slab. The island and surrounding region is discretized at locations (i, j) , for $i = 1, \dots, n$ and $j = 1, \dots, m$. The elevation of the landscape at (i, j) is given by $\delta H(i, j)$, where $H(i, j)$ is the number of slabs of sediment at location (i, j) relative to sea level. Additional arrays, $P_k(i, j)$ for $k \in \{1, 2, 3, 4\}$, represent the population density of plant species k at cell (i, j) .

Sand and other sediments that make up the subaerial portion of the island shift in response to wind erosion and deposition of sediment, natural gravitational collapse, and landward migration due to marine processes and sea level rise. The presence of plants impede the movement of sediment. The likelihood of each slab of sediment shifting or eroding is inversely proportional to the vegetation cover.

A flow chart for the model procedure is given in Figure 2.1 and explained in further detail in the following sections.

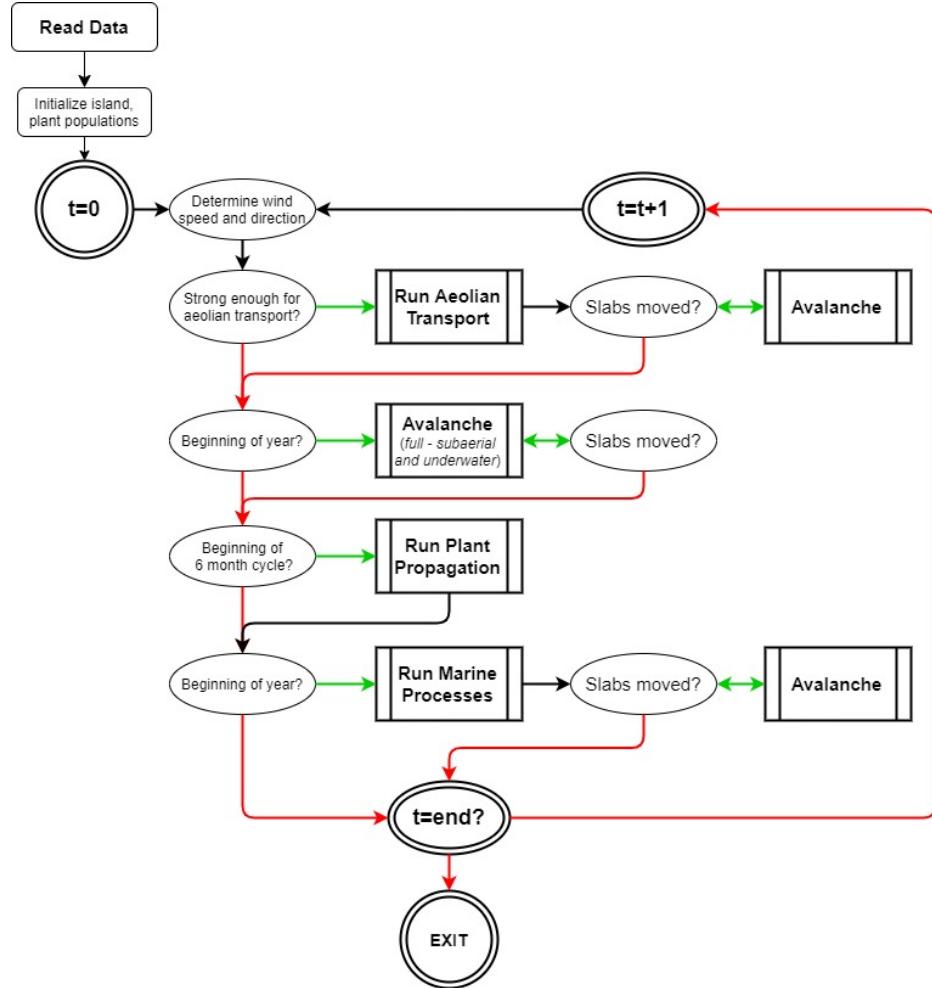


Figure 2.1: Flow chart of the model pathway.

2.1 Plant Populations

The model includes four species of plants native to Virginia's barrier islands: *Ammophila breviligulata*, *Spartina patens*, *Morella cerifera*, and *Spartina alterniflora*. *Ammophila breviligulata* is the primary dune-building grass. Both *Spartina* species are marsh grasses, but *Spartina alterniflora* grows exclusively in the marsh while *Spartina patens* can populate much higher elevations as well. *Morella cerifera* is a woody shrub. Plant populations inhabit elevation ranges given in Table (2.1) and are limited only by their respective growth and death rates, elevation tolerance, and ability to compete for space with neighboring

plant species.

Species	P_k	$\lambda_{L,k}$	$\lambda_{H,k}$
Ammophila breviligulata	P_1	1 m	5m
Spartina patens	P_2	0.75m	3m
Morella cerifera	P_3	1.5m	2.5m
Spartina alterniflora	P_4	-0.5m	1m

Table 2.1: Elevation ranges of each plant species.

For a species k , with $k \in \{1, 2, 3, 4\}$, the population density of each cell, given by $P_k(i, j) \in [0, 1]$, can vary seasonally. Growth is determined for each species k on cell (i, j) by selecting a growth parameter, $\gamma_k(i, j, t)$, uniformly on the interval $[g, G]$, that may include both positive and negative values such that $\gamma_k(i, j, t) < 0$ indicates plant death, $\gamma_k(i, j, t) > 0$ indicates plant growth, and $\gamma_k(i, j, t) = 0$ has no effect on the current population density of the cell. Different ranges of parameter values capture the behaviors of growth and death associated with different seasons, as indicated by the time dependence $\gamma_k(i, j, t)$.

Propagation of plants into new cellular regions is handled by polling the plant populations of neighboring cells. For a species k at location (i, j) with population $P_k(i, j)$ we define $\Omega_{k,n}$ for $n = 1, 2, \dots, 8$, to be the Moore neighborhood (8-cell) adjacent to cell (i, j) . Propagation into the current cell is considered to be at the same growth rate, $\gamma_k(i, j, t)$, as is applied to growth within the cell. The new population density, P'_k , is given by

$$P'_k = P_k(1 + \gamma_k(i, j, t)) + \sum_{n=1}^8 \gamma_k(i, j, t) \Omega_{k,n}. \quad (2.1)$$

Note that if there is no species population on the current cell (i.e. $P_k(i, j) = 0$), then equation (2.1) represents the spread of vegetation from populations of neighboring cells into new territory at cell (i, j) when $\sum_{n=1,2,\dots,8} \Omega_{k,n} \neq 0$. In the case that $P_k(i, j) \neq 0$, it is

assumed that proximity to same-species populations creates stronger growth within a cell if $\gamma_k(i, j, t) > 0$. In effect, this represents better protection for communities of plants surrounded by the same species of plant. These populations would naturally experience higher rates of development than those that stood alone, or those with fewer neighboring same-species populations. The effect is similar in cases of $\gamma_k(i, j, t) < 0$, as proximity to dying plants is likely to effect same species plants. Provided at least one cell in the eight cell neighborhood currently hosts the species, equation (2.1) accounts for propagation into cells that were previously unpopulated, as well as growth within a cell that already has an established population. All cells that lie within the plants viable elevation range given in Table 2.1 are susceptible to growth.

The woody shrub *Morella* has an additional propagation condition. The seeds of this plant species are spread by birds locally. This is accounted for by allotting each cell within the viable growing range a small probability of a population being established at random, without requiring the existence of neighboring populations of *Morella*.

Each plant type is defined by a maximum percent cover value, η_k . We use these factors to modify the new population density, P'_k as given in equation (2.1) to

$$P'_k = \min \left(\eta_k, P_k (1 + \gamma_k(i, j, t)) + \sum_{n=1}^8 \gamma_k(i, j, t) \Omega_{k,n} \right), \quad (2.2)$$

where we ensure growth does not exceed the maximum percent cover, η_k , for species k .

If shifting sediment causes a cell with a plant population to fall outside of the viable elevation range, (i.e. $\delta \cdot H(i, j) < \lambda_{L,k}$ or $\delta \cdot H(i, j) > \lambda_{H,k}$ for the values given in Table 2.1), then the plant population begins to die at some fixed rate. We define β to be the death by elevation rate, and for every time step outside of the viable range for a population $P_k(i, j)$, the plant density is diminished by

$$P'_k = P_k - \beta P_k.$$

Multiple species of plants may cohabit the same cell. We define a global maximum percent coverage, M_∞ , as an upper bound for a cell's total population density. The total percent cover array, T , is managed for all cells within the island domain for this purpose. This array is defined as

$$T(i, j) = \sum_{k=1}^4 P_k(i, j).$$

Plants may die due to competition or overcrowding. Death by competition occurs whenever $T(i, j) > M_\infty$. Our model is designed to favor *Morella* populations (P_3), hence when a cell become overpopulated, residing non-*Morella* plant species (i.e. the grass species) are reduced while leaving the *Morella* populations intact. In this event we let the excess coverage be given by $a = T(i, j) - M_\infty$ and define a new value for k^{th} species of grass ($k = 1, 2, \text{ or } 4$),

$$P'_k(i, j) = P_k(i, j) - \frac{a}{l}, \quad (2.3)$$

where $l \in \{1, 2, 3\}$ is total number of grass populations present on the cell (i, j) . Equation (2.3) reduces the percent cover of any plant species presently residing on the cell to an even proportion of the space that is not being occupied by $P_3(i, j)$. If $P_3(i, j) = 0$, then the entire space is evenly divided among the grasses.

The woody shrub *Morella* has two more unique characteristics. *Morella* demonstrates a clear tendency to grow on the nearshore side of the island where it is guarded from the salt water spray of the ocean [30]. To accommodate for this trend, *Morella* communities having population cells within the boundaries of the beach region are subjected to gradual decay.

2.2 Aeolian Transport

Aeolian transportation is the movement of sediment by the wind. Saltation occurs when sediment is lifted up by the wind and deposition occurs when the sediment resettles. For our model, the presence of sufficient wind speeds prompts the removal of a slab of sediment from one cell which is then deposited one or more cells downwind. We adapt a wind table from existing research in order to consider a range of wind speeds which are likely to cause aeolian transport [8]. Wind measurements for the model environment are based on data taken from Hog Island, Virginia between 2007 and 2012 [22]. A wind speed, ω , is sampled from the data set and the possible extent of a slab being transported is determined using Table 2.2.

Wind Speed (m/s)	Distance (in cells)
$\omega < 6$	0
$6 \leq \omega < 9$	1
$9 \leq \omega < 13$	2
$13 \leq \omega \leq 16$	3
$16 < \omega$	not considered

Table 2.2: The number of cells that sediment may be moved downwind corresponding to different possible wind speed values. The presence of plants may reduce the distance moved by sediment. High wind events will be the focus of later research.

A wind direction is sampled from the same data set. The chosen direction is then associated with a even scalar multiple of $\pi/8$ (22.5°) corresponding to a typical compass rose. Wind in the northern direction (blowing south to north) corresponds to wind angles between $-\frac{\pi}{8}$ and $\frac{\pi}{8}$, north-western wind corresponds to wind angles between $\frac{\pi}{8}$ and $\frac{3\pi}{8}$, and so on. Erosion is considered to be taken from the current cell as $H(i, j) = H(i, j) - 1$ and deposited in any of the directions associated with the downwind current, i.e. $H'(i, j) = H'(i, j) + 1$. With a westerly wind sediment can be deposited $d \in \{1, 2, 3\}$

cells away, to $H'(i, j) \in \{H(i, j-d), H(i-d, j-d), H(i+d, j-d)\}$ which are the western, north-western, or southwestern cells, respectively. Every step taken requires that the angle between the current and destination cells be no greater than 15° [17].

Plants act as barriers to wind flow, effectively reducing local wind speed and allowing sediment to accumulate [9]. To approximate the inhibition of erosion due to each plant species we associate an erosion coefficient parameter, $\alpha_k \in [0, 1]$. Known plant characteristics are taken into consideration. For instance dune building grasses and shrubs with large root systems have a higher erosion coefficient than normal grasses. The effective plant cover array, PC is the weighted effect of all plant populations at a given location on the island given by

$$PC(i, j) = \sum_{k=1}^4 \alpha_k P_k(i, j). \quad (2.4)$$

Note that the effective plant cover array satisfies $PC(i, j) \in [0, 1]$ and represents the ability of all plants on the cell to impede erosion. The effective plant cover scales wind speed to determine the probability that conditions are sufficient to overcome the impeding effects of vegetation and permit saltation at a given cell.

If a slab moves more than one cell width, each step beyond the first requires a check for vegetation present in the cell to determine if the sediment stops or continues to move. The probability of erosion at the d^{th} step, ρ_{e_d} for $d \in \{1, 2, 3\}$, is based on the weighted densities of plant populations given in equation (2.4) and the chosen wind speed, calculated as

$$\rho_{e_d} = (1 - PC(i, j)) \cdot \frac{\omega - \omega_L}{\omega_H - \omega_L}, \quad (2.5)$$

where ω_L is the minimum wind speed required for aeolian transportation, and ω_H is the maximum wind speed considered by the model. Note that equation (2.5) satisfies $\rho_{e_d} \in [0, 1]$, and as the effective plant cover PC increases, the probability of erosion decreases. The likelihood of erosion is therefore inversely proportional to the density of

vegetation while being directly proportional to the wind speed.

A cell being transported has a 50% chance of moving with the wind direction, and a 25% of moving in either of the off-directions. A more rigid probability is dependent upon the angle between the current slab and the destination slab, with preference going to the direction where the angle is steepest. We do not adjust for this probability here, as sediment will always shift in the direction of a sufficiently steep angle as will be explained in section 2.3.

2.3 Avalanche

As sediment moves around the island domain, it is possible that unrealistically steep mounds of sediment have formed. Gravitational forces effect these steep mounds by causing avalanches of sediment from areas of higher elevation into areas of lower elevation when certain conditions are met.

1 $H(i-1, j-1)$	2 $H(i-1, j)$	3 $H(i-1, j+1)$
4 $H(i, j-1)$	5 $H(i, j)$	6 $H(i, j+1)$
7 $H(i+1, j-1)$	8 $H(i+1, j)$	9 $H(i+1, j+1)$

Figure 2.2: 8 cell neighborhood

The angle of repose between two cell elevations is given by the angle measure

$$\theta' = \tan^{-1} \left(\frac{H(i, j) - H'(i, j)}{L} \cdot \delta \right), \quad (2.6)$$

where $\delta H'(i, j)$ is the elevation of any cell in the von Neumann (4-cell) neighborhood of cell (i, j) , labeled as 2, 4, 6, and 8 in Figure 2.2.

A critical angle of repose, θ_o , is defined as the shallowest angle between neighboring stacks of sediment which prompts sediment to collapse [1]. If θ' , as calculated from equation (2.6), satisfies $\theta' \geq \theta_o$, then the polled cell is in violation of the critical angle of repose and the probability of avalanching, ρ_{av} , is given by

$$\rho_{av}(i, j) = \min\left(1, \frac{\theta'}{\theta_o} \cdot (1 - PC(i, j))\right). \quad (2.7)$$

In the absence of plant populations, $PC(i, j) = 0$, and avalanching is guaranteed. For cells partially or entirely covered by vegetation the erosive quality of the surrounding sediment is hindered [30]. In this scenario the probability found by equation (2.7) the effective percent cover value satisfies, $PC(i, j) > 0$, as given in equation (2.4). Clearly when the effective plant cover is high, the probability of collapse is much reduced.

2.4 Marine Processes

Barrier Island shorelines are sculpted by a variety of processes, including tidal erosion and deposition, and aeolian transport of sediment. Each of these mechanisms involve a great deal of variation. For instance, water levels vary on a variety of timescales such as those during daily tidal cycles versus weekly neap-spring cycles, or during inclement weather events which bring storm surges and overwashing; any of which may become more or less prevalent over seasons or years [6].

The model focuses on long-term migratory behavior due to sea-level rise, and not on active shoreface profiling. The beach profile is assumed to be impacted only by aeolian processes. The sediment supply to the beach is otherwise abundant and sufficient to maintain a given rate of migration. For our purposes, the islands migrate at some rate that is consistent with observed shoreline changes as well as the assumptions required

to employ the Bruun model as outlined in [25].

The rate of shoreline recession, R , varies widely from island to island, so the individual rates of migration are estimated from existing resources. For the Virginia barrier islands that are the focus of this study, these rates were established using the Virginia Coastal Resilience planning tool [27] which is compiled based on data sets provided by the Virginia Institute for Marine Science [28].

The Bruun model derives a basic relationship for predicting the shoreline recession, R , from an increase in sea level rise, S , as

$$R = \frac{A^*}{B + h^*} S. \quad (2.8)$$

A^* is taken to be the cross-shore distance to the depth of closure, h^* . The depth of closure is the depth along the beach profile at which point sediment transport is minimal or non-existent. The height of the berm, B , is the uppermost portion of the beach face. As noted by Davidson-Arnott [6], for shallow shore angles, θ_b , the equation 2.8 can be approximated as

$$R \approx \frac{1}{\tan \theta_b} S,$$

where $\theta_b \approx (B + h^*)/A^*$ is the average slope of the nearshore. A common rate for sea level rise on the central eastern coast of United States is about 1/4 inch, or 6.35 millimeters, per year [20].

For $R < L$, where L is the width of a cell in the island domain, accumulated migration distances for each vertical location, i , is stored in the vector R_i until sufficient time has passed such that the island can be moved landward by one unit length with respect to that vertical coordinate. The entire subaerial portion of the island then migrates in unison with the shoreline, as defined as the easternmost horizontal cell location, j_s , of the elevation map for each vertical location i , for which $H(i, j_s) \geq 0$.

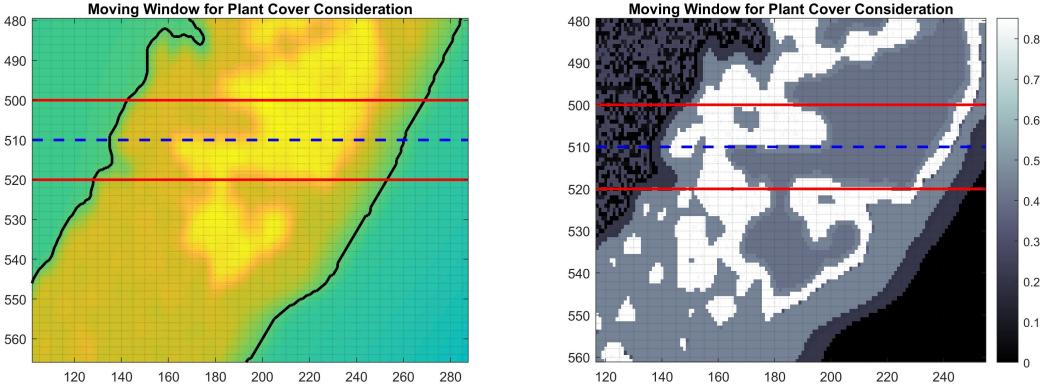


Figure 2.3: A moving window transect considering the impact of vegetation on the yearly migration of the shoreline for row i (given by the dashed line). Equation (2.9) takes into consideration all of the values of PC which fall within the red lines. The left image is the elevation map, while the right image is the total population density scaled by erosion inhibiting factors, PC

The effect of vegetation on migration is measured using a moving transectional window of size $2w \times n$ as given in Figure 2.3. The value w is number of rows above and below the current row, i , and n is the total number of horizontal cells in the island domain. Using the effective plant cover, PC, as given in equation (2.4), the total weighted percent coverage values within the window are averaged such that cumulative impact of the nearby plant population at vertical location i is given by

$$X_p = \frac{\sum_{r=-w}^w \sum_{j=1}^n PC(i+r, j)}{\Psi}, \quad (2.9)$$

where Ψ is the area of the subaerial portion of the island within the transectional window. The resulting scalar, $X_p \in [0, 1]$, is used to calculate the extent of the migration. The migration landward in meters for the current row, R_i , is reduced each year by factors given in Table 2.3.

Reduction of R_i	X_p range
100%	$0.5 \leq X_p$
70%	$0.35 \leq X_p < .5$
50%	$0.1 \leq X_p < .35$

Table 2.3: Reduction values for ranges of scaled total percent cover

We wish to examine different sea level rise scenarios. To accomplish this we define the following equation

$$R = \lfloor R_o(M_a)^{t/26} \rfloor, \quad (2.10)$$

where R_o is the initial rate of the island migration, $t/26$ gives the current number of years passed (we take t to be a two week time step), and $\lfloor \cdot \rfloor$ is the floor function. The parameter for migration acceleration, M_a , is varied to correspond with a desired rate of sea level rise. We wish to consider the absence of sea level rise, constant rates of sea level rise, and accelerating rates of sea level rise. For no sea level rise we take $M_a = 0$. Constant sea level rise is achieved by taking $M_a = 1$. For acceleration of sea level rise, we take $M_a > 1$ such that the desired rate of increase is observed.

Chapter 3

Results

The goal of this study is to model the impact of vegetation on the evolution of a barrier island system. We assess variations in evolutionary behavior based on the percent cover of plant populations and three different sea level rise scenarios. Baseline parameter values are established using vegetation and shoreline data for existing islands. With these parameters established, we examine the effects of vegetation assuming no sea level rise, constant sea level rise, and accelerating sea level rise.

3.1 Experiment Design

Two unique barrier island elevation maps are utilized establish our parameter values. The maps are used to outline basic trends in evolution at an accelerating rate of sea level rise. Both are compared to existing geographical images to confirm model accuracy and thus confirm that the chosen parameters are reasonable. Either map will then be used for additional testing which will vary the initial plant percent cover conditions and rates of sea level rise.

The maps are created using the known distribution of plant species on two barrier islands from the Eastern Shore of Virginia: Smith Island and Parramore Island. Simple imagery compiled from field observations are color-coded by variety of vegetation

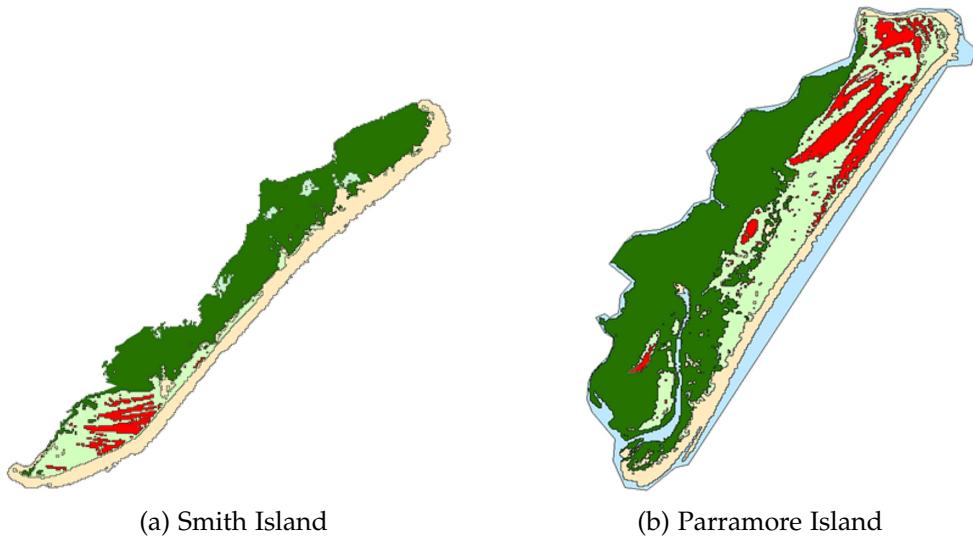
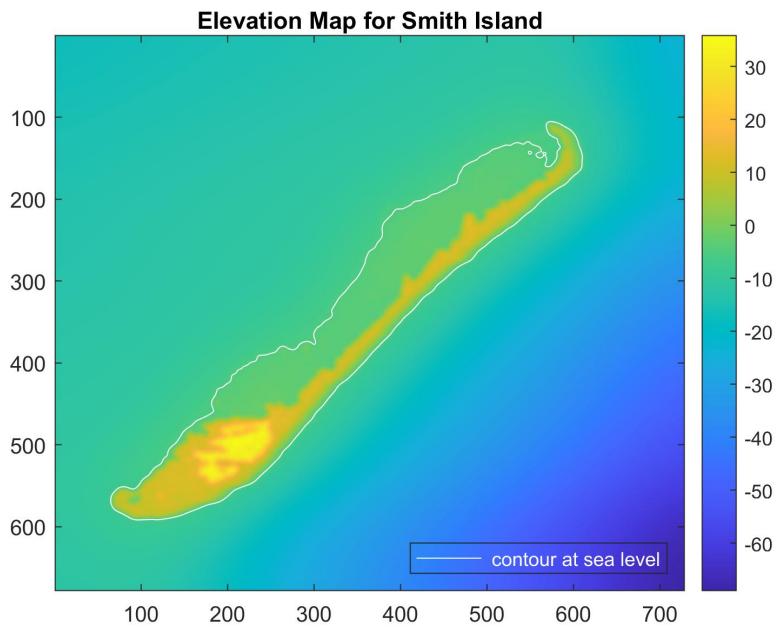


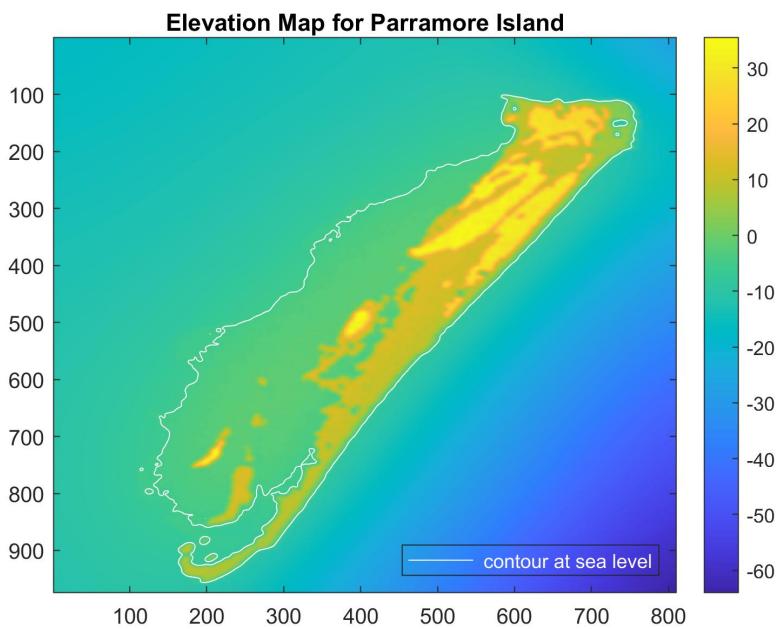
Figure 3.1: Original, color-coded images of Virginia barrier islands

present at each area. As seen in Figure 3.1, a dark green was associated with the marsh region, a lighter green for the dune grasses, red for the woody shrub, and a tan beach region with no vegetation.

Using these maps we approximated the elevation array, $H(i, j)$, based on Table 2.1. Areas below sea level were added by linear interpolation east and west from the boundary of island, with a shallower slope for the backbarrier marsh west of the island and a steeper slope for the ocean facing eastern side of the island. The resulting elevation maps used for our tests are given in Figure 3.2. These elevation maps are used to seed the island with appropriate plant life, generating our plant cover arrays, P_k .



(a) Smith Island



(b) Parramore Island

Figure 3.2: Elevation maps for Smith and Parramore Island

Note from Figure 3.1a that the northern portion of Smith island is long and narrow,

with significant beach cover and little vegetation. Alternatively, the southern portion has much denser cover, and more plant variety, covering a larger surface area. In this case we would expect that vegetation would hinder the migration and sediment movement on the southern portion of the island and the lack of plant cover would encourage movement in the northern region. Parramore Island, seen in Figure 3.1b, shows the opposite trend: more vegetation in the north and less in the south. We would expect to see more movement in the south and less movement in the north.

Island evolution is simulated over a 27 year time period. The resulting figures are compared to illustrations taken from satellite imagery over the period of time from 1984-2011, seen in 3.3. These images are converted to overlaid contours, and compared with contour outputs of the model sampled at 9 year intervals.

3.2 Parameterization

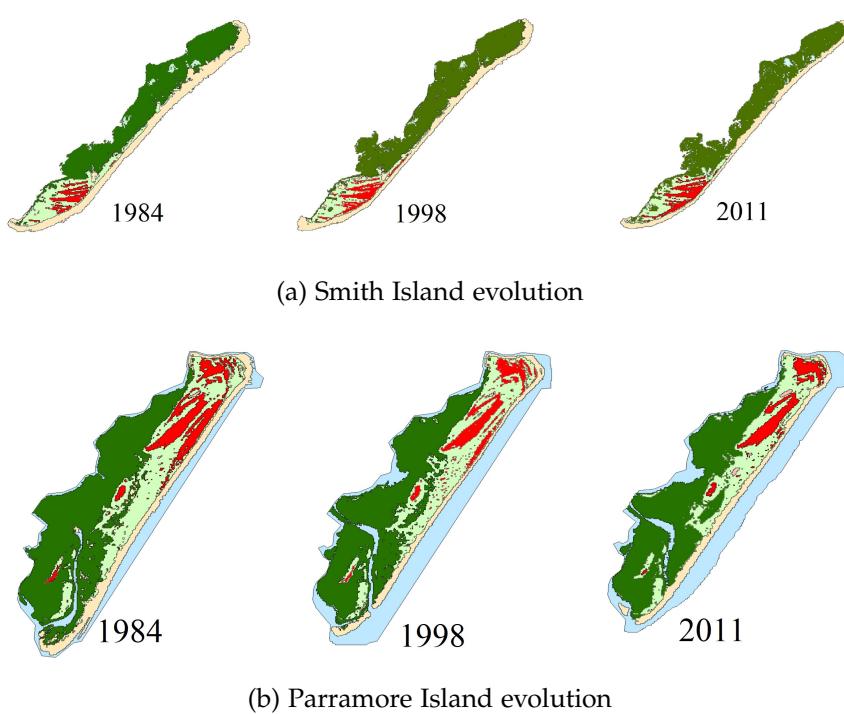


Figure 3.3: Illustration of island evolution spanning 27 years

Parameterization for this model is difficult due to the large number of parameters, the paucity of good, long-term available data, and lack of sources with proper experimentation for these parameter values. Some of our parameters are established through educated guess followed by repeated model testing for optimization (for a full list see Table A.1 in appendix A). The parameters that require specific attention for these tests included those in Table 2.3 and those given in Table 3.1.

Note the coefficient α_1 is slightly larger than α_2 , reflecting the status of P_1 as the primary dune building grass. The coefficient α_3 is large because the woody shrub has larger root systems, and wider leaf cover, making it more capable of stopping sediment in motion. The marsh *Spartina* has a large erosion coefficient due to being primarily underwater. The growth range γ_k along with the death by elevation was was established through repeated model tested to ensure plant life stayed abundant and thriving.

The maximum percent cover values for all plant populations used during parameterization is taken to be 100%, ensuring an abundant plant population. Sea level rise is accelerating, resulting in an escalation of yearly migration. We take these conditions to be approximate to those of the island between 1984 and 2014.

Notation	Definition	Value
α_1	erosion coefficient for P_1	2/3
α_2	erosion coefficient for P_2	1/3
α_3	erosion coefficient for P_3	1
α_4	erosion coefficient for P_4	1
γ_k	growth range	[-0.02, 0.08]
β	death by elevation percentage	-0.3
R	rate of migration due to sea level rise	15 m/year

Table 3.1: Select parameters optimized during this study, along with the migration rate reduction values given in Table 2.3.

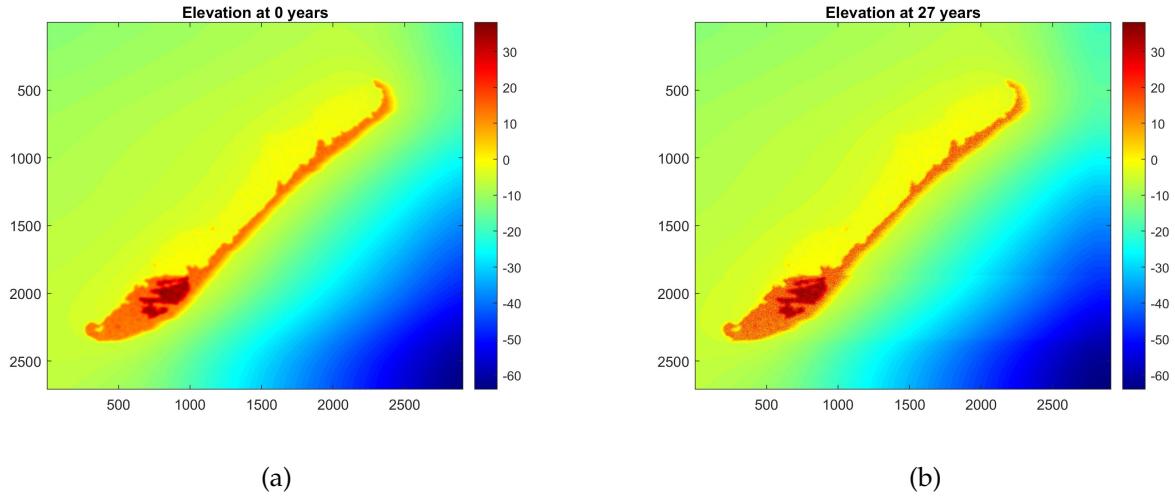


Figure 3.4: Plots of the elevation map for Smith island before and after 27 years of evolution.

The plots in Figure 3.4 are taken from the initial elevation map and the map after 27 years of evolution. Very little change is evident, which is in keeping with expectations for high initial plant cover. Zooming in around the centroid of the map, given in Figure 3.5, allows us to see the effects of aeolian transport and avalanching in more granular detail. We can also see, around the middle of both figures.

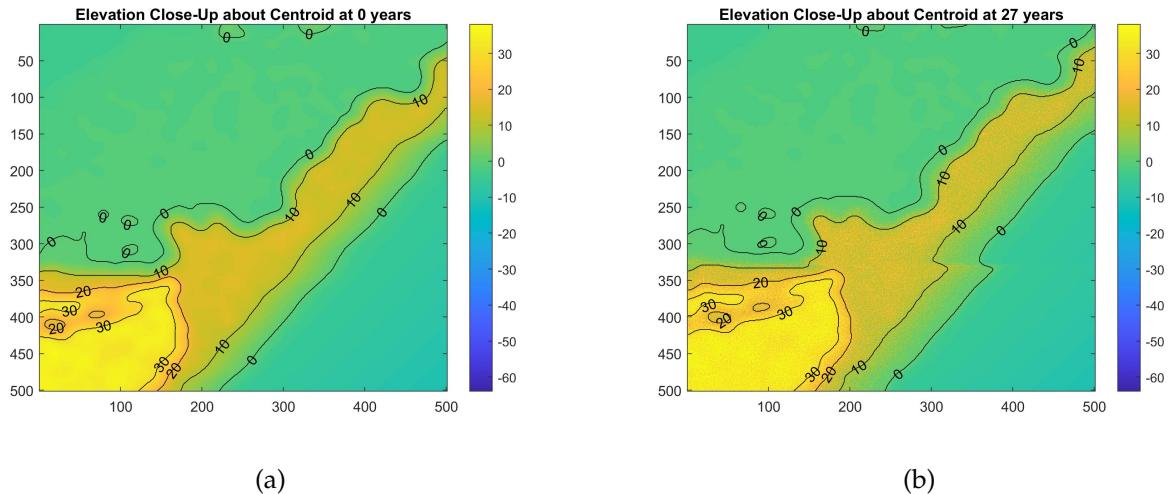


Figure 3.5: Close up of the elevation map with contours for areas around the centroid of Smith island before and after 27 years of evolution.

Plots of the vegetation cover are given in Figure 3.6. We can see in the Figure 3.6a how

the plant populations are initially placed in very distinct locations with clear boundaries where the edges of their viable growth ranges occur. The black areas correspond to negative elevation areas; unviable for all plants except for the marsh Spartina, P_4 in the lower right. The darker shade of grey represents subaerial portions of the island which are outside of the plants elevation range. All varying lighter shades represent some population of the given species present in that cell, with the lighter shades being the highest percent cover possible. Grey areas are often shared by overlapping populations of different species, but the bottom left image shows the clear preference P_3 is given within it's comparatively minimal elevation range.

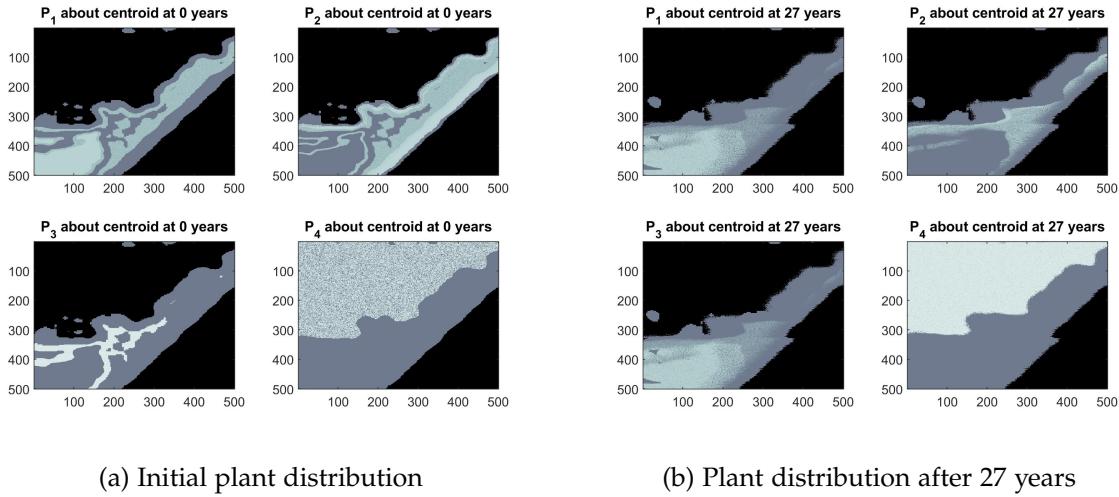


Figure 3.6: Plots of percent plant cover for each P_k at areas focused around the centroid of Smith island before and after 27 years of evolution.

The second Figure 3.6b shows significant spread of all plant species, indicating that the growth range, $\gamma_k \in [g, G]$, has been chosen to allow optimal vegetation growth. Morella has followed a pattern of migrating away from the beach, leaving bands of older populations to die as sediment shifting create conditions outside of the plants viable elevation range. In these areas, Spartina has moved in to take greater portions of the vacated cells. The marsh Spartina population has enjoyed abundant growth in underwater areas where it is uncontested, and also dominates the larger part of the

western shoreline.

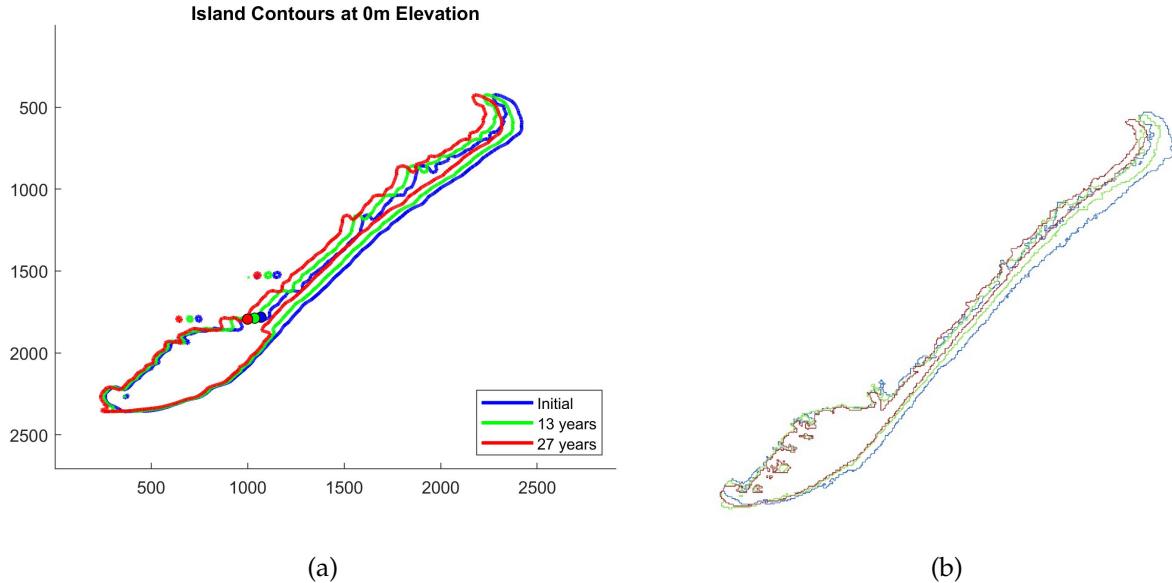


Figure 3.7: A progression of contours plots of elevation map taken at 0, 12, and 27 years compared to similarly timed contours of Smith island. The dots represent the centroid of the island for that year.

Comparison of the contour lines taken at sea level around the shorelines of the island display the migratory trend of the island. The Figure 3.7 demonstrates clear landward progression of the island (the island is oriented such that the mainland is to the west, or left on the image). The centroid, defined as the center of mass for all positive elevation areas of the island, is plotted as a filled dot with color corresponding to the year. This point is a good tool for referring to trends around areas of the island with dense vegetation and multiple plant species. Note that the progression of the centroids taken during the same years as the contours follows a similar trend westward. In comparing our model to the contours taken from the true island, several positive relationships can be established.

The long, thin northern portion of the island is at lower elevations with a greater area of beach. This limits the area in which vegetation can grow. The lower elevations also prevent Morella from maintaining populations, leaving only the dune grasses which are less capable of hindering erosion. Alternatively, the southern area of the island is

much wider and has a greater range of elevation values. This permits the full variety of plant species to occupy a greater area of the island. The impact of this can be seen in the image - the bottom, wider portion of the island migrates significantly less than the northern portions. Most importantly, this trend can be observed in both the model island evolution and the observed island evolution. This indicates that the values selected for migration rate reduction, X_p given in Table 2.3, are appropriately chosen to return optimal results.

To confirm reasonable parameter estimates, we simulated the same sea level rise scenario with identical parameter values over the same time frame on Parramore Islands. This led to the results given in Figure 3.8.

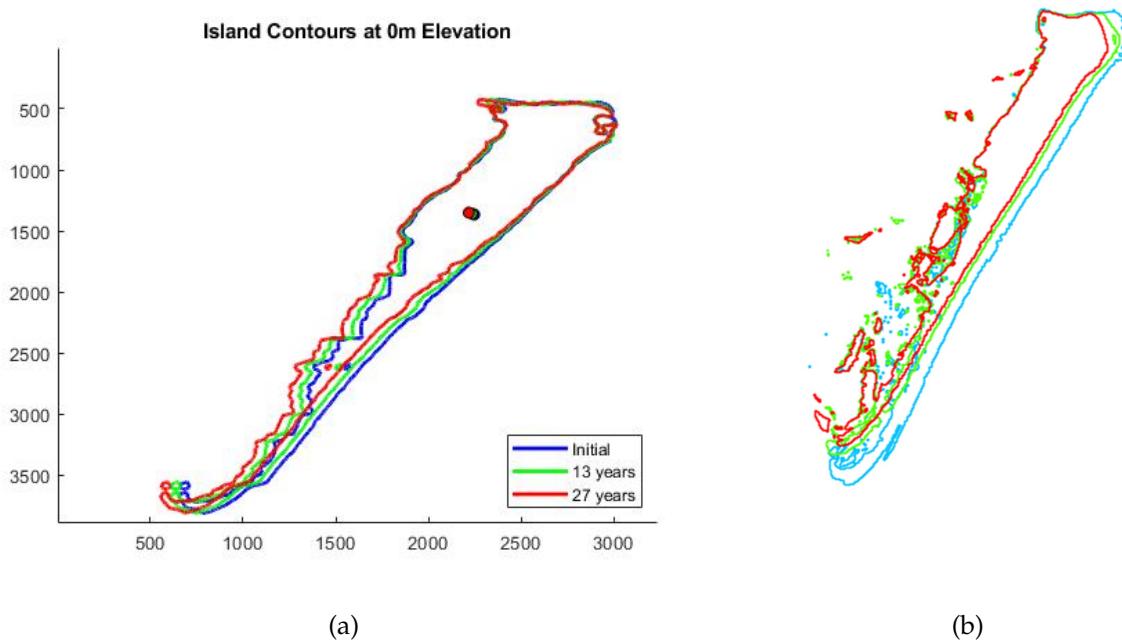


Figure 3.8: A progression of contour plots of elevation map taken at 0, 12, and 27 years compared to similarly timed contours of Parramore island. The dots represent the centroid of the island for that year.

Parramore island has denser land mass to the north, with a long narrow portion in the south. The contours of the island after 27 years of evolution are given in Figure 3.8. The migration in the North has clearly been stifled by the presence of vegetation.

Comparing the model behavior to the observed island contours, we see that the model evolutionary behavior largely follows empirical trends.

We note here that there are a few differences between the model behavior and the observed island behavior that can be pointed out in Figures 3.7 and 3.8. There is some lateral shrinking of the islands and additional regression in the southern part of Parramore Island, for instance. However, the overall drift of each island appears to be reasonably close and at this point in development, it is our goal to capture the migratory behavior of the island and dependence upon living plant populations. Many processes, like high wind events, storms, and overwashing, contribute to the geographical evolution of the island's topography and the shape of the shorelines. We are further restrained by the limits of atmospheric data available of this time frame, and the manner in which it is implemented is similarly restricted as a result. It is our intention to include many more atmospheric processes and improvements in future model development. The results we have shown are highly positive given our limitations.

3.3 Results - Variations on Initial Plant Conditions and Sea Level Rise

We simulate the island under varying conditions of sea level rise and plant percent coverage to demonstrate the dependence of barrier island geomorphology on sea level rise and the presence of vegetation. Sea level rise is taken to be either non existent, constant, or accelerating. Plant percent cover conditions are taken to be either non existent, at 50% of maximum coverage, or at 100% of maximum coverage. The island contours are used to establish key relationships and make observations.

3.3.1 No Sea Level Rise

Island evolution in the absence of sea level rise is achieved by taking $M_a = 0$. It follows that the island migration rate, R , would be reduced to zero by the rate acceleration function given in equation (2.10). The contours are given for Smith island.

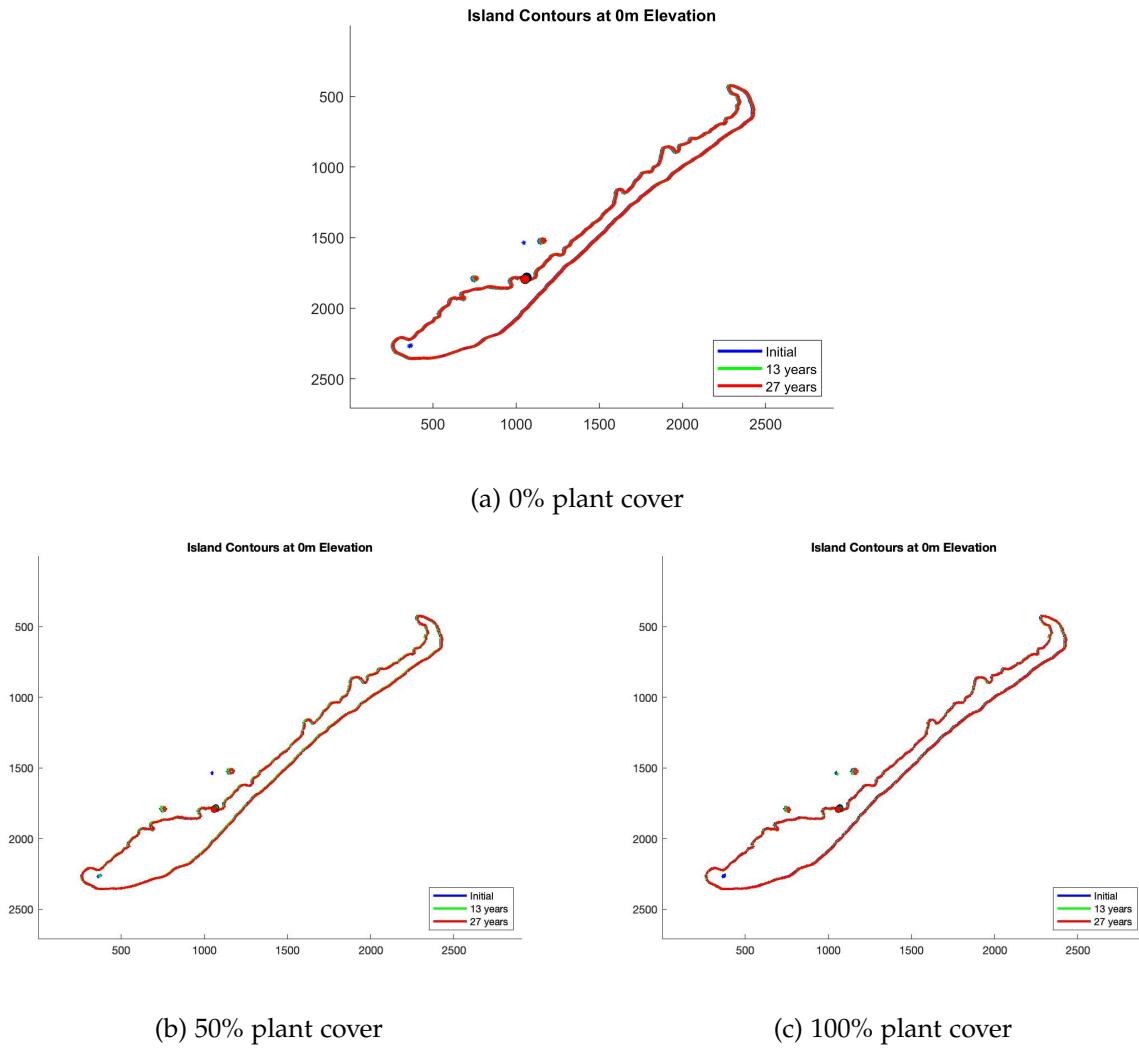


Figure 3.9: Evolution of Smith island in the absence of sea level rise, $M_a = 0$, taken at varying percentages of initial and maximum plant cover.

As expected, there is virtually no movement of the island. Shorelines vary in the slightest degree, which is evidence that the aeolian transport and avalanche processes are still being carried out. The same reasoning explains the slight change in centroid position.

3.3.2 Constant Sea Level Rise

Constant sea level rise is simulated by taking the migration acceleration growth factor to be $M_a = 1$.

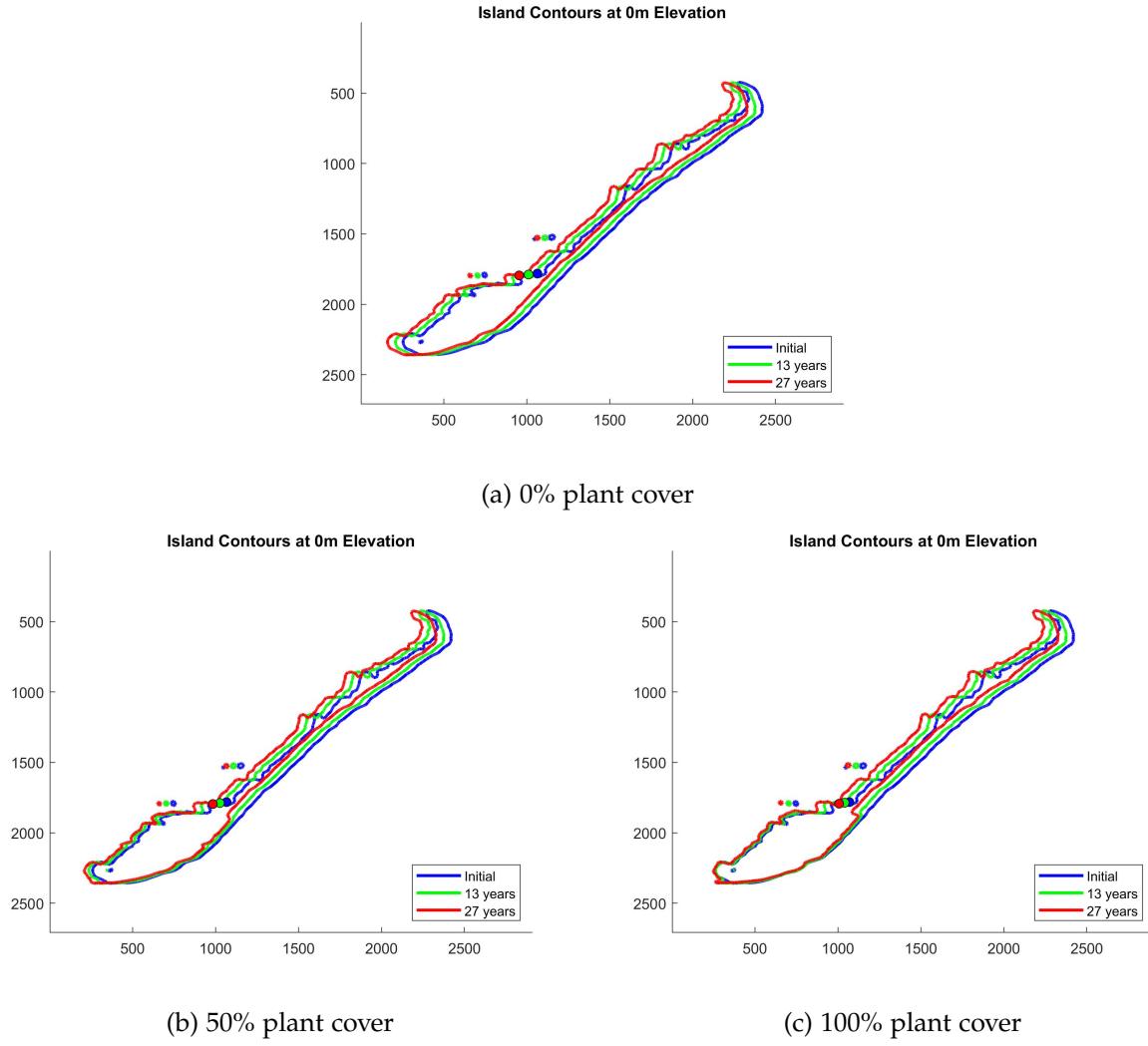


Figure 3.10: Evolution of Smith island with constant sea level rise, $M_a = 1$, taken at varying percentages of initial and maximum plant cover.

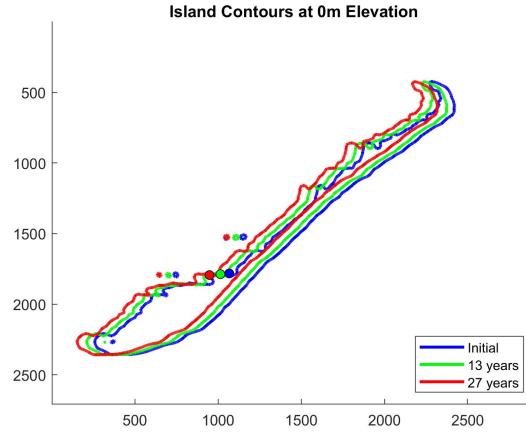
We can see in the Figure 3.10 that there is a notable change in the evolutionary behavior as the initial and maximum percent cover values are increased. The island observed in the absence of all plants, Figure 3.10a, can be seen to migrate uniformly. The curvature of the Eastern coastline remains generally unchanged, with small variations that can be attributed to aeolian transportation and avalanche. In Figure 3.10b we begin to see the

effect of plants diminishing the migration, which particular hinderance occuring at the southern portion of the island where vegetation covers a greater surface area. The final Figure 3.10c displays full coverage bringing the southern area of the island to a near stand still. The centroids are grouped increasingly close together as the plant cover is increased, further illustrating this reduction of migratory behavior.

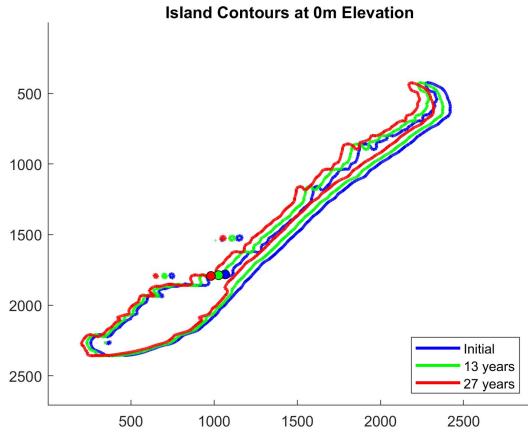
Note also the orientation of the centroids. The line connecting the centroid points becomes gradually more curved as the plant cover increases. We also see a small isthmus forming at the very southern tip of the island. When considered together, these observations demonstrate the island gradually curving, and more years of evolution may result in the pronounced overall bowed shape; a feature common to many barrier islands.

3.3.3 Accelerating Sea Level Rise

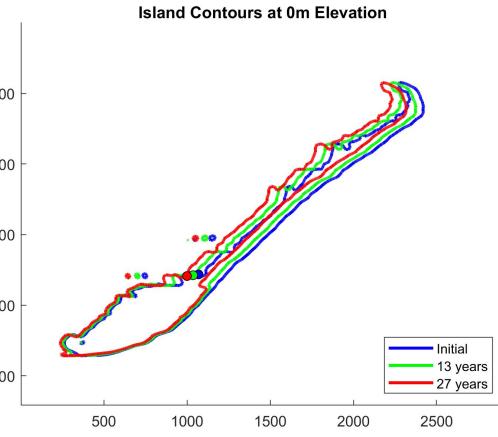
Accelerating sea level rise is achieved using a growth rate of 0.75%, as determined by the parameterization process. This gives us a growth factor $M_a = 1.0075$ which, when applied in equation (2.10), results in a gradual acceleration of landward migration. We would expect to see trends similar but more pronounced than those with constant sea level rise.



(a) 0% plant cover



(b) 50% plant cover



(c) 100% plant cover

Figure 3.11: Evolution of Smith island with accelerating sea level rise, $M_a = 1.0075$, taken at varying percentages of initial and maximum plant cover.

We do indeed see the same trends as with a constant rate of sea level rise. The initial Figure 3.11a shows near uniform migration of both east and west shorelines, indicated that the island has the same migratory trends everywhere. Again we see in Figures 3.11b and 3.11c that the migration is significantly inhibited by increasing the initial and maximum percent cover values.

In comparing the vertical and horizontal location of the centroids we obtain more information. The initial, 13 year, and 27 year centroid coordinates for full plant cover and constant sea level rise given in Figure 3.10c are (1069,1782), (1040,1786), and (1007,1793),

respectively. Considering a unit cell width of L , this means that the centroid of the island migrated by $29 * L$ meters in the first 13 years, and an additional $33L$ meters in the following 14 years, for a total of $62L$ meters over the whole 27 year span. The centroid coordinates in Figure 3.11c are (1069,1782), (1036,1788), and (999.5,1794). The same analysis yields migration values of $33L$ meters in the first 13 years and 36.5 meters in the last 14 years, for a total of $69.5L$ meters in 27 years. The overall migration is then $7.5L$ meters greater when sea level rise is accelerating. Since the centroid is necessarily located in the densest area of the island, this serves as a lower bound on the possible increase in migration for this scenario, and all other areas of the island would certainly experience even greater increases in landward migration.

Chapter 4

Conclusion

A four species of plants are included within the island domain. Plant populations were configured to allow for natural competition, growth, death and propagation in accordance with known species characteristics. Using educated estimates followed by repeated testing, the model was parameterized to approximate historical maps of island evolution. We optimize erosion coefficients which are used to define an effective total percent cover of vegetation for each location on the island. This effective percent cover is used when calculating the probability of sediment shifts by meteorological processes included in the model.

Aeolian transportation captures the effect of wind erosion via saltation and deposition of sediment slabs in response to sufficient wind conditions sampled from real-world meteorological data. Slabs of sediment were permitted to move multiple steps, subject to wind conditions and the restrictions that capture the hindering effect of local vegetation. A probability of sediment transfer is defined by incorporating the effective percent plant cover.

Avalanching captures the effect of natural gravitational collapse. The critical angle of repose defines sufficient conditions for collapse in the absence of plant life. Dependence upon local vegetation defines the probability of collapse which is inversely proportional

to the local effective percent coverage of plant species.

Marine process captures the long-term effect of sea level rise on island migration in accordance with the Bruun rule for shoreline recession. This landward motion is reduced by a scaling factor defined using the effect plant cover and island subaerial surface area. The values of this scaling factor are associated with migration reduction percentages. We employed a moving window to calculate the migration reduction to ensure realistic island movement. Additionally, we define the acceleration of sea level rise based on a growth parameter which was similarly optimized to demonstrate island evolutionary behavior consistent with historical trends.

The barrier island evolution model that we developed combines four processes to demonstrate how the presence of vegetation effects the evolution of the entire barrier island on the decadal time scales. Using two of Virginia's Eastern Shore barrier islands, we simulated 27 years of geographic development for sea level rise scenarios including the absence of sea level rise, constant rates of sea level rise, and accelerating rates of sea level rise. We further demonstrated the model's global dependence on plant populations by varying the maximum percent cover between 0%, 50% and, 100% for all three sea level rise scenarios. We presented and analyzed the evolutionary results using island contours taken at 0, 13, and 27 years.

The model demonstrated a dramatic increase of landward migration as the rate of sea level rise escalated. This rate of landward migration was large in the absence of plant life, and shown to be appropriately hindered when the percent cover of vegetation was increased. Wider, more densely vegetated areas of the island experienced less shoreline migration, while narrower and sparsely populated areas saw significantly more landward movement. Reducing plant cover to zero showed the shorelines moving uniformly. The absence of sea level rise dramatically decreased migration, and demonstrated near uniform movement of the shoreline regardless of plant cover.

Many barrier island models have been developed which include one or more of the

aeolian, avalanche, and marine processes, or a plant population sub-model. Ours is the first to combine all four elements and employ them on a whole island domain which includes ocean, beach, central dune field, backbarrier marsh, and all shorelines from the northern to the southern tip of the island.

There is much promise in the model, and further development will increase model reliability and application beyond the scope we have presented here. Future versions of the model will include more detailed shoreline development, which would require more robust development marine processes to include sediment fluxes in response to tidal activity and evolution of the beach profile. Further research is also needed to incorporate the known currents around barrier islands in order to capture the subtle but significant southern drift of Virginia's barrier islands.

Additional field observation and laboratory testing of plant species, specifically with respect to their erosion inhibiting capabilities, will continue to inform our parameter selection. With more information about how successfully plant species impede sediment collapse, saltation, and transfer on the wind, we can ensure that the model is performing with the greatest accuracy. Similarly, as more data becomes available regarding species responses to salt exposure and burial by sediment, we can ensure that the parameters governing plant growth and death cycles are best selected to reflect the empirical conditions.

Much of a barrier island's migration is attributed to the process of sediment movement from the beach face into the backbarrier region of the island [19]. Wave run-up and water level surges during storms create overwashing flows [18]. Further development of the model will include storm events and subsequent overwashing while accounting for the effect of increased wind speeds. Furthermore, the increase of occurrence and intensity of storms is closely linked to climate change. For this reason, incorporating storm events into our current model is essential to the goal of understanding the impact of climate change on barrier island evolution.

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Appendix A

Notation Index

Notation	Definition	Value
n	number of cell widths in island domain	678, 974 *
m	number of cell lengths in island domain	728, 810 *
δ	height of each slab	0.1 meters
L	width and length of each slab	4 meters
$\lambda_{L,k}$	minimum viable elevation for P_k , $k = 1, 2, 3, 4$	see Table 1
$\lambda_{H,k}$	maximum viable elevation for P_k , $k = 1, 2, 3, 4$	see Table 1
β	death by elevation percentage	30%
γ_k	growth death percentange ($k = 1, 2, 3, 4$, $\gamma_k \in [g, G]$)	-2%-8% yr ⁻¹
g	plant growth minimum	-0.02
G	plant growth maximum	0.08
η_k	plant percent cover maximum for each P_k , $k = 1, 2, 3, 4$	80%, 80%, 60%, 60%
M_∞	global percent cover maximum (for all P_k on a given cell)	80%
ω_L	minimum wind speed required for sediment transport	6 meters/second
ω_H	threshold for storm event	16 meters/second
α_k	erosion coefficient for each P_k , $k = 1, 2, 3, 4$	0.667, 0.333, 1, 1
θ_o	angle of repose for avalanche	$\pi/6$
R_o	initial rate of shoreline retreat	15 m/yr
θ_o	angle of repose for avalanche	$\pi/6$
$2w$	width of transectional window to calculate X_p	10 cells
M_a	migration rate growth factor	0, 1, 1.0075

Table A.1: Model constant and parameter notion and values,

* values are for Smith, Parramore respectively.

Notation	Variable definition
H	array containing island elevation values in number of slabs
P_k	array containing percent cover values for plant populations ($k = 1, 2, 3, 4$)
PC	total percent cover for all P_k weighted by erosion coefficients, α_k
a	percent cover on cell in excess of M_∞
l	number of grass species on cell ($l \in \{1, 2, 3\}$)
θ'	current cell angle of elevation with respect to a neighboring cell
ρ_{av}	probability of avalanching
ρ_{e_d}	probability of aeolian transport at step d
d	aeolian transport distance in cell widths ($d \in \{1, 2, 3\}$)
ω	wind speed
R	rate of shoreline retreat (Bruun Rule)
R'	accumulated shoreline retreat vector
A^*	cross-shore distance to depth of closure (Bruun Rule)
h^*	depth of closure (Bruun Rule)
B	berm height (Bruun Rule)
θ_b	approximate angle of foreshore slope (Bruun Rule)
j_s	horizontal location of the shoreline for row i
X_p	migration rate reduction factor
Ψ	area of subaerial portion of island within transectional window

Table A.2: Model arrays and variables

Appendix B

MATLAB code

B.1 Main code

```
1 %% MainCode092820
2 % MPswitch=1;
3 % ATcntr=0;
4 % SLRswitch=0;
5 % is the updated main code for barrier island evolution.
6 % this version of the code is build upon the original code by Greg Robson
7
8 % off-hand key notes (NOT EVEN REMOTELY COMPREHENSIVE)
9 % **ARRAYS
10 % H - main elevation matrix
11 % (only updated in initialization and at end of the main loop)
12 % Hstar - dummy elevation array for changes in subroutines
13 % *third dimension unused - was for land categorization
14 % P.i - Plant percent coverage matrices,
15 % P3d - tracks dead morella
16 % ^Pi(:,:,1) current cell percent cover
17 % ^Pi(:,:,2) initial elevation of current cell
18 % (currently unused, will be needed to check for burial)
19 % PC - Combine Pi's for a total percent cover array - (no cell >1)
20 % (Pi stores value -999 in cells without that plant - i.e.
21 % water, so PC is the array with only cells greater than 0
22 % Ptot= Sum of all PCi
23 % W - water table data (currently unused)
24 % S - salinity (?) data (currently unused)
25 % **General PARAMETERS
26 % time = number of iterations (two week time steps)
27 % delta - slab height (meters)
28 % L - slab length and width (meters)
29
30 % **Routines and Governing Parameters
31 % Main Code
32 % t - current time step
```

```

33 % (2) AeolianTransport
34 % Pe - prob. of erosion
35 % Pd - prob. deposition
36 % n - number of slabs which can move due to wind
37 % (3) Plant Propogation
38 % currently runs twice per year
39 % first time ignores morella and is meant to simulate springtime
40 % growth for grasses (P1,P2,P4 - allow them more chance to grow)
41 % PiC - Plant initial percent cover for P1,P2,P3,P4
42 % PiErosionCoefficient - factors into AT
43 % P-Burial - number of slabs until death
44
45 % (4) Marine Processes
46 % currently runs once every 3 months
47 %
48 % avalanche:
49 % whole domain (underwater and island) ever 5th year time step
50 % once per year runs THREE times per step over only subaerial (ground)
51 % after SwampProcess, AeolianTransport, and before loop end
52 % otherwise runs once per time step, before loop end
53 %
54 % This version contains NO use of Land Categorization
55 tic
56
57 %%%%%%
58 %% LOAD ELEVATION MATRDX%%
59 %%%%%%
60 %%%%%%
61 % PARRAMORE ISLAND DATA:%
62 %%%%%%
63 % IslandArea=14400000;
64 % 12km x 1200 m = 14400000 - Relative Influence Antecedent... paper, 12.4 m/yr
65 filename='Parramore03312021.mat'
66 IslandArea=19070000; %for parramore
67 data=importdata(filename);
68 H=data; %H will be the main elevation matrix
69 TranChk=1;
70
71
72
73 % filename='EricIsland.txt'
74 % IslandArea=41000;%EricIsland
75
76 %%%%%%
77 % SMITH ISLAND DATA:%
78 %%%%%%
79 % filename='Smith03312021.mat'
80 % IslandArea=9065000; %for Smith
81 % data=importdata(filename);
82 % H=data; %H will be the main elevation matrix
83 % TranChk=2;
84
85 %%%%%%
86
87
88 ScaleFactor=floor(sqrt(IslandArea/(sum(sum(H(:,:)>0))))) ;

```

```

89 % InterpFactor=.75*sqrt(ScaleFactor); %ScaleFactor 2
90 InterpFactor=0.5*sqrt(ScaleFactor); %ScaleFactor 4
91
92 H=interp2(H,InterpFactor);
93 ScaleFactor=floor(sqrt(IslandArea/(sum(sum(H(:,:,1)>0)))); %choose row for transect for parramore
94 if TranChk==1
95 TranRow=floor(.25* size(H,1)); %choose row for transect for smith
96 elseif TranChk==2
97 TranRow=floor(0.75* size(H,1)); %choose row for transect for smith
98 elseif exists(TranChk)==0
99 TranRow=floor(0.5* size(H,1));
100 end
101 %%END - LOAD ELEVATION MATRIX%%
102 %%END - LOAD ELEVATION MATRIX%%
103 %%%
104 %%%
105 %%%
106 %%%
107 %%%
108 %%%
109 %%%
110 fprintf('\n')
111 fprintf('Initializing ...')
112 %cheat sheet:
113 time=702; %2600^100yrs;%1300^50yrs;%780^30yrs;%520^20yrs;260^10yrs;
114 delta=0.1;
115 % L=1;%<-----ScaleFactor
116 L=ScaleFactor;
117 BchMax =1.5; %greatest elevation that the beach spreads inland to
118 CW=0; %switch for overwashing - might use when we get storms incorporated (if windspeed>16m/s CW=1 for on, etc)
119 BchW=10; %unused - maximum beach width
120 MPswitch=1; %changes marine processes: --(0 or any ^=1,2,3) for OFF
121 % --(1) for ON {new version - update using same equil. slope}
122 % --(2)for ON {old version - update equil. slope every 12 wks}
123 % MarineProcesses03312021
124 % OLDMarineProcesses03312021
125 DepositSupply=3; %number of slabs of sediment supplied to beach each time MarinePProcesses is run (3 months
126 SLRswitch=0; %turns sea level rise ON(1)/OFF(0 or any ^=1)
127 SLRyr=[ 8 7 6 5]; %years at which to perform SLR at rate SLR and/or migration...
128 Ma= 1;%1.0075; %shoreline migration growth factor, use 1 for no accel/noSLR
129 MigAccel=0; %will need to track magnitude of migration change
130 MigYr=15; %initial yearly migration of the island in meters/year
131 ScaleFactor=floor(sqrt(IslandArea/(sum(sum(H(:,:,1)>0)))); %choose row for transect for parramore
132 % R=zeros(size(H,1),1);
133 MaxSwampWidth=1000; %how far the swamp should go out into the water - just have to make something up for now
134
135 if WindData==0
136 Windspeed=16;
137 %%%
138 WindDir=1; %wind direction % 1=N 2=NE 3=E 4=SE 5=S 6=SW 7=W 8=NW %
139 %%%

```

```

140 end
141 Windmin=6;
142 StormThreshold=16;
143 ATcntr=0; %testing variable - to count number of times AT is called
144
145 %%%%%% PLANT PARAMETERS %%%%%%
146 %Plant initial conditions:
147 PlantRangeArray=[1 5;0.75 3;1.5 2.5;-0.5 0]; %all of the elevation ranges for p1-p4
148 P1IC=1.0;
149 P2IC=1.0;
150 P3IC=1.0;
151 P4IC=1.0;
152 P1PctMax=.6; %largest percentage we will allow any plant population on a given cell to attain
153 P2PctMax=.6;
154 P3PctMax=.8;
155 P4PctMax=.8;
156 PctMax=[P1PctMax P2PctMax P3PctMax P4PctMax];
157 MasterMax=1.0;% The most any cell can permit - 80% plant coverage
158 KillSwitch=0; %this will kill plants on the bottom half of the island if set to 1, set to 0 (or anything else) to turn off
159 alpha=.01; %propagation rate for each populated cell
160 DBE=.3; %death by elevation rate for each populated cell outside of plant's elevation range
161 gdrange1=[-.02:.01:.08]; %range of percent values for growth/death for plant populations at (0, 50)% cover
162 gdrange2=[-.02:.01:.08];%[-.04:.01:.04]; %range of percent values for growth/death for plant pops greater than 50% cover
163
164 %Elevation Matrix dependent parameters:
165 ROW=size(H,1);
166 COLUMN=size(H,2);
167 H(:,:,2)=zeros(ROW,COLUMN); %Creating extra dimension for H
168 Hstar=H; %initializing dummy matrix
169 MigCnt=zeros(ROW,1); %used to store how many meters the shoreline should have receded by, shoreline moves when MigCnt>
    ScalingFactor
170 M=max(max(H(:,:,1)));
171 m=min(min(H(:,:,1)));
172 W=zeros(ROW,COLUMN); %do not comment out - needed as input
173 S=zeros(ROW,COLUMN); %do not comment out - needed as input
174
175 %parameters unused so far (check with Greg)
176 % numslabg=0;
177 % q=0;
178 % Salt=1;
179 % ps=0.6;
180 AV_ARRAY=zeros(time,1000,3); %tracks cell movement in AV. routine
181 %%
182 %%%%%% Imaging Options %%%%%%
183
184
185 % ***note that we do not currently have a running land categorization
186 % subroutine, so leave those options commented or at 0 - I think this
187 % will eventually come back into use so I am leaving the lines there ***
188
189 DurImFreq=78; %how often to output "during" elevation images (26^yearly, 130^every 5 years)
190 MElevCont=0;
191 SElevCont=0;
192 PlantDurImFreq=234; %same, just for plant images
193 DurCUImFreq=78;
194

```

```

195 ElevImCU_during=1;
196 Contour27=1; %contours at 0, 13, and 27 years
197 DurContour=0; %images of the island outline
198
199 TransectIm=1; %images of 2D island transect
200 TranImFreq=234; %every 9 years
201 if TransectIm==1 && exist('TranRow') == 0
202 TranRow=floor(.5*size(H,1)); %choose row for transect
203 end
204
205 MnPlantCvrIm=1; %mean percent cover for each plant, displayed at end of routine 1 to turn on, any other number to turn off
206 ElevIm_before=1; ElevIm_during=1; ElevIm_after=0;
207 LandCatIm_before=0; LandCatIm_during=0; LandCatIm_after=0; %leave these at 0 until we have a working
208 LandCategorization routine
209 PlantPCIm_before=0; PlantPCIm_during=0; PlantPCIm_after=0;
210 SingleStepICIm=0; %plots from initialization process :
211 %includes elevation and Plant initial conditions for
212 %one pass through Swamp, PlantPropagation and
213 %AeolianTransport
214 climsH=[min(min(H(:,:,1))) max(max(H(:,:,1)))] ;
215 climsP=[-1 1];
216 %% %%%%Initializing Plant Arrays%/%%
217 %% %%%%
218 %GRASS #1 (Ammophila)(burial resistant)
219 P1=zeros(ROW,COLUMN,2);
220 P1Burial=2; %meters of burial until death
221 P1ErosionCoefficient=(2/3); %used in formula d=c1P1+c2P2+c3P3+c4P4
222
223 %GRASS #2 (Spartina)
224 P2=zeros(ROW,COLUMN,2);
225 P2Burial=0.5; %meters of burial until death
226 P2ErosionCoefficient=(1/3);
227
228 %SHRUB #1 (Morella)(bird-dispersed seeds)
229 P3=zeros(ROW,COLUMN,2);
230 P3Burial=1.5; %meters of burial until death
231 P3ErosionCoefficient=1;
232
233 %dead morella will track when morella reaches death and store dead
234 %debris data in P3d(:,:,1) for some number of years which will be counted in
235 %P3d(:,:,2) - this is only updated inside of PlantProp
236 P3d=zeros(ROW,COLUMN,2);
237 P3dErosionCoefficient=1;
238
239 %SECOND TYPE OF SPARTINA!!!
240 P4=zeros(ROW,COLUMN,2);
241 P4Burial=0.5;
242 P4ErosionCoefficient=(1/3);
243
244 %% % % INITIAL PLANT CONDITIONS %
245 %% % Each plant species has a preferred "altitude" that it grows best in
246 %% % (min and max among all species is 0.75m and 5m, respectively).
247 %% % We set each cell of "appropriate" elevation to be covered by some% of the

```

```

250 % % % respective plant species. For cells which are submerged under water, we
251 % % % set the proportion of plant coverage to -1.
252 % %
253 % % % We have deleted the initialization of plant population since we are using
254 % % % real data.
255 % % % It is still important to ensure that the 2nd layer of each
256 % % % plant matrix is initiated.
257 fprintf('\n')
258 fprintf('Seeding the island... ')
259 PC1=zeros(size(H,1),size(H,2));
260 PC2=zeros(size(H,1),size(H,2));
261 PC3=zeros(size(H,1),size(H,2));
262 PC4=zeros(size(H,1),size(H,2));
263 [Hstar,MeanBeachWidth,ESL,WSL,MESL,MWSL,OL]=Shoreline03312021(Hstar,delta,L,BchMax);%function to return shoreline(s)
264 for i=1:size(H,1)
265     for j=1:size(H,2)
266         if (delta*H(i,j,1))>=1 && (delta*H(i,j,1))<=5
267             P1(i,j,1)=P1IC;
268             P1(i,j,2)=H(i,j,1);
269         elseif (H(i,j,1)-W(i,j))<0
270             P1(i,j,1)=-999;
271             P1(i,j,2)=0;
272         end
273         PC1(i,j)=P1(i,j,1)*(P1(i,j,1)>0);
274         if (delta*H(i,j,1))>=0.25 && (delta*H(i,j,1))<=3
275             P2(i,j,1)=P2IC;
276             P2(i,j,2)=H(i,j,1);
277         elseif (H(i,j,1)-W(i,j))<0
278             P2(i,j,1)=-999;
279             P2(i,j,2)=0;%  

280         end
281         PC2(i,j)=P2(i,j,1)*(P2(i,j,1)>0);
282         if (delta*H(i,j,1))>=1.5 && (delta*H(i,j,1))<=2.5
283             P3(i,j,1)=P3IC;
284             P3(i,j,2)=H(i,j,1);
285         elseif (H(i,j,1)-W(i,j))<0
286             P3(i,j,1)=-999;
287             P3(i,j,2)=0;
288         end
289         PC3(i,j)=P3(i,j,1)*(P3(i,j,1)>0);
290         if (delta*H(i,j,1))>=-0.5 && (delta*H(i,j,1))<=1
291             if ESL(i)==0
292                 if MWSL(i)<j && MESL(i)>=j
293                     if rand<0.5
294                         P4(i,j,1)=P4IC;
295                         P4(i,j,2)=H(i,j,1);
296                     end
297                 else
298                     P4(i,j,1)=0;
299                     P4(i,j,2)=0;
300                 end
301             end
302 %             WesternCells=zeros(1,MaxSwampWidth);
303 %             EasternCells=zeros(1,MaxSwampWidth);
304 %             for nm=1:min(j-1,size(WesternCells,2))
305 %                 WesternCells(nm)=delta*H(i,j-nm,1);

```

```

306 %
307 % for mm=1:min(size(EasternCells,2),size(H,2)-j)
308 % EasternCells(mm)=delta*H(i,j+mm,1);
309 %
310 % CheckWesternCells=WesternCells<=-.5;%must be within MaxSwampWidth cells to the west of a cell which is outside of
marsh range
311 %
312 % CheckEasternCells=EasternCells>0;
313 % if sum(CheckWesternCells)==0 || sum(CheckEasternCells)==0
314 % P4(i,j,1)=-999;
315 % P4(i,j,2)=0;
316 % end%
317 % if sum(CheckWesternCells)>=0 &&.5<rand
318 % P4(i,j,1)=P4IC;
319 % P4(i,j,2)=H(i,j,1);%
320 end
321 elseif (delta*H(i,j,1)-W(i,j))<-0.5 || (delta*H(i,j,1)-W(i,j))>1
322 if (delta*H(i,j,1)<PlantRangeArray(4,1)) %if less than min height (-0.5)
323 P4(i,j,1)=-999;
324 P4(i,j,2)=0;
325 elseif (delta*H(i,j,1)>PlantRangeArray(4,2)) %elseif greater than max height, make 0 (no death by elev.
just kill)
326 P4(i,j,1)=0;
327 P4(i,j,2)=0;
328 end
329 PC4(i,j)=P4(i,j,1)*(P4(i,j,1)>0);
330 end
331 end
332 t=NaN;
333 [P1,P2,P3,P4,P3d]=PlantPropagation03312021(Hstar,t,P1,P2,P3,P4,W,S,delta,P3d,MaxSwampWidth,PlantRangeArray,alpha,DBE,gdrange1,
gdrange2,PctMax,MasterMax,MWSL,MESL,ESL);
334 for i=1:size(H,1)
335 for j=1:size(H,2)
336 PC1(i,j)=P1(i,j,1)*(P1(i,j,1)>0);
337 PC2(i,j)=P2(i,j,1)*(P2(i,j,1)>0);
338 PC3(i,j)=P3(i,j,1)*(P3(i,j,1)>0);
339 PC4(i,j)=P4(i,j,1)*(P4(i,j,1)>0);
340 end
341 end
342 PC=(P1ErosionCoefficient.*PC1(:, :))+(P2ErosionCoefficient.*PC2(:, :))+(P3ErosionCoefficient.*PC3(:, :))+(P4ErosionCoefficient.*PC4
(:, :))+(P3dErosionCoefficient.*P3d(:, :, 1));
343 Ptot=P1(:, :, 1)+P2(:, :, 1)+P3(:, :, 1)+P4(:, :, 1)+P3d(:, :, 1);
344 %%%%%%%%%%%%%%
345 %%%END - INITIALIZING PLANT ARRAYS%%%%%
346 %%%%%%%%%%%%%%
347
348 %%%%%%%%%%%%%%
349 %%%%killing plants on half of island test%%%%%
350 %%%%%%%%%%%%%%
351 if KillSwitch==1;
352 for i=floor(0.5*(size(H,1))):size(H,1) %killing bottom half plants
353 for j=1:size(H,2)
354 if P1(i,j,1)>0
355 P1(i,j,1)=0;
356 PC1(i,j)=0;
357 end

```

```

358     if P2(i,j,1)>0
359         P2(i,j,1)=0;
360         PC2(i,j)=0;
361     end
362     if P3(i,j,1)>0
363         P3(i,j,1)=0;
364         PC3(i,j)=0;
365     end
366     if P4(i,j,1)>0
367         P4(i,j,1)=0;
368         PC4(i,j)=0;
369     end
370 end
371 end
372 PC=(P1ErosionCoefficient.*PC1(:,:,1)+(P2ErosionCoefficient.*PC2(:,:,1)+(P3ErosionCoefficient.*PC3(:,:,1)+(P4ErosionCoefficient.*PC4(:,:,1)+(P3dErosionCoefficient.*P3d(:,:,1));
373 end
374 %%END of half island plant test conditions%%
375 %%END of half island plant test conditions%%
376 %%%
377 %%
378 %% BEFORE IMAGES%%
379 %%%
380
381 if ElevIm.before==1
382     Hfilt=round(imgaussfilt(H(:,:,1),2),0);
383 %%Elevation%%
384 figure %
385 colormap(jet()) %
386 imagesc(H(:,:,1),climsH) %
387 hold on
388 if MElevCont==1
389     contour(H(:,:,1),[-5 -5], 'color','m', 'linewidth',1.1)
390 end
391 if SElevCont==1
392     contour(Hfilt(:,:,1),[-0 -0], 'color','k', 'linewidth',1.1)
393 end
394 if MElevCont==1 && SElevCont==1
395     lgnd=legend('\color{white} marsh contour (-0.5m)', '\color{white} sea level contour (0m)');
396     set(lgnd,'color','none','location','southeast');
397 elseif MElevCont==1 && SElevCont==0
398     lgnd=legend('\color{white} marsh contour (-0.5m)');
399     set(lgnd,'color','none','location','southeast');
400 elseif SElevCont==1 && MElevCont==0
401     lgnd=legend('\color{white} sea level contour (0m)');
402     set(lgnd,'color','none','location','southeast');
403 end
404 colorbar %
405 title('Before Image'); %
406 %%
407 end
408
409 if PlantPCIm.before==1
410 %%PLANTS%%
411 %% AMMOPHILA
412 figure

```

```

413 colormap gray
414 imagesc(P1(:,:,1),climsP)
415 colorbar
416 title('P1 - Ammophila IC')
417 %% SPARTINA
418 figure
419 colormap gray
420 imagesc(P2(:,:,1),climsP)
421 colorbar
422 title('P2 - Spartina patens IC')
423 %% MORELLA
424 figure
425 colormap gray
426 imagesc(P3(:,:,1),climsP)
427 colorbar
428 title('P3 - Morella IC')
429 %% SPARTINA (marsh)
430 figure
431 colormap gray
432 imagesc(P4(:,:,1),climsP)
433 colorbar
434 title('P4 - Spartina alterniflora IC')
435 end
436 %%%%%%
437 %%%%%%Single Step Subroutine Images%%%%%
438 %%%%%%
439 fprintf('\n')
440 fprintf('Running startup sequences:')
441 fprintf('\n')
442 fprintf('Running Swamp Processes ... ')
443 %Initial = Run Swamp
444 [Hstar,ColumnArraySwamp1,ColumnArraySwamp2,AdjascentLengthSwamp,OppositeLocationSwamp,flag,INum]=SwampProcesses03312021(Hstar,
   delta,L,flag,PC);
445 fprintf('done')
446 fprintf('\n')
447 fprintf('Running Avalanche... ')
448 % (1.5) post swamp avalanche
449 PassCount=1;
450 CellsMoved=zeros(1,1000);
451 [Hstar,flag,CellCt]=AVALANCHE03312021(Hstar,delta,L,flag,PC);
452 CellsMoved(PassCount)=CellCt;
453 while flag==1
454   PassCount=PassCount+1;
455   [Hstar,flag,CellCt]=AVALANCHE03312021(Hstar,delta,L,flag,PC);
456   CellsMoved(PassCount)=CellCt;% 
457 end
458 CellsMoved=CellsMoved(1,1:PassCount);
459 SwampAvArray=[NaN PassCount CellsMoved]; %tracking number of passes and number of cells moved per pass
460 AvIC_Array1=SwampAvArray; %AvIC_Array1 tracks avalanche data for initialization routines
461 H=Hstar; %update H
462 fprintf('done')
463
464
465 %***** NOT USING LAND CATEGORIZATION - BUT MAY AGAIN LATER - DO NOT DELETE!!
466 for i=1:size(Hstar,1)
467   for Icount=1:INum

```

```

468     if ColumnArraySwamp2(i,Icount) ~=0
469     %         for j=ColumnArraySwamp1(i,Icount):ColumnArraySwamp2(i,Icount)
470     %             Hstar(i,j,2)=2;
471     %         end
472     end
473 end
474
475 %***** NOT USING LAND CATEGORIZATION - BUT MAY AGAIN LATER - DO NOT DELETE!!
476
477 %post swamp processes/avalanche1 images
478 if SingleStepICIm==1
479     figure('NumberTitle','off','Name','After Swamp');
480     colormap(jet()) %
481     %    clims=[min(min(Hstar(:,:,1))) max(max(Hstar(:,:,1)))]%
482     imagesc(Hstar(:,:,1),climsH)%%
483     title('ICs After Swamp')
484     colorbar
485 end
486 fprintf('\n')
487 fprintf('Running Marine Processes ... ')
488 %Initial - Marine Processes
489 MeanBeachWidthVec=zeros(1,time+2); %for tracking beach width evolution
490 if MPswitch==1
491     % need version of PC with erosion coefficients AND with negative values (zeros only where plants COULD grow) to calculate
492     % migration
493     PCmp=-999*ones(ROW,COLUMN);
494     for i=1:ROW
495         for j=1:COLUMN
496             if P1(i,j,1)>=0 || P2(i,j,1)>=0 || P3(i,j,1)>=0 || P4(i,j,1)>=0
497                 PCmp(i,j)=(P1ErosionCoefficient*P1(i,j,1)*(P1(i,j,1)>0)+(P2ErosionCoefficient*P2(i,j,1)*(P2(i,j,1)>0))+
498                 P3ErosionCoefficient*P3(i,j,1)*(P3(i,j,1)>0));%+(P4ErosionCoefficient*P4(i,j,1)*(P4(i,j,1)>0));
499             end
500         end
501     end
502 %     Pt1=max(P1(:,:,1),0);
503 %     Pt2=max(P2(:,:,1),0);
504 %     Pt3=max(P3(:,:,1),0);
505 %     Pt4=max(P4(:,:,1),0);
506 %     PCmp=(P1ErosionCoefficient.*Pt1)+(P2ErosionCoefficient.*Pt2)+(P3ErosionCoefficient.*Pt3)+(P4ErosionCoefficient.*Pt4);
507 [Hstar,P3,MeanBeachWidth,ESL,WSL,MESL,MWSL,OppositeLocation,SLRyrs,MigCnt,MigAccel]=MarineProcesses03312021(Hstar,delta,L,P1,
508 P2,P3,P4,BchMax,OW,t,SLRyrs,PCmp,Island Area ,MigCnt,ScaleFactor ,MigYr, Ma, MigAccel ,MasterMax);
509 MeanBeachWidthVec(1)=MeanBeachWidth;
510 H=Hstar;
511 elseif MPswitch==2
512     [Hstar,PlantColumnArray ,PlantColumnArray2,P3,flag ,MeanBeachWidth]=OLDMarineProcesses03312021(Hstar,delta,L,flag ,PC,P3,BchMax,
513 BchW);
514     MeanBeachWidthVec(1)=MeanBeachWidth;
515     H=Hstar;
516 end
517 fprintf('done')
518
519 if SingleStepICIm==1
520     figure('NumberTitle','off','Name','After Marine Processes');
521     colormap(jet()) %
522     imagesc(Hstar(:,:,1),climsH)%
523     title('ICs after Swamp, Marine Processes')

```

```

520     colorbar
521 end
522
523 %Redeclare PC since P3 has been updated
524 %PC=(P1ErosionCoefficient.*P1(:,:,1))+(P2ErosionCoefficient.*P2(:,:,1))+(P3ErosionCoefficient.*P3(:,:,1))+(P4ErosionCoefficient.*P4(:,:,1));
525 for i=1:size(H,1)
526     for j=1:size(H,2)
527         PC1(i,j)=P1(i,j,1)*(P1(i,j,1)>0);
528         PC2(i,j)=P2(i,j,1)*(P2(i,j,1)>0);%
529         PC3(i,j)=P3(i,j,1)*(P3(i,j,1)>0);
530         PC4(i,j)=P4(i,j,1)*(P4(i,j,1)>0);
531     end
532 end
533 PC=(P1ErosionCoefficient.*PC1(:,:,1))+(P2ErosionCoefficient.*PC2(:,:,1))+(P3ErosionCoefficient.*PC3(:,:,1))+(P4ErosionCoefficient.*PC4(:,:,1))+(P3dErosionCoefficient.*P3d(:,:,1));
534
535 %post marine processes avalanche
536 PassCount=1;
537 CellsMoved=zeros(1,1000);
538 [Hstar,flag,CellCt]=AVALANCHE03312021(Hstar,delta,L,flag,PC);
539 CellsMoved(PassCount)=CellCt;
540 while flag==1
541     PassCount=PassCount+1;
542     [Hstar,flag,CellCt]=AVALANCHE03312021(Hstar,delta,L,flag,PC);
543     CellsMoved(PassCount)=CellCt;%
544 end
545 CellsMoved=CellsMoved(1:1:PassCount);
546 AvIC_Array2=[NaN PassCount CellsMoved];
547 H=Hstar;
548
549 %***** NOT USING LAND CATEGORIZATION - BUT MAY AGAIN LATER - DO NOT DELETE!!
550 %    %Initial Declare all categories in H
551 PlantColumnArray=zeros([size(H,1) 1]); %P3 isn't allowed to grow on the beach - this is to check for that
552 PlantColumnArray2=zeros([size(H,1) 1]);
553 [Hstar,P1,P2,P3,P4]=LandCategorizationUNUSED03312021(Hstar,P1,P2,P3,P4,PlantColumnArray,PlantColumnArray2,ColumnArraySwamp1,
      ColumnArraySwamp2,INum);
554 %***** NOT USING LAND CATEGORIZATION - BUT MAY AGAIN LATER - DO NOT DELETE!!
555
556 if SingleStepICIm==1
557     figure
558     colormap(jet())
559     imagedesc(Hstar(:,:,2),climsH)
560     colorbar
561     ('ICs_LandCats - After Swamp, Marine Processes and Avalanche');
562 end
563 fprintf('\n')
564 fprintf('Initialization complete')
565
566 %%%
567 %%%END INITIAL PARAMETERIZATION%%
568 %%%
569 %%%
570 tic
571 T=zeros(time,1);
572 #####%

```

```

573 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
574 %%!@#$%
575 %%MAIN LOOP%%%
576 %#####
577 tStart=cputime;
578 for t=0:time
579     TimeStep=t
580     Ptot=P1(:,:,1)+P2(:,:,1)+P3(:,:,1)+P4(:,:,1)+P3d(:,:,1);
581     if 0==mod(t,26)
582         if t==0
583             fprintf('\n')
584             fprintf('Here we go... ')
585         elseif t==26
586             fprintf('\n')
587             fprintf("%d year has passed",t/26)
588         else
589             fprintf('\n')
590             fprintf("%d years have passed",t/26)
591         end
592     end
593     % TimeStep=t
594     %% PC=(P1ErosionCoefficient.*P1(:,:,1))+(P2ErosionCoefficient.*P2(:,:,1))+(P3ErosionCoefficient.*P3(:,:,1))+(P4ErosionCoefficient.*P4(:,:,1));
595     %need to work this into the inside of PlantProcesses
596     for i=1:size(H,1)
597         for j=1:size(H,2)
598             PC1(i,j)=P1(i,j,1)*(P1(i,j,1)>0);
599             PC2(i,j)=P2(i,j,1)*(P2(i,j,1)>0);
600             PC3(i,j)=P3(i,j,1)*(P3(i,j,1)>0);
601             PC4(i,j)=P4(i,j,1)*(P4(i,j,1)>0);
602         end
603     end
604     PC=(P1ErosionCoefficient.*PC1(:,:,1))+(P2ErosionCoefficient.*PC2(:,:,1))+(P3ErosionCoefficient.*PC3(:,:,1))+(P4ErosionCoefficient.*PC4(:,:,1))+ (P3dErosionCoefficient.*P3d(:,:,1));
605
606     %% %(1) Run Swamp
607
608
609 [ Hstar ,ColumnArraySwamp1,ColumnArraySwamp2,AdjascentLengthSwamp ,OppositeLocationSwamp ,flag ,lNum]=SwampProcesses03312021(Hstar ,
610 delta ,L,flag ,PC );
611
612 %% %%(1.AV) THIS AVALANCHE RUNS ONCE PER YEAR (every 26 time steps) AND IS THE FIRST AVALANCHE
613 % if (0==mod(t,26)) && t~=0
614 PassCount=1;
615 CellsMoved=zeros(1,1000);
616 [ Hstar ,flag ,CellCt]=AVALANCHEtime03312021(Hstar ,delta ,L,flag ,PC,t );
617 CellsMoved(PassCount)=CellCt;
618 while flag==1
619     PassCount=PassCount+1;
620     [ Hstar ,flag ,CellCt]=AVALANCHEtime03312021(Hstar ,delta ,L,flag ,PC,t );
621     CellsMoved(PassCount)=CellCt;%#
622     if CellCt<=5
623         flag=0;
624     end
625 end
626 CellsMoved=CellsMoved(1 ,1:PassCount );

```

```

626 SwampAvArray=[NaN PassCount CellsMoved];
627 AvIC_Array1=SwampAvArray;
628 AV.ARRAY(TimeStep+1,1:PassCount+2,1)=SwampAvArray;
629
630
631 %***** NOT USING LAND CATEGORIZATION - BUT MAY AGAIN LATER - DO NOT DELETE!!
632 for i=1:size(Hstar,1)
633     for Icount=1:INum
634         if ColumnArraySwamp2(i,Icount) ~=0
635             for j=ColumnArraySwamp1(i,Icount):ColumnArraySwamp2(i,Icount)
636                 Hstar(i,j,2)=2;
637             end
638         end
639     end
640 end
641 %***** NOT USING LAND CATEGORIZATION - BUT MAY AGAIN LATER - DO NOT DELETE!!
642
643
644 %%    %(2) Aeolian Transport
645
646 if WindData==0
647     if Windspeed>=6
648         WindCnt=floor(((max(Windspeed-Windmin,0))/(StormThreshold-Windmin))*24);
649         for day=1:14
650             %           for hour =1:WindCnt
651                 [Hstar]=AeolianTransport03212021(Hstar,delta,L,W,Windspeed,Windmin,StormThreshold,WindDir,PC);
652             %           end
653         end%
654     end
655 end
656
657 if WindData==1 && t>0
658     %WindDir=randi([1,8]); can randomize wind or use data-weighted wind directions outlined below. (comment this if you
659     %randomize)
660     for day=1:14
661         WindSpeedParam=randi(2183);
662         if WindSpeedParam>=1 && WindSpeedParam<=2116
663             Windspeed=randi([0,5]);
664         elseif WindSpeedParam>2116 && WindSpeedParam<=2183
665             ATcntr=ATcntr+1;
666             Windspeed=randi([6,15]);
667         elseif WindSpeedParam>2183
668             Windspeed=16;
669         end
670         WindParam=randi(2107);
671         if WindParam>=1 && WindParam<=250
672             WindDir=1;
673         elseif WindParam>=251 && WindParam<=655
674             WindDir=2;
675         elseif WindParam>=656 && WindParam<=835
676             WindDir=3;
677         elseif WindParam>=836 && WindParam<=1091
678             WindDir=4;
679         elseif WindParam>=1092 && WindParam<=1464
680             WindDir=5;
681         elseif WindParam>=1465 && WindParam<=1717

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```

681         WindDir=6;
682     elseif WindParam>=1718 && WindParam<=1865
683         WindDir=7;
684     elseif WindParam>=1866 && WindParam<=2107
685         WindDir=8;
686     end
687
688     if Windspeed>=6
689 %         WindCnt=floor (((max(Windspeed-Windmin,0) /(StormThreshold-Windmin) ) *24) ;
690 %         for hour=1:WindCnt
691 %             [Hstar]=AeolianTransport03312021(Hstar,delta,L,W,Windspeed,Windmin,StormThreshold,WindDir,PC);
692 %         end
693 %     end
694 end
695 end
696
697 %%    %(2.AV)                                THIS AVALANCHE RUNS ONCE PER YEAR (every 26 time steps) AND IS THE SECOND AVALANCHE
698 % if (0==mod(t,26)) && t~=0
699 PassCount=1;
700 CellsMoved=zeros(1,1000);
701 [Hstar,flag,CellCt]=AVALANCHEtime03312021(Hstar,delta,L,flag,PC,t);
702 CellsMoved(PassCount)=CellCt;
703 while flag==1
704     PassCount=PassCount+1;
705     [Hstar,flag,CellCt]=AVALANCHEtime03312021(Hstar,delta,L,flag,PC,t);
706     CellsMoved(PassCount)=CellCt;%
707     %        if CellCt<=5
708     %            flag=0;
709     %        end
710 end
711 CellsMoved=CellsMoved(1,1:PassCount);
712 Av2.Array=[TimeStep PassCount CellsMoved];
713 AV.ARRAY(TimeStep+1,1:PassCount+2,2)=Av2.Array;
714 % end
715
716 %%    %(3) Plant Propogation
717
718 %land categorization used to be required for plant processes - this might be removeable
719 %***** NOT USING LAND CATEGORIZATION - BUT MAY AGAIN LATER - DO NOT DELETE!!
720 [Hstar,P1,P2,P3,P4]=LandCategorizationUNUSED03312021(Hstar,P1,P2,P3,P4,PlantColumnArray,PlantColumnArray2,ColumnArraySwamp1,
721 ColumnArraySwamp2,INum);
722 %***** NOT USING LAND CATEGORIZATION - BUT MAY AGAIN LATER - DO NOT DELETE!!
723
724 if (0==mod(t,13)) % choose 26 for 2-week timesteps; 52 for 1-week timesteps
725     [Hstar,MeanBeachWidth,ESL,WSL,MESL,MWSL,OL]=Shoreline03312021(Hstar,delta,L,BchMax);%get shoreline to use in
726     PlantPropagation
727     [P1,P2,P3,P4,P3d]=PlantPropagation03312021(Hstar,t,P1,P2,P3,P4,W,S,delta,P3d,MaxSwampWidth,PlantRangeArray,alpha,DBE,
728     gdrange1,gdrange2,PctMax,MasterMax,MWSL,MESL,ESL);
729     if P3IC==0 %killing off any morella that was established due to bird activity
730         P3(:,:,1)=min(P3(:,:,1),0);
731     end
732 end
733
734 for i=1:size(H,1)
735     for j=1:size(H,2)
736         PC1(i,j)=P1(i,j)*(P1(i,j),1)>0;

```

```

734     PC2(i,j)=P2(i,j,1)*(P2(i,j,1)>0);
735     PC3(i,j)=P3(i,j,1)*(P3(i,j,1)>0);
736     PC4(i,j)=P4(i,j,1)*(P4(i,j,1)>0);
737   end
738 end
739 PC=(P1ErosionCoefficient.*PC1(:,:,1)+(P2ErosionCoefficient.*PC2(:,:,1)+(P3ErosionCoefficient.*PC3(:,:,1)+(P4ErosionCoefficient.*PC4(:,:,1)+(P3dErosionCoefficient.*P3d(:,:,1));
740 Ptot=PC1(:,:,1)+PC2(:,:,1)+PC3(:,:,1)+PC4(:,:,1)+P3d(:,:,1);
741
742 %%  %(4) Marine Processes - edits
743 %currently every 12 months, moves 2 slabs into ocean
744 if (0==mod(t,26))
745   if MPswitch==1
746     PCmp=-999*ones(ROW,COLUMN);
747     for i=1:ROW
748       for j=1:COLUMN
749         if P1(i,j,1)>=0 || P2(i,j,1)>=0 || P3(i,j,1)>=0 || P4(i,j,1)>=0
750           PCmp(i,j)=(P1ErosionCoefficient*P1(i,j,1)*(P1(i,j,1)>0)+(P2ErosionCoefficient*P2(i,j,1)*(P2(i,j,1)>0))+
751             P3ErosionCoefficient*P3(i,j,1)*(P3(i,j,1)>0));%+(P4ErosionCoefficient*P4(i,j,1)*(P4(i,j,1)>0));
752         end
753       end
754     PCmp=(P1ErosionCoefficient.*P1(:,:,1)+(P2ErosionCoefficient.*P2(:,:,1)+(P3ErosionCoefficient.*P3(:,:,1)+(P4ErosionCoefficient.*P4(:,:,1)+(P3dErosionCoefficient.*P3d(:,:,1));
755 [ Hstar , P3 , MeanBeachWidth , ESL , WSL , MESL , MWSL , OL , SLRyrs , MigCnt , MigAccel ] = MarineProcesses03312021 ( Hstar , delta , L , P1 , P2 , P3 ,
756 P4 , BchMax , OW , t , SLRyrs , PCmp , IslandArea , MigCnt , ScaleFactor , MigYr , Ma , MigAccel , MasterMax );
757 elseif MPswitch==2
758   [ Hstar , PlantColumnArray , PlantColumnArray2 , P3 , flag , MeanBeachWidth ] = OLDMarineProcesses03312021 ( Hstar , delta , L , flag , PC , P3 ,
759 BchMax , BchW );
760 end
761 if MPswitch~=0
762   MeanBeachWidthVec(1)=MeanBeachWidth;
763   H=Hstar;
764 end
765
766 %%  %(4.AV*)update PC before avalanching again
767 %need to work this into the inside of PlantProcesses
768 for i=1:size(H,1)
769   for j=1:size(H,2)
770     %      PC1(i,j)=P1(i,j,1)*(P1(i,j,1)>0);
771     %      PC2(i,j)=P2(i,j,1)*(P2(i,j,1)>0); %
772     PC3(i,j)=P3(i,j,1)*(P3(i,j,1)>0); %p3 is only thing that changes inside of marine processes - killed on beach
773     %      PC4(i,j)=P4(i,j,1)*(P4(i,j,1)>0);
774   end
775 end
776 PC=(P1ErosionCoefficient.*PC1(:,:,1)+(P2ErosionCoefficient.*PC2(:,:,1)+(P3ErosionCoefficient.*PC3(:,:,1)+(P4ErosionCoefficient.*PC4(:,:,1)+(P3dErosionCoefficient.*P3d(:,:,1));
777 %%  %(4.AV) Avalanche after Marine Processes THIS AVALANCHE RUNS EVERY TIME STEP AND IS THE FINAL AVALANCHE
778 PassCount=1;
779 CellsMoved=zeros(1,1000);
780 [ Hstar , flag , CellCt ] = AVALANCHEtime03312021 ( Hstar , delta , L , flag , PC , t );
781 CellsMoved(PassCount)=CellCt;
782 while flag==1
783   PassCount=PassCount+1;

```

```

784     [Hstar ,flag ,CellCt]=AVALANCHEtime03312021(Hstar ,delta ,L, flag ,PC,t);
785     CellsMoved(PassCount)=CellCt;
786 end
787 CellsMoved=CellsMoved(1 ,1:PassCount );
788 Av3.Array=[TimeStep PassCount CellsMoved ];
789 AV.ARRAY(TimeStep+1,1:PassCount+2,3)=Av3.Array ;
790 %%      %(5) Data and categories in H
791 %***** NOT USING LAND CATEGORIZATION - BUT MAY AGAIN LATER - DO NOT DELETE!!
792 [Hstar ,P1,P2,P3,P4]=LandCategorizationUNUSED03312021(Hstar ,P1,P2,P3,P4,PlantColumnArray ,PlantColumnArray2 ,ColumnArraySwamp1 ,
793 ColumnArraySwamp2,INum);
794 %***** NOT USING LAND CATEGORIZATION - BUT MAY AGAIN LATER - DO NOT DELETE!!
795 [Hstar ,Centroid]=Qdata03312021(Hstar ,P1,P2,P3,P4);%,ESL,WSL,MESL,MWSL,OppositeLocation );
796 CentroidVec(t+1,:)=Centroid;
797
798 %calculating mean percent cover for each Pi
799 p1=P1(:, :, 1)>0;p2=P2(:, :, 1)>0;p3=P3(:, :, 1)>0;p4=P4(:, :, 1)>0;
800 P1gt=P1(:, :, 1).*p1;
801 P2gt=P2(:, :, 1).*p2;
802 P3gt=P3(:, :, 1).*p3;
803 P4gt=P4(:, :, 1).*p4;
804
805 MnP1(t+2)=sum(P1gt,'all')/sum(p1,'all');
806 MnP2(t+2)=sum(P2gt,'all')/sum(p2,'all');
807 MnP3(t+2)=sum(P3gt,'all')/sum(p3,'all');
808 MnP4(t+2)=sum(P4gt,'all')/sum(p4,'all');
809
810 %%%
811 %% Sea Level Rise %%
812 if SLRswitch==1
813     if 0==mod(t,156)%0==mod(t,156)      %156 timesteps = 312 weeks = 6 years
814         %    if 0==mod(t,260)
815             Hstar=Hstar-1; %working estimate for SLR in VA is 1.66cm/yr = .1m/6yrs
816     end
817 end
818 %%%
819 %% End Sea Level Rise %%
820 %%%
821
822 H=round(Hstar ,0);      %**** THIS IS THE ONLY UPDATE FOR H IN THE MAIN LOOP - OTHERWISE ALL UPDATES ARE MADE TO HSTAR
823
824 if t==1
825     Sv1=H(:, :, 1);
826     Sv1f=round(imgaussfilt(H(:, :, 1),4),0);
827     Sv1Cent=Centroid;
828 elseif t==338
829     Sv2=H(:, :, 1);
830     Sv2f=round(imgaussfilt(H(:, :, 1),4),0);
831     Sv2Cent=Centroid;
832 elseif t==702
833     Sv3=H(:, :, 1);
834     Sv3f=round(imgaussfilt(H(:, :, 1),4),0);
835     Sv3Cent=Centroid;
836 end
837
838 tEnd=cputime-tStart;

```

```

839
840
841     T(t+1)=toc;
842     fprintf ('\n')
843     if t==0
844         Tnew=T(t+1)-T(t);
845     else
846         Tnew=T(1);
847     end
848     fprintf ('t=%d time: %0.1f',TimeStep,Tnew)
849 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%% During Images %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
850 %%%
851 %%%
852 %%%
853 %% % % % %ELEVATION
854
855 if ElevIm.during==1
856     Hfilt=round(imgaussfilt(H(:,:,1),4),0);
857     if (0==mod(t,DurImFreq))
858
859         %
860         figure
861
862             %
863             colormap(jet())
864             imagesc(H(:,:,1),climsH);
865             hold on
866             if MElevCont==1
867                 contour(H(:,:,1),[-5 -5],'color','m','linewidth',1.1)
868             end
869             if SElevCont==1
870                 contour(Hfilt(:,:,1),[-0 -0],'color','k','linewidth',1.1)
871             end
872             if MElevCont==1 && SElevCont==1
873                 lgnd=legend ('\color{white} marsh contour (-0.5m)', '\color{white} sea level contour (0m)');
874                 set(lgnd,'color','none','location','southeast');
875             elseif MElevCont==1 && SElevCont==0
876                 lgnd=legend ('\color{white} marsh contour (-0.5m)');
877                 set(lgnd,'color','none','location','southeast');
878             elseif SElevCont==1 && MElevCont==0
879                 lgnd=legend ('\color{white} sea level contour (0m)');
880                 set(lgnd,'color','none','location','southeast');
881             end
882             colorbar
883             title(sprintf('Elevation at %d years',t/26))
884             hold off
885
886         end
887     end
888
889 %This is the unsmoothed transect migration image
890 %% % % % if TransectIm==1
891 %% % % % if 0==mod(t,TranImFreq)
892 %% % % % Trow=H(TranRow,:,:1);
893 %% % % % Trow=(Trow<-5)==-6;
894 %% % % % xlim1=find(Trow>=-5,1,'first')-100; xlim2=find(Trow>=-5,1,'last')+100;

```

```

891 % % %
892 % % %
893 % % %
894 % % %
895 % % %
896 % % %
897 % % %
898 % % %
899 % % %
900 %%Close up elev:
901 if ElevImCU_during==1
902 if (0==mod(t,DurCUImFreq))
903 Wndw=250;
904 MidRow=round(Centroid(2));
905 MidCol=round(Centroid(1));
906 figure
907 imagesc(H(MidRow-Wndw:MidRow+Wndw, MidCol-Wndw: MidCol+Wndw,1),climsH);
908 hold on
909 ContourVec=[0:10:max(max(Hfilt))];
910 colorbar
911 contour(Hfilt(MidRow-Wndw:MidRow+Wndw, MidCol-Wndw: MidCol+Wndw,1),ContourVec);
912 contour(Hfilt(MidRow-Wndw:MidRow+Wndw, MidCol-Wndw: MidCol+Wndw,1),ContourVec,'LineColor','k');
913 [C,h]=contour(Hfilt(MidRow-Wndw:MidRow+Wndw, MidCol-Wndw: MidCol+Wndw,1),ContourVec,'LineColor','k');
914 clabel(C,h)
915 title(sprintf('Elevation Close-Up about Centroid at %d years',t/26))
916 %% old one (lines at 10, 20 close up):
917 figure

%
918 colormap(jet())
919 MidPt=round(CentroidVec(t+1,:));
920 MidCol=MidPt(1); MidRow=MidPt(2);
921 imagesc(H(MidRow-50:MidRow+50, MidCol-50:MidCol+50,1),climsH);
922 hold on
923 ContourVec=[0:5:max(max(Hfilt))];
924 contour(Hfilt(MidRow-50:MidRow+50, MidCol-50:MidCol+50,1),[10 10],'Color','m','linewidth',1.1);
925 contour(Hfilt(MidRow-50:MidRow+50, MidCol-50:MidCol+50,1),[20 20],'Color','k','linewidth',1.1);
926 lgnd=legend('\color{white} marsh contour (-0.5m)', '\color{white} sea level contour (0m)');
927 set(lgnd,'color','none','location','southeast');
928 colorbar
929 title(sprintf('Elevation Close-Up about Centroid at %d years',t/26))
930 hold off
931
932
933 hFig=figure;
934 set(gcf,'PaperPositionMode','auto')
935 set(hFig,'units','inches')
936 hFig.Position(1)=.5;
937 hFig.Position(2)=.5;
938 hFig.Position(3)=2*hFig.Position(3);
939 hFig.Position(4)=1.25*hFig.Position(4);
940 subplot(1,2,1)
941 colormap(jet())
942 imagesc(H(MidRow-Wndw:MidRow+Wndw, MidCol-Wndw: MidCol+Wndw,1),climsH);
943 title(sprintf('Elevation Close-Up about Centroid at %d years',t/26))
944 subplot(1,2,2)

```

```

945 [C,h] = contour (Hfilt(MidRow-Wndw:MidRow+Wndw, MidCol-Wndw:MidCol+Wndw,1) ,ContourVec);
946 xlabel(C,h)
947 set(gca,'YDir','reverse')
948 title(sprintf('Contours of Elevation Close-Up about Centroid at %d years',t/26))
949
950
951 figure
952 subplot(2,2,1)
953 colormap bone
954 imagesc(P1(MidRow-Wndw:MidRow+Wndw, MidCol-Wndw:MidCol+Wndw,1),climsP);
955 title(sprintf('P_1 about centroid at %d years',t/26))
956 subplot(2,2,2)
957 colormap bone
958 imagesc(P2(MidRow-Wndw:MidRow+Wndw, MidCol-Wndw:MidCol+Wndw,1),climsP);
959 title(sprintf('P_2 about centroid at %d years',t/26))
960 subplot(2,2,3)
961 colormap bone
962 imagesc(P3(MidRow-Wndw:MidRow+Wndw, MidCol-Wndw:MidCol+Wndw,1),climsP);
963 title(sprintf('P_3 about centroid at %d years',t/26))
964 subplot(2,2,4)
965 colormap bone
966 imagesc(P4(MidRow-Wndw:MidRow+Wndw, MidCol-Wndw:MidCol+Wndw,1),climsP);
967 title(sprintf('P_4 about centroid at %d years',t/26))
968 end
969 end
970
971 % % % % Land Category
972
973 if LandCatIm.during==1
974 if (0==mod(t,DurImFreq)) %every 5 years
975
976 figure
977
978 colormap(jet())
979 clim=[min(min(H(:,:,2))) max(max(H(:,:,2)))];
980 imagesc(H(:,:,2),clims);
981 colorbar
982 title(sprintf('Land Category at time step = %d',t))
983 end
984 end
985
986 % % % % Plant Percent Cover%
987
988 if PlantPCIm.during==1
989 if (0==mod(t,PlantDurImFreq)) % 2^-/mo, choose 26^-/year
990
991 %% AMMOPHILA
992 figure
993 colormap gray
994 clim=[-1 max(0,max(max(P1(:,:,1))))];
995 imagesc(P1(:,:,1),climsP)
996 colorbar
997 title(sprintf('P1-Ammophila at %d years',t/26))
998 title(sprintf('P1-Ammophila at time step = %d',t))

```

```

997      %% SPARTINA
998      figure
999      colormap gray
1000      %      clims=[-.1 max(0,max(max(P2(:,:,1))))];
1001      imagesc(P2(:,:,1),climsP)
1002      colorbar%
1003      title(sprintf('P2 - Spartina patens at %d years',t/26))
1004      %      title(sprintf('P2 - Spartina patens at time step = %d',t))
1005      %% MORELLA
1006      figure
1007      colormap gray
1008      %      clims=[-.1 max(0,max(max(P3(:,:,1))))];
1009      imagesc(P3(:,:,1),climsP)
1010      colorbar%
1011      title(sprintf('P3 - Morella at %d years',t/26))
1012      %      title(sprintf('P3 - Morella at time step = %d',t))
1013      %% DEAD MORELLA
1014      figure
1015      colormap gray
1016      %      clims=[-.1 max(0,max(max(P3d(:,:,1))))];
1017      imagesc(P3d(:,:,1),climsP)
1018      colorbar
1019      title(sprintf('P3d - DEAD Morella at %d years',t/26))
1020      %      title(sprintf('P3d - DEAD Morella at time step = %d',t))
1021      %% SPARTINA (marsh)
1022      figure
1023      colormap gray
1024      %      clims=[-.1 max(1,max(max(P4(:,:,1))))];
1025      imagesc(P4(:,:,1),climsP)
1026      colorbar
1027      title(sprintf('P4 - Spartina alterniflora at %d years',t/26))
1028      %      title(sprintf('P4 - Spartina alterniflora at time step = %d',t))
1029      end
1030
1031      end
1032
1033      end
1034      %% END OF MAIN LOOP %%
1035
1036
1037      %%
1038      %% After Images %%
1039      %% After Images %%
1040
1041
1042      % % % Elevation
1043      if ElevIm_after==1
1044          figure
1045          colormap(jet())
1046          imagesc(H(:,:,1),climsH);
1047          hold on
1048          contour(H(:,:,1),[-0.5 -0.5], 'color', 'black')
1049          colorbar
1050          title('After Image')
1051      end
1052

```

```

1053 %Mean Plant Percent Cover Images
1054 if MnPlantCvrIm==1
1055 figure
1056 hold on
1057 plot(MnP1)
1058 plot(MnP2)
1059 plot(MnP3)
1060 plot(MnP4)
1061 legend('P_1','P_2','P_3','P_4')
1062 xlabel('time in two week steps')
1063 ylabel('Mean Percent Cover')
1064 title(sprintf('Mean Percent Cover - %.0f years',time/26))
1065 end
1066
1067 % % % %Land Category
1068
1069 if LandCatIm_after==1
1070 figure
1071 colormap(jet())
1072 clims=[min(min(H(:,:,2))) max(max(H(:,:,2)))];
1073 imagesc(H(:,:,2),clims);
1074 colorbar
1075 title(sprintf('Land Category - After'))
1076 end
1077
1078 % % % %PLANTS (percent cover)
1079
1080 if PlantPCIm_after==1
1081 %% AMMOPHILA
1082 figure
1083 colormap gray
1084 imagesc(P1(:,:,1),climsP)
1085 colorbar
1086 title(sprintf('P1-Ammophila After %d years',time/26))
1087 %% SPARTINA
1088 figure
1089 colormap gray
1090 imagesc(P2(:,:,1),climsP)
1091 colorbar
1092 title(sprintf('P2 - Spartina patens after %d years',time/26))
1093 %% MORELLA
1094 figure
1095 colormap gray
1096 imagesc(P3(:,:,1),climsP)
1097 colorbar%
1098 title(sprintf('P3 - Morella after %d years',time/26))
1099 %% SPARTINA (marsh)
1100 figure
1101 colormap gray
1102 imagesc(P4(:,:,1),climsP)
1103 colorbar
1104 title(sprintf('P4 - Spartina alterniflora after %d years',time/26))
1105 end
1106
1107 %% Contours at 0, 13, and 27 years
1108 if Contour27==1

```

```

1109 %Contours of the shoreline (0m elevation)
1110 figure

    %

1111 colormap(jet())
1112 hold on
1113 contour(Sv1f(:, :, 1), [1 1], 'Color', 'blue', 'LineWidth', 2);           %beginning contour (after initialization)
1114 contour(Sv2f(:, :, 1), [1 1], 'Color', 'green', 'LineWidth', 2);          %contour at 13 years (t=338)
1115 contour(Sv3f(:, :, 1), [1 1], 'Color', 'red', 'LineWidth', 2);            %contour at 27 years (t=702)
1116 scatter(Sv1Cent(1), Sv1Cent(2), 'o', 'MarkerEdgeColor', 'k', 'MarkerFaceColor', 'b')
1117 scatter(Sv2Cent(1), Sv2Cent(2), 'o', 'MarkerEdgeColor', 'k', 'MarkerFaceColor', 'g')
1118 scatter(Sv3Cent(1), Sv3Cent(2), 'o', 'MarkerEdgeColor', 'k', 'MarkerFaceColor', 'r')
1119 % scatter(Sv1Cent(1),Sv1Cent(2),'o','MarkerEdgeColor','w',...
1120 %                           'MarkerFaceColor','b',...
1121 %                           'LineWidth',1.25)
1122 % scatter(Sv2Cent(1),Sv2Cent(2),'o','MarkerEdgeColor','w',...
1123 %                           'MarkerFaceColor','g',...
1124 %                           'LineWidth',1.25)
1125 % scatter(Sv3Cent(1),Sv3Cent(2),'o','MarkerEdgeColor','w',...
1126 %                           'MarkerFaceColor','r',...
1127 %                           'LineWidth',1.25)
1128 set(gca, 'YDir', 'reverse')
1129 legend('Initial', '13 years', '27 years', 'Location', 'southeast')
1130 title('Island Contours at 0m Elevation')
1131
1132 %contours including the marsh area:
1133 %% % % figure

    %

1134 %% % % colormap(jet())
1135 %% % % hold on
1136 %% % % contour(Sv1f(:, :, 1), [-5 -5], 'Color', 'blue', 'LineWidth', 2);      %beginning contour (after initialization)
1137 %% % % contour(Sv2f(:, :, 1), [-5 -5], 'Color', 'green', 'LineWidth', 2);        %contour at 13 years (t=338)
1138 %% % % contour(Sv3f(:, :, 1), [-5 -5], 'Color', 'red', 'LineWidth', 2);          %contour at 27 years (t=702)
1139 %% % % scatter(Sv1Cent(1),Sv1Cent(2), 'o', 'MarkerEdgeColor', 'k', 'MarkerFaceColor', 'b')
1140 %% % % scatter(Sv2Cent(1),Sv2Cent(2), 'o', 'MarkerEdgeColor', 'k', 'MarkerFaceColor', 'g')
1141 %% % % scatter(Sv3Cent(1),Sv3Cent(2), 'o', 'MarkerEdgeColor', 'k', 'MarkerFaceColor', 'r')
1142 %% % % scatter(Sv3Cent(1),Sv3Cent(2), '*r')
1143 %% % % scatter(Sv2Cent(1),Sv2Cent(2), '*g')
1144 %% % % scatter(Sv1Cent(1),Sv1Cent(2), '*b')
1145 %% % % set(gca, 'YDir', 'reverse')
1146 %% % % legend('Initial', '13 years', '27 years', 'Location', 'southeast')
1147 %% % % title('Island Contours with Marshland (at -0.5m Elevation)')
1148 end
1149
1150 if TransectIm==1
1151     figure
1152     Trow1=Sv1f(TranRow, :, 1);
1153     Trow2=Sv2f(TranRow, :, 1);
1154     Trow3=Sv3f(TranRow, :, 1);
1155     Trow1(Trow1<-5)=-6; Trow2(Trow2<-5)=-6; Trow3(Trow3<-5)=-6;
1156     xlim1=find(Trow1>=-5, 1, 'first')-100; xlim2=find(Trow1>=-5, 1, 'last')+100;
1157     hold on
1158     plot(1:size(H, 2), Trow1, '-.', 'Linewidth', 2)
1159     plot(1:size(H, 2), Trow2, ':', 'Linewidth', 2)
1160     plot(1:size(H, 2), Trow3, ':', 'Linewidth', 2)

```

```
1161     xlim([xlim1 xlim2])
1162     ylim([-5,max(Trow1)+20])
1163     title(sprintf('Island transect at row %d',TranRow))
1164     legend('Initial','13 years','27 years','Location','northwest')
1165     hold off
1166 end
1167
1168 fprintf('DONE!')
1169 toc
1170
1171 %!!!!!!!!!!!!!!no, seriously ... it's over!!!!!!!!!!!!!!%
```

B.2 Aeolian Transport code

```

1 function [Hstar]=AeolianTransport03312021(Hstar,delta,L,W,Windspeed,Windmin,StormThreshold,WindDir,PC)
2
3 %Aeolian Transport is triggered by sufficient wind speeds chosen in the MainCode.
4 %AT determines the number of cells that the sediment will move based on the
5 %current windspeed:
6 %           windspeed < 6 move 1 cell
7 %           6<= windspeed < 11 move 2 cells
8 %           11<= windspeed < 16 move 3 cells
9
10 %When each cell is polled the plant density on that cell is accounted for,
11 %but it is assumed that after initial saltation the sediment is moving
12 %freely enough so as not to require polling subsequent cells' plant cover.
13 %The angle between the current cell and the next potential cell is checked
14 %for every step 1, 2, and 3.
15
16 %each cell has a probability of moving either in the same direction as the
17 %EindDirection input or one of the two off-directions
18 % (i.e. if WindDir is North: 50% move North, 25% move NorthEast, 25% move NorthWest
19
20
21 MvF=.8; %movement probability factor (turn up for more movement, down for less)
22
23 Hp=padarray(Hstar(:,:,1),[3 3]); %padding Hstar with three extra rows/cols in each direction - avoids index errors
24 %cells moved into padded region are
25 %deleted when Hstar is redeclared
26 %after each loop
27 [n1 n2]=size(Hstar(:,:,1)); %array indexes for loop
28
29 %
30 % fprintf('I am running AT! ')
31
32
33 %can move up to three cells based on windspeed
34 MvCnt=1*(Windspeed>=6)+1*(Windspeed>=9)+1*(Windspeed>=12);
35
36 %***about MarshFlag*** - we are currently allowing the wind to affect cells in
37 %the swamp, but previously we were flagging them so that they would not be
38 %moved. If you do not want the wind to move swamp cells then change the
39 %rows labeled below
40
41 for i=4:n1+3
42     Rnow=Hp(i,:);
43     for j=n2+3:-1:4
44         MarshFlag=0; %flagging cells in the marsh
45         if Rnow(j)>=0
46             if (Rnow(j)> 0)&& Rnow(j)<=1
47                 if j==1
48                     if Rnow(j)<Rnow(j+1) && Rnow(j+1)<Rnow(j+2)
49                         MarshFlag=0; %<--change to MarshFlag=1; if wish to ignore marsh cells
50                 end
51             elseif j==n2

```

```

52         if Know(j)>Know(j-1) && Know(j-1)>Know(j-2)
53             MarshFlag=0;                                     %<--change to MarshFlag=1; if wish to ignore marsh cells
54         end
55     else
56         if Know(j)<Know(j+1) && Know(j-1)<Know(j)
57             MarshFlag=0;                                     %<--change to MarshFlag=1; if wish to ignore marsh cells
58         end
59     end
60 end
61
62 if Know(j)>0 && MarshFlag==0
63     %probability for RNG use
64     P=0.5;      %P splits the likelihood of moving in primary wind direction or the two alternative directions
65     Rand=rand; %for probability check
66     MoveChance=(1-PC(i,j))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin))*MvF;    %cells chance of moving,
67     %actors in plants and windseed ranges
68     dist=round(MvCnt*MoveChance,0); %number of cells a slab can potentially move
69
70 %% DEPOSITION RULES: %%
71 %%%
72
73 %Wind Direction
74 %1=N 2=NE 3=E 4=SE 5=S 6=SW 7=W 8=NW
75
76 Nhd=Hp(i-3:i+3,j-3:j+3); %7x7 moving window for movement up to three cells
77 PCNhd=PC(i-3:i+3,j-3:j+3);
78 %
79 %NORTH BLOCK
80
81 %NORTH - NW
82
83 if WindDir==1 && Rand<MoveChance
84     if Rand<((1-P)/2) %&& (i>3) && (j>3) %move to the port slab I don't think I need to worry about these if I
85         use the padded array
86     DirV=[Nhd(4,4), Nhd(3,3), Nhd(2,2), Nhd(1,1)]; %vector of neighborhood Hstar values in the direction
87         of chosen movement
88
89 %next line for re-calculating chance of moving from new cell - if we wish to poll for plant cover at each step at some
90 %later time
91 PCNE=[PCNhd(4,4), PCNhd(3,3), PCNhd(2,2), PCNhd(1,1)];
92
93 flag=1; %trigger the cell movement
94 k=1;    %count for number of cells moved so far in while loop
95 while flag==1
96     if atan(((DirV(k+1)-DirV(k))*delta)/L)<(pi/12) % if the angle between current cell and cell being
97         moved to is sufficiently shallow
98         DirV(k)=DirV(k)-1;                                %remove one slab from current cell
99         DirV(k+1)=DirV(k+1)+1;                            %add that cell to neighbor
100        k=k+1;                                         %add one to cell moved count
101        flag=1*(k<=dist);                             %repeat until k is equal to distance calculated
102            earlier
103
104 %next line for re-calculating chance of moving from new cell - if we wish to poll for plant cover at each step at some

```

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later time
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149
150
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152
MoveChance=(1-PCNE(k)) *((max(Windspeed-Windmin,0))/(StormThreshold-Windmin))*MvF;
if Rand >= MoveChance
    flag =0;
end
else
    flag =0;
        %if too steep an angle is encountered , movement
        stops
end
end
Nh(4,4)=DirV(1);
%replace neighborhood values with the direction
vector values
Nh(3,3)=DirV(2);
Nh(2,2)=DirV(3);
Nh(1,1)=DirV(4);

%NORTH - N
elseif Rand>=((1-P)/2) && Rand<((1+P)/2) && (i>1) %move with the wind / North
DirV=[Nh(4,4), Nh(3,4), Nh(2,4), Nh(1,4)];
PCNE=[PCNh(4,4), PCNh(3,4), PCNh(2,4), PCNh(1,4)];
flag=1;
k=1;
while flag==1
    if atan(((DirV(k+1)-DirV(k))*delta)/L)<(pi/12)
        DirV(k)=DirV(k)-1;
        DirV(k+1)=DirV(k+1)+1;
        cellcnt=cellcnt+1;
        MoveChance=(1-PCNE(k+1)) *((max(Windspeed-Windmin,0))/(StormThreshold-Windmin));
        k=k+1;
        flag=1*(k<=dist);
        MoveChance=(1-PCNE(k)) *((max(Windspeed-Windmin,0))/(StormThreshold-Windmin))*MvF;
        if Rand >= MoveChance
            flag=0;
        end
    else
        flag=0;
    end
end
Nh(4,4)=DirV(1);
Nh(3,4)=DirV(2);
Nh(2,4)=DirV(3);
Nh(1,4)=DirV(4);

%NORTH - NE
elseif Rand>=((1+P)/2) && (i>1) && (j<size(Hstar,2)) %move to the starboard slab
DirV=[Nh(4,4), Nh(3,5), Nh(2,6), Nh(1,7)];
PCNE=[PCNh(4,4), PCNh(3,5), PCNh(2,6), PCNh(1,7)];
flag=1;
k=1;
while flag==1
    if atan(((DirV(k+1)-DirV(k))*delta)/L)<(pi/12)
        DirV(k)=DirV(k)-1;
        DirV(k+1)=DirV(k+1)+1;
        cellcnt=cellcnt+1;
        MoveChance=(1-PCNE(k+1)) *((max(Windspeed-Windmin,0))/(StormThreshold-Windmin));

```

```

153
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169 %

170
171 %NORTH - EAST BLOCK
172
173 elseif WindDir==2 && rand<MoveChance
174
175 %MOVE N
176 if Rand<((1-P)/2) && (i>1)
177 DirV=[Nhd(4,4), Nhd(3,4), Nhd(2,4), Nhd(1,4)];
178 PCNE=[PCNhd(4,4), PCNhd(3,4), PCNhd(2,4), PCNhd(1,4)];
179 flag=1;
180 k=1;
181 while flag==1
182 if atan(((DirV(k+1)-DirV(k))*delta)/L)<(pi/12)
183 DirV(k)=DirV(k)-1;
184 DirV(k+1)=DirV(k+1)+1;
185 cellcnt=cellcnt+1;
186 MoveChance=(1-PCNE(k+1))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin));
187 k=k+1;
188 flag=1*(k<=dist);
189 MoveChance=(1-PCNE(k))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin))*MvF;
190 if Rand >= MoveChance
191 flag=0;
192 end
193 else
194 flag=0;
195 end
196 end
197 Nhd(4,4)=DirV(1);
198 Nhd(3,4)=DirV(2);
199 Nhd(2,4)=DirV(3);
200 Nhd(1,4)=DirV(4);
201 %
202 %MOVE NE
203 elseif Rand>=((1-P)/2) && Rand<((1+P)/2)% && (i>1) && (j<size(Hstar,2))
204 DirV=[Nhd(4,4), Nhd(3,5), Nhd(2,6), Nhd(1,7)];
205 PCNE=[PCNhd(4,4), PCNhd(3,5), PCNhd(2,6), PCNhd(1,7)];
206 flag=1;

```

```

207     k=1;
208
209     while flag==1
210         if atan(((DirV(k+1)-DirV(k))*delta)/L)<(pi/12)
211             DirV(k)=DirV(k)-1;
212             DirV(k+1)=DirV(k+1)+1;
213             %cellcnt=cellcnt+1;
214             MoveChance=(1-PCNE(k+1))*(max(Windspeed-Windmin,0))/(StormThreshold-Windmin));
215             k=k+1;
216             flag=1*(k<=dist);
217             MoveChance=(1-PCNE(k))*(max(Windspeed-Windmin,0))/(StormThreshold-Windmin)*MvF;
218             if Rand >= MoveChance
219                 flag=0;
220             end
221         else
222             flag=0;
223         end
224     end
225     Nhd(4,4)=DirV(1);
226     Nhd(3,5)=DirV(2);
227     Nhd(2,6)=DirV(3);
228     Nhd(1,7)=DirV(4);
229
230     %MOVE E
231     elseif Rand>=(1+P)/2% && (j<size(Hstar,2))
232         DirV=[Nhd(4,4), Nhd(4,5), Nhd(4,6), Nhd(4,7)];
233         PCNE=[PCNhd(4,4), PCNhd(4,5), PCNhd(4,6), PCNhd(4,7)];
234         flag=1;
235         k=1;
236         while flag==1
237             if atan(((DirV(k+1)-DirV(k))*delta)/L)<(pi/12)
238                 DirV(k)=DirV(k)-1;
239                 DirV(k+1)=DirV(k+1)+1;
240                 cellcnt=cellcnt+1;
241                 MoveChance=(1-PCNE(k+1))*(max(Windspeed-Windmin,0))/(StormThreshold-Windmin));
242                 k=k+1;
243                 flag=1*(k<=dist);
244                 MoveChance=(1-PCNE(k))*(max(Windspeed-Windmin,0))/(StormThreshold-Windmin)*MvF;
245                 if Rand >= MoveChance
246                     flag=0;
247                 end
248             else
249                 flag=0;
250             end
251         end
252         Nhd(4,4)=DirV(1);
253         Nhd(4,5)=DirV(2);
254         Nhd(4,6)=DirV(3);
255         Nhd(4,7)=DirV(4);
256
257     end
258
259     %EAST BLOCK
260

```

```

261 elseif WindDir==3 && rand<MoveChance
262
263 %MOVES NE
264 if Rand<((1-P)/2) && (i>1) && (j<size(Hstar,2))
265 DirV=[Nhd(4,4), Nhd(3,5), Nhd(2,6), Nhd(1,7)];
266 PCNE=[PCNhd(4,4), PCNhd(3,5), PCNhd(2,6), PCNhd(1,7)];
267 flag=1;
268 k=1;
269 while flag==1
270 if atan(((DirV(k+1)-DirV(k))*delta)/L)<(pi/12)
271 DirV(k)=DirV(k)-1;
272 DirV(k+1)=DirV(k+1)+1;
273 cellcnt=cellcnt+1;
274 MoveChance=(1-PCNE(k+1))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin));
275 k=k+1;
276 flag=1*(k<=dist);
277 MoveChance=(1-PCNE(k))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin))*MvF;
278 if Rand >= MoveChance
279 flag=0;
280 end
281 else
282 flag=0;
283 end
284 end
285 Nhd(4,4)=DirV(1);
286 Nhd(3,5)=DirV(2);
287 Nhd(2,6)=DirV(3);
288 Nhd(1,7)=DirV(4);
289
290 %MOVES E
291 elseif Rand>=((1-P)/2) && Rand<((1+P)/2) && (j<size(Hstar,2))
292 DirV=[Nhd(4,4), Nhd(4,5), Nhd(4,6), Nhd(4,7)];
293 PCNE=[PCNhd(4,4), PCNhd(4,5), PCNhd(4,6), PCNhd(4,7)];
294 flag=1;
295 k=1;
296 while flag==1
297 if atan(((DirV(k+1)-DirV(k))*delta)/L)<(pi/12)
298 DirV(k)=DirV(k)-1;
299 DirV(k+1)=DirV(k+1)+1;
300 cellcnt=cellcnt+1;
301 MoveChance=(1-PCNE(k+1))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin));
302 k=k+1;
303 flag=1*(k<=dist);
304 MoveChance=(1-PCNE(k))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin))*MvF;
305 if Rand >= MoveChance
306 flag=0;
307 end
308 else
309 flag=0;
310 end
311 end
312 Nhd(4,4)=DirV(1);
313 Nhd(4,5)=DirV(2);
314 Nhd(4,6)=DirV(3);
315 Nhd(4,7)=DirV(4);
316

```



```

371           end
372       else
373           flag=0;
374       end
375   end
376   Nhd(4,4)=DirV(1);
377   Nhd(4,5)=DirV(2);
378   Nhd(4,6)=DirV(3);
379   Nhd(4,7)=DirV(4);

380
381
382 %MOVES SE
383 elseif Rand>=(1-P)/2 && Rand<((1+P)/2) && (i<size(Hstar,1)) && (j<size(Hstar,2))
384 DirV=[Nhd(4,4), Nhd(5,5), Nhd(6,6), Nhd(7,7)];
385 PCNE=[PCNhd(4,4), PCNhd(5,5), PCNhd(6,6), PCNhd(7,7)];
386 flag=1;
387 k=1;
388 while flag==1
389     if atan(((DirV(k+1)-DirV(k))*delta)/L)<(pi/12)
390         DirV(k)=DirV(k)-1;
391         DirV(k+1)=DirV(k+1)+1;
392         cellcnt=cellcnt+1;
393         MoveChance=(1-PCNE(k+1))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin));
394         k=k+1;
395         flag=1*(k<=dist);
396         MoveChance=(1-PCNE(k))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin))*MvF;
397         if Rand >= MoveChance
398             flag=0;
399         end
400     else
401         flag=0;
402     end
403 end
404 Nhd(4,4)=DirV(1);
405 Nhd(5,5)=DirV(2);
406 Nhd(6,6)=DirV(3);
407 Nhd(7,7)=DirV(4);

408
409 %MOVES S
410 elseif Rand>=((1+P)/2) && (i<size(Hstar,1))
411 DirV=[Nhd(4,4), Nhd(5,4), Nhd(6,4), Nhd(7,4)];
412 PCNE=[PCNhd(4,4), PCNhd(5,4), PCNhd(6,4), PCNhd(7,4)];
413 flag=1;
414 k=1;
415 while flag==1
416     if atan(((DirV(k+1)-DirV(k))*delta)/L)<(pi/12)
417         DirV(k)=DirV(k)-1;
418         DirV(k+1)=DirV(k+1)+1;
419         cellcnt=cellcnt+1;
420         MoveChance=(1-PCNE(k+1))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin));
421         k=k+1;
422         flag=1*(k<=dist);
423         MoveChance=(1-PCNE(k))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin))*MvF;
424         if Rand >= MoveChance
425             flag=0;
426         end

```

```

427           else
428               flag=0;
429           end
430       end
431       Nhd(4,4)=DirV(1);
432       Nhd(5,4)=DirV(2);
433       Nhd(6,4)=DirV(3);
434       Nhd(7,4)=DirV(4);
435
436   end
437
438 %
```

%%%%%%%%%%%%%

```

439
440 %SOUTH BLOCK
441
442 elseif WindDir==5 && rand<MoveChance
443
444 %MOVES SE
445 if Rand<((1-P)/2) && (i<size(Hstar,1)) && (j<size(Hstar,2))
446     DirV=[Nhd(4,4), Nhd(5,5), Nhd(6,6), Nhd(7,7)];
447     PCNE=[PCNh(4,4), PCNh(5,5), PCNh(6,6), PCNh(7,7)];
448     flag=1;
449     k=1;
450     while flag==1
451         if atan(((DirV(k+1)-DirV(k))*delta)/L)<(pi/12)
452             DirV(k)=DirV(k)-1;
453             DirV(k+1)=DirV(k+1)+1;
454             cellcnt=cellcnt+1;
455             MoveChance=(1-PCNE(k+1))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin));
456             k=k+1;
457             flag=1*(k<=dist);
458             MoveChance=(1-PCNE(k))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin))*MvF;
459             if Rand >= MoveChance
460                 flag=0;
461             end
462         else
463             flag=0;
464         end
465     end
466     Nhd(4,4)=DirV(1);
467     Nhd(5,5)=DirV(2);
468     Nhd(6,6)=DirV(3);
469     Nhd(7,7)=DirV(4);
470
471 %MOVES S
472 elseif Rand>=(1-P)/2 && Rand<((1+P)/2) && (i<size(Hstar,1))
473     DirV=[Nhd(4,4), Nhd(5,4), Nhd(6,4), Nhd(7,4)];
474     PCNE=[PCNh(4,4), PCNh(5,4), PCNh(6,4), PCNh(7,4)];
475     flag=1;
476     k=1;
477     while flag==1
478         if atan(((DirV(k+1)-DirV(k))*delta)/L)<(pi/12)
479             DirV(k)=DirV(k)-1;
480             DirV(k+1)=DirV(k+1)+1;
```

```

481 %           cellcnt=cellcnt+1;
482 %           MoveChance=(1-PCNE(k+1))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin));
483 k=k+1;
484 flag=1*(k<=dist);
485 MoveChance=(1-PCNE(k))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin))*MvF;
486 if Rand >= MoveChance
487     flag=0;
488 end
489 else
490     flag=0;
491 end
492 end
493 Nhd(4,4)=DirV(1);
494 Nhd(5,4)=DirV(2);
495 Nhd(6,4)=DirV(3);
496 Nhd(7,4)=DirV(4);
497
498 %MOVES SW
499 elseif Rand>=((1+P)/2) && (i<size(Hstar,1)) && (j>1)
500 DirV=[Nhd(4,4), Nhd(5,3), Nhd(6,2), Nhd(7,1)];
501 PCNE=[PCNhd(4,4), PCNhd(5,3), PCNhd(6,2), PCNhd(7,1)];
502 flag=1;
503 k=1;
504 while flag==1
505     if atan(((DirV(k+1)-DirV(k))*delta)/L)<(pi/12)
506         DirV(k)=DirV(k)-1;
507         DirV(k+1)=DirV(k+1)+1;
508         cellcnt=cellcnt+1;
509         MoveChance=(1-PCNE(k+1))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin));
510         k=k+1;
511         flag=1*(k<=dist);
512         MoveChance=(1-PCNE(k))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin))*MvF;
513         if Rand >= MoveChance
514             flag=0;
515         end
516     else
517         flag=0;
518     end
519 end
520 Nhd(4,4)=DirV(1);
521 Nhd(5,3)=DirV(2);
522 Nhd(6,2)=DirV(3);
523 Nhd(7,1)=DirV(4);
524
525
526 %
527 %SOUTH-WEST BLOCK
528
529
530 elseif WindDir==6 && rand<MoveChance
531
532 %MOVES S
533 if Rand<((1-P)/2) && (i<size(Hstar,1))
534     DirV=[Nhd(4,4), Nhd(5,4), Nhd(6,4), Nhd(7,4)];

```

```

535 PCNE=[PCNhd(4,4), PCNhd(5,4), PCNhd(6,4), PCNhd(7,4)];
536 flag=1;
537 k=1;
538 while flag==1
539 if atan(((DirV(k+1)-DirV(k))*delta)/L)<(pi/12)
540 DirV(k)=DirV(k)-1;
541 DirV(k+1)=DirV(k+1)+1;
542 % cellcnt=cellcnt+1;
543 % MoveChance=(1-PCNE(k+1))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin));
544 k=k+1;
545 flag=1*(k<=dist);
546 MoveChance=(1-PCNE(k))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin))*MvF;
547 if Rand >= MoveChance
548 flag=0;
549 end
550 else
551 flag=0;
552 end
553 end
554 Nhd(4,4)=DirV(1);
555 Nhd(5,4)=DirV(2);
556 Nhd(6,4)=DirV(3);
557 Nhd(7,4)=DirV(4);
558
559
560 %MOVES SW
561 elseif Rand>=((1-P)/2) && Rand<=((1+P)/2) %&& (i<size(Hstar,1)) && (j>1)
562 DirV=[Nhd(4,4), Nhd(5,3), Nhd(6,2), Nhd(7,1)];
563 PCNE=[PCNhd(4,4), PCNhd(5,3), PCNhd(6,2), PCNhd(7,1)];
564 flag=1;
565 k=1;
566 while flag==1
567 if atan(((DirV(k+1)-DirV(k))*delta)/L)<(pi/12)
568 DirV(k)=DirV(k)-1;
569 DirV(k+1)=DirV(k+1)+1;
570 % cellcnt=cellcnt+1;
571 % MoveChance=(1-PCNE(k+1))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin));
572 k=k+1;
573 flag=1*(k<=dist);
574 MoveChance=(1-PCNE(k))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin))*MvF;
575 if Rand >= MoveChance
576 flag=0;
577 end
578 else
579 flag=0;
580 end
581 end
582 Nhd(4,4)=DirV(1);
583 Nhd(5,3)=DirV(2);
584 Nhd(6,2)=DirV(3);
585 Nhd(7,1)=DirV(4);
586
587
588 %MOVES W
589 elseif Rand>=((1+P)/2) %&& (j>1)
590 DirV=[Nhd(4,4), Nhd(4,3), Nhd(4,2), Nhd(4,1)];

```

```

591 PCNE=[PCNhd(4,4) , PCNhd(4,3) , PCNhd(4,2) , PCNhd(4,1) ];
592 flag=1;
593 k=1;
594 while flag==1
595 if atan(((DirV(k+1)-DirV(k))*delta)/L)<(pi/12)
596 DirV(k)=DirV(k)-1;
597 DirV(k+1)=DirV(k+1)+1;
598 %
599 MoveChance=(1-PCNE(k+1))*(max(Windspeed-Windmin,0))/(StormThreshold-Windmin));
600 k=k+1;
601 flag=1*(k<=dist);
602 MoveChance=(1-PCNE(k))*(max(Windspeed-Windmin,0))/(StormThreshold-Windmin)*MvF;
603 if Rand >= MoveChance
604 flag=0;
605 end
606 else
607 flag=0;
608 end
609 end
610 Nhd(4,4)=DirV(1);
611 Nhd(4,3)=DirV(2);
612 Nhd(4,2)=DirV(3);
613 Nhd(4,1)=DirV(4);
614
615 end
616
617 %

618 %WEST BLOCK
619
620
621 elseif WindDir==7 && rand<MoveChance
622
623 %MOVES SW
624 if Rand<((1-P)/2) && (i<size(Hstar,1)) && (j>1)
625 DirV=[Nhd(4,4) , Nhd(5,3) , Nhd(6,2) , Nhd(7,1)];
626 PCNE=[PCNhd(4,4) , PCNhd(5,3) , PCNhd(6,2) , PCNhd(7,1)];
627 flag=1;
628 k=1;
629 while flag==1
630 if atan(((DirV(k+1)-DirV(k))*delta)/L)<(pi/12)
631 DirV(k)=DirV(k)-1;
632 DirV(k+1)=DirV(k+1)+1;
633 %
634 MoveChance=(1-PCNE(k+1))*(max(Windspeed-Windmin,0))/(StormThreshold-Windmin));
635 k=k+1;
636 flag=1*(k<=dist);
637 MoveChance=(1-PCNE(k))*(max(Windspeed-Windmin,0))/(StormThreshold-Windmin)*MvF;
638 if Rand >= MoveChance
639 flag=0;
640 end
641 else
642 flag=0;
643 end
644 end

```

```

645 Nhd(4,4)=DirV(1);
646 Nhd(5,3)=DirV(2);
647 Nhd(6,2)=DirV(3);
648 Nhd(7,1)=DirV(4);
649
650 %MOVES W
651 elseif Rand>=(1-P)/2 && Rand<((1+P)/2) && (j>1)
652 DirV=[Nhd(4,4), Nhd(4,3), Nhd(4,2), Nhd(4,1)];
653 PCNE=[PCNh(4,4), PCNh(4,3), PCNh(4,2), PCNh(4,1)];
654 flag=1;
655 k=1;
656 while flag==1
657 if atan(((DirV(k+1)-DirV(k))*delta)/L)<(pi/12)
658 DirV(k)=DirV(k)-1;
659 DirV(k+1)=DirV(k+1)+1;
660 cellcnt=cellcnt+1;
661 MoveChance=(1-PCNE(k+1))*(max(Windspeed-Windmin,0))/(StormThreshold-Windmin));
662 k=k+1;
663 flag=1*(k<=dist);
664 MoveChance=(1-PCNE(k))*(max(Windspeed-Windmin,0))/(StormThreshold-Windmin)*MvF;
665 if Rand >= MoveChance
666 flag=0;
667 end
668 else
669 flag=0;
670 end
671 end
672 Nhd(4,4)=DirV(1);
673 Nhd(4,3)=DirV(2);
674 Nhd(4,2)=DirV(3);
675 Nhd(4,1)=DirV(4);
676
677 %MOVES NW
678 elseif Rand>=((1+P)/2) && (i>1) && (j>1)
679 DirV=[Nhd(4,4), Nhd(3,3), Nhd(2,2), Nhd(2,1)];
680 PCNE=[PCNh(4,4), PCNh(3,3), PCNh(2,2), PCNh(1,1)];
681 flag=1;
682 k=1;
683 while flag==1
684 if atan(((DirV(k+1)-DirV(k))*delta)/L)<(pi/12)
685 DirV(k)=DirV(k)-1;
686 DirV(k+1)=DirV(k+1)+1;
687 cellcnt=cellcnt+1;
688 MoveChance=(1-PCNE(k+1))*(max(Windspeed-Windmin,0))/(StormThreshold-Windmin));
689 k=k+1;
690 flag=1*(k<=dist);
691 MoveChance=(1-PCNE(k))*(max(Windspeed-Windmin,0))/(StormThreshold-Windmin)*MvF;
692 if Rand >= MoveChance
693 flag=0;
694 end
695 else
696 flag=0;
697 end
698 end
699 Nhd(4,4)=DirV(1);
700 Nhd(3,3)=DirV(2);

```

```

701             Nhd(2,2)=DirV(3);
702             Nhd(1,1)=DirV(4);
703
704         end
705
706     %
707
708     %NORTH-WEST
709
710     elseif WindDir==8 && rand<MoveChance
711
712         %MOVES W
713         if Rand<((1-P)/2) && (j>1)
714             DirV=[Nhd(4,4), Nhd(4,3), Nhd(4,2), Nhd(4,1)];
715             PCNE=[PCNhd(4,4), PCNhd(4,3), PCNhd(4,2), PCNhd(4,1)];
716             flag=1;
717             k=1;
718             while flag==1
719                 if atan(((DirV(k+1)-DirV(k))*delta)/L)<(pi/12)
720                     DirV(k)=DirV(k)-1;
721                     DirV(k+1)=DirV(k+1)+1;
722                 %
723                 MoveChance=(1-PCNE(k+1))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin));
724                 k=k+1;
725                 flag=1*(k<=dist);
726                 MoveChance=(1-PCNE(k))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin))*MvF;
727                 if Rand >= MoveChance
728                     flag=0;
729                 end
730             else
731                 flag=0;
732             end
733         end
734         Nhd(4,4)=DirV(1);
735         Nhd(4,3)=DirV(2);
736         Nhd(4,2)=DirV(3);
737         Nhd(4,1)=DirV(4);
738
739         %MOVES NW
740     elseif Rand>=((1-P)/2) && Rand<=((1+P)/2) && (i>1) && (j>1)
741         DirV=[Nhd(4,4), Nhd(3,3), Nhd(2,2), Nhd(2,1)];
742         PCNE=[PCNhd(4,4), PCNhd(3,3), PCNhd(2,2), PCNhd(1,1)];
743         flag=1;
744         k=1;
745         while flag==1
746             if atan(((DirV(k+1)-DirV(k))*delta)/L)<(pi/12)
747                 DirV(k)=DirV(k)-1;
748                 DirV(k+1)=DirV(k+1)+1;
749             %
750             MoveChance=(1-PCNE(k+1))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin));
751             k=k+1;
752             flag=1*(k<=dist);
753             MoveChance=(1-PCNE(k))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin))*MvF;
754             if Rand >= MoveChance

```

```

755         flag=0;
756     end
757     else
758         flag=0;
759     end
760 end
761 Nhd(4,4)=DirV(1);
762 Nhd(3,3)=DirV(2);
763 Nhd(2,2)=DirV(3);
764 Nhd(1,1)=DirV(4);
765
766 %MOVES N
767 elseif Rand>=((1+P)/2) && (i>1)
768 DirV=[Nhd(4,4), Nhd(3,4), Nhd(2,4), Nhd(1,4)];
769 PCNE=[PCNhd(4,4), PCNhd(3,4), PCNhd(2,4), PCNhd(1,4)];
770 flag=1;
771 k=1;
772 while flag==1
773 if atan(((DirV(k+1)-DirV(k))*delta)/L)<(pi/12)
774     DirV(k)=DirV(k)-1;
775     DirV(k+1)=DirV(k+1)+1;
776     cellcnt=cellcnt+1;
777     MoveChance=(1-PCNE(k+1))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin));
778     k=k+1;
779     flag=1*(k<=dist);
780     MoveChance=(1-PCNE(k))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin))*MvF;
781     if Rand >= MoveChance
782         flag=0;
783     end
784 else
785     flag=0;
786 end
787 end
788 Nhd(4,4)=DirV(1);
789 Nhd(3,4)=DirV(2);
790 Nhd(2,4)=DirV(3);
791 Nhd(1,4)=DirV(4);
792 %
793 flag=1;
794 cnt=0;
795 k=1;
796 while flag==1
797 if atan(((Nhd(4-k,4)-Nhd(4-k+1,4))*delta)/L)<(pi/12)
798     Nhd(4-k+1,4)=Nhd(4-k+1,4)-1;%4-k+1=4-(k-1)
799     Nhd(4-k,4)=Nhd(4-k,4)+1;
800     MoveChance=(1-PCNhd(4-k,4))*((max(Windspeed-Windmin,0))/(StormThreshold-Windmin));%
(calculating, but not using yet)
801 k=k+1;
802 cnt=cnt+1;
803 flag=1*(k<=dist);%*(Nhd(4,4)>=0)
804 else
805     flag=0;
806 end
807 end
808 end
809 end

```

```

810           end
811           Hp(i-3:i+3,j-3:j+3,1)=Nhd;
812       end
813   else
814   end
815 end
816 end
817
818 Hstar(:,:,1)=Hp(4:n1+3,4:n2+3);
819
820 end %end of AT function
821
822 %COMMENT: Old way of polling may have made it easier to change number of
823 %steps in each direction that a cell can possible move:
824
825 %it used this neighborhood function to declare a local region of 3 cells in
826 %each direction. If we used a variablelike D=#cells wished to move
827
828 %then ...
829
830 %
831 % function Nl>NewNhd(R,C,H)
832 % if R<=(size(H,1)-1)
833 %     R=floor(R);
834 %     Rp=R+1;
835 % else
836 %     Rp=floor(R);
837 % end
838 % if R>=2
839 %     R=floor(R);
840 %     Rm=R-1;
841 % else
842 %     Rm=floor(R);
843 % end
844 % if C<=(size(H,2)-1)
845 %     C=floor(C);
846 %     Cp=C+1;
847 % else
848 %     Cp=floor(C);
849 % end
850 % if C>=2
851 %     C=floor(C);
852 %     Cm=C-1;
853 % else
854 %     Cm=floor(C);
855 % end
856 % Nl=zeros(3,3);           %<-----CHANGED THIS TO zeros(D,D) *****
857
858 % Nl=[H(Rm,Cm),H(Rm,C),H(Rm,Cp);H(R,Cm),H(R,C),H(R,Cp);H(Rp,Cm),H(Rp,C),H(Rp,Cp)];
859 %
860 % end
861
862 % *****and used the old method of checking:
863
864 % ***** All of these 4's would need to be replaced with D+1
865

```

```

866 % flag=1;
867 % cnt=0;
868 % k=1;
869 % while flag==1
870 % if atan (((Nhd(4-k,4)-Nhd(4-k+1,4))*delta)/L)<(pi/12)
871 % Nhd(4-k+1,4)=Nhd(4-k+1,4)-1;%4-k+1=4-(k-1)
872 % Nhd(4-k,4)=Nhd(4-k,4)+1;
873 % MoveChance=(1-PCNhd(4-k,4))*(max(Windspeed-Windmin,0))/(StormThreshold-Windmin));%(calculating , but not using yet)
874 % k=k+1;
875 % cnt=cnt+1;
876 % flag=1*(k<=dist);%*(Nhd(4,4)>=0)
877 % else
878 % flag=0;
879 % end
880 % end

```

B.3 Avalanche code

```

1 function [Hstar,flag,CellCt] = AVALANCHEtime03312021(Hstar,delta,L,flag,PC,t)
2 %% This version of avalanche:
3 %   -weights the probability of avalanching to favor the direction of the
4 %       greatest violation of the angle of repose.
5 %   -takes t as input to track if avalanching is required over whole domain
6 %       (once per 5 years)
7 %   -most recent edit code was ATTEMPT2newAVALANCHEtime0928
8 %
9 AoR=pi/6;
10 % AoR=pi/9;
11
12 %%
13 % tic
14
15 Hstarflag=Hstar;
16 CellCt=0;
17 flag=0;
18 FLAG=1;
19 alpha=1;
20 % fprintf('I am running AV! ')
21 Nhd=4; %size of neighborhood check (4 or 8)
22 beta1=zeros(1,Nhd); %angle of repose
23 beta2=zeros(1,Nhd);
24 check1=zeros(1,Nhd);
25 check2=zeros(1,Nhd);
26
27 %once per 5 year we check every cell in domain, both above and below sea level
28
29 if (0==mod(t,26)) || exist('t','var')==0
30 for R=1:size(Hstar,1)
31     for C=1:size(Hstar,2)
32         Erosioncheck=1;
33         FLAG=1;
34         while FLAG==1
35             RAND=rand;
36             %FLAG=1;
37             %if Hstar(R,C)>0
38             if R<=(size(Hstar,1)-1)
39                 R=floor(R);
40                 Rp=R+1;
41             else
42                 Rp=floor(R);
43             end
44             if R>=2
45                 R=floor(R);
46                 Rm=R-1;
47             else
48                 Rm=floor(R);
49             end
50             if C<=(size(Hstar,2)-1)
51                 C=floor(C);
52                 Cp=C+1;
53             else
54                 Cp=floor(C);

```

```

55      end
56      if C>=2
57          C=floor(C);
58          Cm=C-1;
59      else
60          Cm=floor(C);
61      end
62
63      Hx=Hstar(R,C); %current cell value
64      N=[Hstar(Rm,C),Hstar(R,Cp),Hstar(Rp,C),Hstar(R,Cm)]; %neighborhood
65
66      beta1=atan(((Hx-N)*delta)/L);
67      check1=(beta1>=(AoR));
68      %Avdir=find(beta1>=AoR);
69      beta2=alpha*((beta1/(AoR))*(1-PC(R,C)));
70      check2=(RAND<beta2);
71
72
73      if sum(check2)==0
74          while sum(check1)==0 && sum(check2)==0 %if I use a while loop, there's no point to using probability
75              posbeta1=beta1;
76              posbeta1(find(beta1<0))=0;
77              Nprob=posbeta1/sum(posbeta1);
78              AVbeta1=zeros(1,4);
79              AVbeta1(check1)=beta1(check1);
80              AVbeta1(check2)=AVbeta1(check2);
81              Nprob=AVbeta1/sum(AVbeta1);
82              prob=rand;
83              Hcheck=Hx;
84              Hx=Hx-1*check1(1)*check2(1)*(prob<Nprob(1))-1*check1(2)*check2(2)*(prob<Nprob(2))-1*check1(3)*check2(3)*
85              prob<Nprob(3))-1*check1(4)*check2(4)*(prob<Nprob(4));
86      if Hx-Hcheck==0
87          FLAG=0;
88          break
89      end
90      N(1)=N(1)+check1(1)*check2(1)*(prob<Nprob(1));
91      N(2)=N(2)+check1(2)*check2(2)*(prob<Nprob(2));
92      N(3)=N(3)+check1(3)*check2(3)*(prob<Nprob(3));
93      N(4)=N(4)+check1(4)*check2(4)*(prob<Nprob(4));
94      beta1=newbeta1(N,Hx);
95      beta2=newbeta2(N,beta1);
96      check1=newcheck1(N,beta1);
97      check2=newcheck2(N,beta2);
98      %flag=1;
99      if Hx-Hcheck==0
100         CellCt=CellCt+1;
101         flag=1;
102     end
103     if sum(check1)==0
104         Hstar(R,C)=Hx;
105         Hstar(Rm,C)=N(1);
106         Hstar(R,Cp)=N(2);
107         Hstar(Rp,C)=N(3);
108         Hstar(R,Cm)=N(4);
109         %fprintf('Changes have been made')
110         FLAG=0;

```

```

110             if Hx >=0
111                     break
112                 end
113             end
114             if check1*check2'==0
115                     break
116                 end
117             end
118             if sum(check1)==0
119                     FLAG=0;
120                     %no avalanching needed
121                 end
122             elseif sum(check2)==0 && sum(check1)~=0
123                     FLAG=0;
124                     %fprintf('Too many plants!')
125             elseif sum(check1)==0
126                     FLAG=0;      %only other case should be if both sum to 0
127                 end
128
129 %           else%{if Hstar(R,C)<=0}
130 %               Erosioncheck=0;
131 %               FLAG=0;
132 %           end
133             FLAG=0;
134         end
135     end
136
137 %for other instances of avalanche we only check subaerial portions of island
138 else
139 %   ISLANDIndex=Hstar(:,:,1)>0; %all cells with land
140 %   Hstarflag=cumsum(ISLANDIndex,2) == 1 & ISLANDIndex; %this outputs an array same size as H but with a 1 in the first cell>0
141 %   IslandCheck=sum(Hstarflag');    %outputs a row vector with 0^ no col>0, 1^col>0 (ie yes/no land in that row)
142 %   COLindex1 = Hstarflag*(1:size(Hstar,2))';    %the index of the first positive value in a row
143 %   COLindex2 = zeros(size(COLindex1));
144 %   for ii=1:length(COLindex1)
145 %       if ii == 101
146 %           fprintf('yay')
147 %       end
148 %
149 %       if COLindex1(ii)~=0
150 %           RowNow=ISLANDIndex(ii,:);
151 %           Icount=0;
152 %           for jj = COLindex1(ii):1:size(RowNow)
153 %               if RowNow(jj)==1 && RowNow(jj+1)==0
154 %                   Icount=Icount+1;
155 %                   COLindex2(ii,Icount)=jj;
156 %               end
157 %           end
158 %       end
159 %   end
160 IslandColumnArray1=zeros([size(Hstar,1) 1]);
161
162 for i=1:size(Hstar,1)
163     ElevCheck1=Hstar(i,:,1)>=0; %first cell above water
164     Icount=0;%%
165     for j=2:size(Hstar,2)

```

```

166     if ElevCheck1(j)==1 && ElevCheck1(j-1)==0      %if delta*Hstar(i,j)>-.5 && Hstar(i,j-1)<=-.5 %&& ColumnArraySwamp1(i,Icount)
167         ==0
168         Icount=Icount+1;%  

169         IslandColumnArray1(i,Icount)=j;  

170
171         %  

172         %break;  

173
174         end  

175
176         %  

177         end  

178
179         INum=size(IslandColumnArray1,2);
180         IslandColumnArray2=zeros(size(IslandColumnArray1(:, :)));
181         for i=1:size(Hstar,1)
182             ElevCheck2=Hstar(i,:,1)<=0;
183             if sum(IslandColumnArray1(i,1:INum)^-0)>0
184                 for Icount=1:INum
185                     if IslandColumnArray1(i,Icount)^-0
186                         for j=IslandColumnArray1(i,Icount):size(Hstar,2)
187                             if ElevCheck2(j)==1 && IslandColumnArray2(i,Icount)==0
188                                 IslandColumnArray2(i,Icount)=j;
189                                 break;
190                             elseif sum(ElevCheck2)==0
191                                 ColumnArraySwamp1(i,Icount)=0;
192                             end
193                         end
194                     end
195                 end
196             end
197         end
198         end
199         end
200         for R=1:size(Hstar,1)
201             for Icount=1:INum
202                 if IslandColumnArray2(R,Icount)^-0
203                     for C=IslandColumnArray1(R,Icount):IslandColumnArray2(R,Icount)
204                         Erosioncheck=1;
205                         FLAG=1;
206                         while FLAG==1
207                             RAND=rand;
208                             %FLAG=1;
209                             if Hstar(R,C)>0
210                                 if R<=(size(Hstar,1)-1)
211                                     R=floor(R);
212                                     Rp=R+1;
213                                 else
214                                     Rp=floor(R);
215                                 end
216                                 if R>=2
217                                     R=floor(R);
218                                     Rm=R-1;
219                                 else
220

```

```

213          Rm=floor(R);
214
215      end
216      if C<=(size(Hstar,2)-1)
217          C=floor(C);
218          Cp=C+1;
219      else
220          Cp=floor(C);
221      end
222      if C>=2
223          C=floor(C);
224          Cm=C-1;
225      else
226          Cm=floor(C);
227      end
228
229      Hx=Hstar(R,C); %current cell value
230      N=[Hstar(Rm,C),Hstar(R,Cp),Hstar(Rp,C),Hstar(R,Cm)]; %neighborhood
231
232      beta1=atan(((Hx-N)*delta)/L);
233      check1=(beta1>=(AoR));
234      %Avdir=find(beta1>=AoR);
235      beta2=alpha*((beta1/(AoR))*(1-PC(R,C)));
236      check2=(RAND<beta2);
237
238      %
239      if sum(check1)^=0
240          %
241          if sum(check2)^=0
242              %
243              if R==241
244                  %
245                  if C==492
246                      %
247                      fprintf('STOP!');
248
249                  if sum(check2)^=0
250                      if check1*check2'^=0
251                          while sum(check1)^=0 && sum(check2)^=0 %if I use a while loop, there's no point to
252                              using probability
253                              %posbeta1=beta1;
254                              %posbeta1(find(beta1<0))=0;
255                              %Nprob=posbeta1/sum(posbeta1);
256                              AVbeta1=zeros(1,4);
257                              AVbeta1(check1)=beta1(check1);
258                              AVbeta1(check2)=AVbeta1(check2);
259                              Nprob=AVbeta1/sum(AVbeta1);
260                              prob=rand;
261                              Hcheck=Hx;
262
263                              Hx=Hx-1*check1(1)*check2(1)*(prob<Nprob(1))-1*check1(2)*check2(2)*(prob<Nprob(2))
264
265                              -1*check1(3)*check2(3)*(prob<Nprob(3))-1*check1(4)*check2(4)*(prob<Nprob(4))
;
```

```

266 N(2)=N(2)+check1(2)*check2(2)*(prob<=Nprob(2));
267 N(3)=N(3)+check1(3)*check2(3)*(prob<=Nprob(3));
268 N(4)=N(4)+check1(4)*check2(4)*(prob<=Nprob(4));
269 beta1=newbeta1(N,Hx);
270 beta2=newbeta2(N, beta1);
271 check1=newcheck1(N, beta1);
272 check2=newcheck2(N, beta2);
273 %flag =1;
274 if Hx-Hcheck~=0
275 CellCt=CellCt+1;
276 flag=1;
277 end
278 if sum(check1)==0
279     Hstar(R,C)=Hx;
280     Hstar(Rm,C)=N(1);
281     Hstar(R,Cp)=N(2);
282     Hstar(Rp,C)=N(3);
283     Hstar(R,Cm)=N(4);
284     %fprintf('Changes have been made')
285     FLAG=0;
286     if Hx >=0
287         break
288     end
289 end
290 if check1*check2'==0
291     break
292 end
293 end
294 end
295 if sum(check1)==0
296     FLAG=0;
297     %no avalanching needed
298 end
299 elseif sum(check2)==0 && sum(check1)~=0
300     FLAG=0;
301     %fprintf('Too many plants!')
302 elseif sum(check1)==0
303     FLAG=0;      %only other case should be if both sum to 0
304 end
305
306 else%{ if Hstar(R,C)<=0}
307     Erosioncheck=0;
308     FLAG=0;
309 end
310 FLAG=0;
311 end
312 end
313 end
314 end
315
316 end
317 end
318 % end
319
320 %this portion is for elevation maps with multiple full sized islands within the domain
321 %we rarely need this, but it's here just in case

```

```

322
323 % for R=1:size(Hstar,1)
324 %     %ISLANDindex=(Hstar(R,:,1)>0);
325 %     if sum(ISLANDindex)^=0      %skip whole rows of water
326 %         for C=1:size(Hstar,2)
327 %             Erosioncheck=1;
328 %             FLAG=1;
329 %             while FLAG==1
330 %                 RAND=rand;
331 %                 %FLAG=1;
332 %                 if Hstar(R,C)>0
333 %                     if R<=(size(Hstar,1)-1)
334 %                         R=floor(R);
335 %                         Rp=R+1;
336 %                     else
337 %                         Rp=floor(R);
338 %                     end
339 %                     if R>=2
340 %                         R=floor(R);
341 %                         Rm=R-1;
342 %                     else
343 %                         Rm=floor(R);
344 %                     end
345 %                     if C<=(size(Hstar,2)-1)
346 %                         C=floor(C);
347 %                         Cp=C+1;
348 %                     else
349 %                         Cp=floor(C);
350 %                     end
351 %                     if C>=2
352 %                         C=floor(C);
353 %                         Gm=C-1;
354 %                     else
355 %                         Gm=floor(C);
356 %                     end
357 %

358 %             Hx=Hstar(R,C);           %current cell value
359 %             N=[Hstar(Rm,C),Hstar(R,Cp),Hstar(Rp,C),Hstar(R,Gm)]; %neighborhood
360 %

361 %             beta1=atan(((Hx-N)*delta)/L);
362 %             check1=(beta1>=(AoR));
363 %             %Avdir=find(beta1>=AoR);
364 %             beta2=alpha*((beta1/(AoR))*(1-PC(R,C)));
365 %             check2=(RAND<beta2);

366 %

367 %

368 %             if sum(check1)^=0
369 %                 if sum(check2)^=0
370 %                     end
371 %                 end
372 %             if R==24
373 %                 fprintf('STOP! ')
374 %             end
375 %

376 %             if sum(check2)^=0
377 %                 if check1*check2'^=0

```

```

378 %           while sum(check1)~=0 && sum(check2)~=0 %if I use a while loop, there's no point to using
379 %           probability
380 %           %posbeta1=beta1;
381 %           %posbeta1(find(beta1<0))=0;
382 %           %Nprob=posbeta1/sum(posbeta1);
383 %           AVbeta1=zeros(1,4);
384 %           AVbeta1(check1)=beta1(check1);
385 %           AVbeta1(check2)=AVbeta1(check2);
386 %           Nprob=AVbeta1/sum(AVbeta1);
387 %           prob=rand;
388 %           Hcheck=Hx;
389 %           Hx=Hx-1*check1(1)*check2(1)*(prob<Nprob(1))-1*check1(2)*check2(2)*(prob<Nprob(2))-1*check1(3)*
390 %           check2(3)*(prob<Nprob(3))-1*check1(4)*check2(4)*(prob<Nprob(4));
391 %           %
392 %           if Hx-Hcheck==0
393 %           %
394 %           FLAG=0;
395 %           %
396 %           break
397 %           %
398 %           end
399 %           %
400 %           N(1)=N(1)+check1(1)*check2(1)*(prob<Nprob(1));
401 %           N(2)=N(2)+check1(2)*check2(2)*(prob<Nprob(2));
402 %           N(3)=N(3)+check1(3)*check2(3)*(prob<Nprob(3));
403 %           N(4)=N(4)+check1(4)*check2(4)*(prob<Nprob(4));
404 %           %
405 %           beta1=newbeta1(N,Hx);
406 %           %
407 %           beta2=newbeta2(N,beta1);
408 %           %
409 %           check1=newcheck1(N,beta1);
410 %           %
411 %           check2=newcheck2(N,beta2);
412 %           %
413 %           %flag=1;
414 %           %
415 %           if Hx-Hcheck~=0
416 %           %
417 %           flag=1;
418 %           %
419 %           end
420 %           %
421 %           if sum(check1)==0
422 %           %
423 %           Hstar(R,C)=Hx;
424 %           %
425 %           Hstar(Rm,C)=N(1);
426 %           %
427 %           Hstar(R,Cp)=N(2);
428 %           %
429 %           Hstar(Rp,C)=N(3);
430 %           %
431 %           Hstar(R,Cm)=N(4);
432 %           %
433 %           %fprintf('Changes have been made')
434 %           %
435 %           FLAG=0;
436 %           %
437 %           if Hx >=0
438 %           %
439 %           break
440 %           %
441 %           end
442 %           %
443 %           if check1*check2'==0
444 %           %
445 %           break
446 %           %
447 %           end
448 %           %
449 %           end
450 %           %
451 %           end
452 %           %
453 %           if sum(check1)==0
454 %           %
455 %           FLAG=0;
456 %           %
457 %           %no avalanching needed
458 %           %
459 %           end
460 %           %
461 %           elseif sum(check2)==0 && sum(check1)~=0
462 %           %
463 %           FLAG=0;
464 %           %
465 %           %fprintf('Too many plants!')
466 %           %
467 %           elseif sum(check1)==0
468 %           %
469 %           FLAG=0;    %only other case should be if both sum to 0
470 %           %
471 %           end

```

```

432 %
433 %           else%{if Hstar(R,C)<=0}
434 %               Erosioncheck=0;
435 %               FLAG=0;
436 %           end
437 %           FLAG=0;
438 %       end
439 %   end
440 % end
441 %
442 % end
443 % end
444
445
446 %Local functions for finding angle of repose and probability WRT plant cover
447 function B1=newbeta1(N,Hx)
448 %B1=zeros(1,length(N));
449 B1=atan(((Hx-N)*delta)/L);
450
451
452 %     for k=1:length(N)
453 %         B1(k)=atan(((Hx-N(k))*delta)/L);
454 %     end
455 end
456
457 function B2=newbeta2(N,beta1)
458 %B2=zeros(1:length(N));
459 B2=alpha*((beta1/(AoR)*(1-PC(R,C)));
460
461 %     for k=1:length(N)
462 %         B2(k)=alpha*((beta1(k)/(AoR)*(1-PC(R,C)));
463 %     end
464 end
465
466 function C1=newcheck1(N,beta1)
467 %C1=zeros(1,length(N));
468 C1=(beta1>=(AoR));
469 %     for k=1:length(N)
470 %         C1(k)=(beta1(k)>=(AoR));
471 %     end
472 end
473
474 function C2=newcheck2(N,beta2)
475 %C2=zeros(1,length(N));
476 C2=(RAND<beta2);
477 %     for k=1:length(N)
478 %         C2(k)=(RAND<beta2(k));
479 %     end
480 end
481
482 %FLAGCHECK=Hstarflag-Hstar;
483 %if sum(sum(Hstarflag-Hstar))~=0
484 %    %flag=1;
485 %end
486
487

```

488 % toc
489 end

B.4 Plant Propagation code

```

1 function [P1,P2,P3,P4,P3d]=PlantPropagation03312021(Hstar,t,P1,P2,P3,P4,W,S,delta,P3d,MaxSwampWidth,PlantRangeArray,alpha,DBE,
2 gdrange1,gdrange2,PctMax,MasterMax,MWSL,MESL,ESL)
3 % function [P1,P2,P3,P4,P3d]=PlantPropagation03312021(Hstar,P1,P2,P3,P4,W,S,delta,P1Burial,P2Burial,P3Burial,P4Burial,P3d,
4 MaxSwampWidth,t)
5
6
7 P1B4=P1(:,:,1);
8 P2B4=P2(:,:,1);
9 P3B4=P3(:,:,1);
10 P4B4=P4(:,:,1);
11
12 % first loop does all propagating and death of all populations,
13 % second loop is death by competition for cells > MasterMAX
14
15
16 % To run this file you will need to specify:
17 % H - elevation matrix that is continually used in main code
18 % P1 - the plant matrix for Ammophila (GRASS)
19 % P2 - the plant matrix for Spartina (GRASS)
20 % P3 - the plant matrix for Morella (SHRUB)
21 % W - the elevation matrix for the water table
22 % S - the matrix which determines available salinity at each cell
23 % delta - the thickness of each slab
24 %
25 % The routine will return the matrix for each of the plant species after
26 % propagating.
27
28
29 % fprintf('I am running PP! ')
30 %recently moved to main code:
31 % PlantRangeArray=[1 5;0.75 3;1.5 2.5;-0.5 1]; %all of the elevation ranges for p1-p4
32 % alpha=.01; %propagation rate for each populated cell
33 % DBE=.3; %death by elevation rate for each populated cell outside of plant's elevation range
34 % gdrange1=[-.02:.01:.08]; %range of percent values for growth/death for plant populations at (0, 50)% cover
35 % gdrange2=[-.02:.01:.08];%[-.04:.01:.04]; %range of percent values for growth/death for plant pops greater than 50% cover
36 % P1PctMax=.6; %largest percentage we will allow any plant population on a given cell to attain
37 % P2PctMax=.6;
38 % P3PctMax=.8;
39 % P4PctMax=.8;
40 % PctMax=[P1PctMax P2PctMax P3PctMax P4PctMax];
41 % MasterMax=0.8;% The most any cell can permit - 80% plant coverage
42
43
44 SwampWidth=MaxSwampWidth; % number of cells wide that the swamp should be - should find a better way of establishing, 10 'looks
45 right' for now
46 WesternCells=zeros(1,SwampWidth);
47 dH=delta*Hstar(:,:,1); %to make sure everything works correctly in this subroutine we work in meters and not slabs -
48 %since plant data is in meters
49

```

```

50
51
52 %%%
53
54 %%%
55 %%DEATH BY WATER TABLE STUFF%%
56 %%%
57 %not using -we have(?) data , but I've never seen us use water table concept
58
59
60 % HWcheck=H(:, :, 1)-W(:, :, );
61 % HWcheck1=(HWcheck>0);
62 % HWcheck2a(:, :, )=(delta *HWcheck>=-0.5);
63 % HWcheck2b=(delta *HWcheck<=1);
64
65 % for i=1:size(H,1)
66 %     for j=1:size(H,2)
67 %         if H(i, j, 2)=-1
68 %             if HWcheck2a(i, j)==1
69 %                 if HWcheck2b(i, j) ==1
70 %                     if H(i, j, 2)==2
71 %                         if P4(i, j, 1)==-999
72 %                             P4(i, j, 1)=0;
73 %                         end
74 %                     end
75 %                 end
76 %             end
77 %
78 %         if HWcheck1(i, j)==1
79 %             if P1(i, j, 1)==-999
80 %                 P1(i, j, 1)=0;
81 %             end
82 %
83 %         if P2(i, j, 1)==-999
84 %             P2(i, j, 1)=0;
85 %         end
86 %
87 %         if P3(i, j, 1)==-999
88 %             P3(i, j, 1)=0;
89 %         end
90 %
91 %     end
92 %     if HWcheck1(i, j)==0
93 %         P1(i, j, 1)=-999;
94 %         P1(i, j, 2)=0;
95 %         P2(i, j, 1)=-999;
96 %         P2(i, j, 2)=0;
97 %         P3(i, j, 1)=-999;
98 %         P3(i, j, 2)=0;
99 %
100 %     end
101 %
102 %%%
103
104 %%%

```

```

106
107 %%GROWTH/DEATH/PROP
108 %%GROWTH/DEATH/PROP
109 %%splitting P_i into arrays for P_i(:,1) and P_i(:,2)
110 PA=zeros(size(Hstar,1),size(Hstar,2),4); %Plant (A)rray for tracking plant pct cover in growth/death/prop loop
111 PA(:,:,1)=P1(:,:,1);
112 PA(:,:,2)=P2(:,:,1);
113 PA(:,:,3)=P3(:,:,1);
114 PA(:,:,4)=P4(:,:,1);
115 PHA=zeros(size(Hstar,1),size(Hstar,2),4); %Plant (H)eight (A)rray for tracking plant init. elev. in growth/death/prop loop
116 PHA(:,:,1)=P1(:,:,2);
117 PHA(:,:,2)=P2(:,:,2);
118 PHA(:,:,3)=P3(:,:,2);
119 PHA(:,:,4)=P4(:,:,2);
120
121 % plants do not propagate during initialization , skip straight to death by competition
122 if isnan(t)==0
123 % Beginning of the year, plants use full gdrange (death and growth)
124 if mod(t,26)==0
125 for i=1:size(PA,3)
126     PAB4=PA(:,:,i);
127     Px=PA(:,:,i);
128     Ph=PHA(:,:,i);
129     for R=1:size(Hstar,1)
130         for C=1:size(Hstar,2)
131             if dH(R,C)<-0.5
132                 Px(R,C)=-999;
133                 Ph(R,C)=0;
134             elseif ESL(R)~=-0 && C>ESL(R)
135                 Px(R,C)=-999;
136                 Ph(R,C)=0;
137             else
138                 if i==3
139                     P3d(R,C,2)=P3d(R,C,2)-1*(P3d(R,C,2)>0);      %if i=3 (working on P3) we remove a counter from the p3d
140                     array if there is a value stored there
141                     if P3d(R,C,2)==0
142                         P3(R,C,1)=0;
143                     end
144                     if dH(R,C)<0 && P3d(R,C,1)>0           %if elev. goes below zero we get rid of dead morella
145                         P3d(R,C,1)=0;
146                         P3d(R,C,2)=0;
147                     end
148                 end
149                 if i~=4
150                     if (dH(R,C)<PlantRangeArray(i,1)) || (dH(R,C)>PlantRangeArray(i,2)) %if we are outside of the
151                         elevation range for this plant...
152                         if Px(R,C)~=-999
153                             if i==3 && Px(R,C)>0 && dH(R,C)>0 && t~=0
154                                 have to create a dead morella value
155                                 Px4=Px(R,C);
156                                 Px(R,C)=Px(R,C) - DBE*Px(R,C);%-999;
157                                 is not a sudden drop to 0
158                                 if Px4>0.01 && Px(R,C)<0.01
159                                     %if newly below 1% we create a p3d cell and kill
160                                     off remaining p3
161                                     Px(R,C)=-999;

```

```

157          Ph(R,C)=0;
158          P3d(R,C,1) =.05;
159          P3d(R,C,2) =10;
160      end
161      elseif Px(R,C) >0 && dH(R,C)>=0
162          outside of elevation we remove a percentage
163          Px(R,C)=Px(R,C)-DBE*Px(R,C);%-999; %changed on 9/21 see above
164          if Px(R,C)<0.01
165              %if that percentage drops below .1% we kill it
166              Px(R,C) = 0;
167              %since it is outside of it's elev. range we
168              negate the cell for future popln.
169          Ph(R,C)=0;
170      end
171      else
172          %should only have cells now underwater which we will
173          negate
174
175          Ph(R,C)=0;
176      end
177      end
178  end
179  if (dH(R,C)>=PlantRangeArray(i,1)) && (dH(R,C)<=PlantRangeArray(i,2)) %if we are inside of the plant
180      elevation range
181      %
182      %resetting negated cells which were previously submerged
183      if Px(R,C)==-999
184          Px(R,C)=0;
185          Ph(R,C)=Hstar(R,C,1);
186      end
187      %
188      %find the neighborhood, calc new popln for
189      %growth/propgtn :
190      %some % * (how many neighbors are
191      %populated)
192      Nhd>NewNhd(R,C,PAB4);
193      if Px(R,C) <.5
194          Px4=Px(R,C);
195          kk=randi([1,length(gdrange1)]);
196          beta=gdrange1(kk);
197          Px(R,C)=min(Px(R,C)+sum(beta*Nhd)+beta*(beta>0)*(i==3),PctMax(i));
198          %grow by sum of
199          %neighbors* beta, if it's morella grow a little more?
200          if i==3 && Px4>=0.05 && Px(R,C)<=.05
201              add's chance of spread by birds anywhere inside of p3 range (same below)
202              Px(R,C)=0;
203              Ph(R,C)=0;
204              P3d(R,C,1) =.05;
205              P3d(R,C,2) =5;
206          end
207          else
208              kk=randi([1,length(gdrange2)]);
209              beta=gdrange2(kk);
210              Px(R,C)=min(Px(R,C)+sum(beta*Nhd)+beta*(beta>0)*(i==3),PctMax(i));
211              %grow by sum of
212              %neighbors* beta, if it's morella grow a little more?
213          end
214          %
215          %record elevations for all cells inside the range,
216          %elevation=zero if no popln exists on cell currently
217          if Px(R,C)==0
218              Ph(R,C)=0;
219          elseif Px(R,C)>0
220              Ph(R,C)=Hstar(R,C,1);

```

```

206         elseif Px(R,C)<0
207             Px(R,C)=0;
208             Ph(R,C)=0;
209             end
210         end
211     elseif i==4
212         if (dH(R,C)<PlantRangeArray(i,1)) %if less than min height (-0.5)
213             if Px(R,C) ~= -999      %negate (should already be done from first loop after R,C declared
214
215                 Ph(R,C)=0;
216             end
217         elseif (dH(R,C)>PlantRangeArray(i,2)) %elseif greater than max height, make 0 (no death by elev. just
218             kill)
219             Px(R,C)=0;
220             Ph(R,C)=0;
221         end
222         if (dH(R,C)>=PlantRangeArray(i,1)) && (dH(R,C)<=PlantRangeArray(i,2))
223             if ESL(R) ~=0
224                 if MWSL(R)<=C && MESL(R)>=C
225                     Nhd>NewNhd(R,C,Px);
226                     if Px(R,C) <.5
227                         kk=randi([1,length(gdrange1)]);
228                         beta=gdrange1(kk);
229                         Px(R,C)=min(Px(R,C)+sum(beta*Nhd)+beta*(beta>0)*(i==3),PctMax(i));    %this also kills
230                         by a
231
232                     else
233                         kk=randi([1,length(gdrange2)]);
234                         beta=gdrange2(kk);
235                         Px(R,C)=min(Px(R,C)+sum(beta*Nhd)+beta*(beta>0)*(i==3),PctMax(i));
236                     end
237                 end
238             end
239             Nhd>NewNhd(R,C,Px);
240             if Px(R,C) <.5
241                 kk=randi([1,length(gdrange1)]);
242                 beta=gdrange1(kk);
243                 Px(R,C)=min(Px(R,C)+sum(beta*Nhd)+beta*(beta>0)*(i==3),PctMax(i));    %this also kills by a
244             else
245                 kk=randi([1,length(gdrange2)]);
246                 beta=gdrange2(kk);
247                 Px(R,C)=min(Px(R,C)+sum(beta*Nhd)+beta*(beta>0)*(i==3),PctMax(i));
248             end
249             %           record elevations for all cells inside the range,
250             %           elevation=zero if no popln exists on cell currently
251             if Px(R,C)==0
252                 Ph(R,C)=0;
253             elseif Px(R,C)>0
254                 Ph(R,C)=Hstar(R,C,1);
255             elseif Px(R,C)<0 && Px(R,C) ~= -999
256                 Px(R,C)=0;
257                 Ph(R,C)=0;
258             end
259         end

```

```

260           end
261       end
262   end
263 end
264 PA(:,:,i)=Px;
265 PHA(:,:,i)=Ph;
266 end
267
268
269 % Half year, plants only grow (no death, simulate spring time growth)
270 else
271     Spr_gdrange1=gdrange1(gdrange1>0);
272     Spr_gdrange2=gdrange2(gdrange2>0);
273     for i=1:size(PA,3)
274         PAB4=PA(:,:,i);
275         Px=PA(:,:,i);
276         Ph=PHA(:,:,i);
277         for R=1:size(Hstar,1)
278             for C=1:size(Hstar,2)
279                 if dH(R,C)<-.5
280                     Px(R,C)=-999;
281                     Ph(R,C)=0;
282                 elseif ESL(R)>0 && C>ESL(R)
283                     Px(R,C)=-999;
284                     Ph(R,C)=0;
285                 else
286                     if i==3
287                         if dH(R,C)<0 && P3d(R,C,1)>0 %if elev. goes below zero we get rid of dead morella
288                             P3d(R,C,1)=0;
289                             P3d(R,C,2)=0;
290                         end
291                     end
292                     if i~=4 %work on all Pi arrays except p4 first
293                         if (dH(R,C)<PlantRangeArray(i,1)) || (dH(R,C)>PlantRangeArray(i,2)) %if we are outside of the
294                             elevation range for this plant...
295                             if Px(R,C) ~= -999 %but we aren't underwater...
296                                 if i==3 && Px(R,C)>0 && dH(R,C)>0 && t~=0 %if it's p3 outside of elevation range we
297                                     have to create a dead morella value
298                                     Px4=Px(R,C); %store p3 %cover before death by elev.
299                                     Px(R,C)=Px(R,C) - DBE*Px(R,C);%-999; %changed on 9/21 so that death by elevation
300                                     is not a sudden drop to 0
301                                     if Px4>0.01 && Px(R,C)<0.01 %if newly below 1% we create a p3d cell and kill
302                                         off remaining p3
303                                         Px(R,C)=0;
304                                         Ph(R,C)=0;
305                                         P3d(R,C,1)=.05;
306                                         P3d(R,C,2)=5;
307                                     end
308                                 elseif Px(R,C) >0 && dH(R,C)>=0 %if it's p1 or p2
309                                     outside of elevation we remove a percentage
310                                     Px(R,C)=Px(R,C)-DBE*Px(R,C);%-999; %changed on 9/21 see above
311                                     if Px(R,C)<0.001 %if that percentage drops below .1% we kill it
312                                         Px(R,C) = 0; %since it is outside of it's elev. range we drop
313                                         to 0, will negate after elev drops below -0.5.
314                                         Ph(R,C)=0;
315                                     end

```

```

310           else                                %should only have cells now underwater which we will
311               negate
312                   Px(R,C)=0;
313                   Ph(R,C)=0;
314           end
315       end
316   if i~=3 && (dH(R,C)>=PlantRangeArray(i,1)) && (dH(R,C)<=PlantRangeArray(i,2))    %if we are inside of
317       the plant elevation range, don't do morella this time
318       %
319           resetting negated cells which were previously submerged
320               if Px(R,C)==-999
321                   Px(R,C)=0;
322                   Ph(R,C)=Hstar(R,C,1);
323           end
324       %
325           find the neighborhood, calc new popln for
326           %
327           growth/propgtn :
328           %
329           some % * (how many neighbors are
330           %
331           populated)
332       Nhd>NewNhd(R,C,PAB4);
333       if Px(R,C) <.5
334           PxB4=Px(R,C);
335           kk=randi([1,length(Spr.gdrange1)]);
336           beta=Spr.gdrange1(kk);
337           Px(R,C)=min(Px(R,C)+sum(beta*Nhd)+beta*(beta>0)*(i==3),PctMax(i));
338           %grow by sum of
339           neighbors* beta, if it's morella grow a little more?
340           if i==3 && PxB4>=0.05 && Px(R,C)<=.05
341               add's chance of spread by birds anywhere inside of p3 range (same below)
342               Px(R,C)=0;
343               Ph(R,C)=0;
344               P3d(R,C,1)=.05;
345               P3d(R,C,2)=10;
346           end
347       else
348           kk=randi([1,length(Spr.gdrange2)]);
349           beta=Spr.gdrange2(kk);
350           Px(R,C)=min(Px(R,C)+sum(beta*Nhd)+beta*(beta>0)*(i==3),PctMax(i));
351           %grow by sum of
352           neighbors* beta, if it's morella grow a little more?
353       end
354       %
355       record elevations for all cells inside the range,
356       %
357       elevation=zero if no popln exists on cell currently
358   if Px(R,C)==0
359       Ph(R,C)=0;
360   elseif Px(R,C)>0
361       Ph(R,C)=Hstar(R,C,1);
362   elseif Px(R,C)<0
363       Px(R,C)=0;
364       Ph(R,C)=0;
365   end
366   end
367   elseif i==4
368       if (dH(R,C)<PlantRangeArray(i,1)) %if less than min height (-0.5)
369           if Px(R,C)~-999      %negate (should already be done from first loop after R,C declared
370               Px(R,C)=-999;
371               Ph(R,C)=0;
372           end
373       elseif (dH(R,C)>PlantRangeArray(i,2)) %elseif greater than max height, make 0 (no death by elev. just

```

```

            kill)
361      Px(R,C)=0;
362      Ph(R,C)=0;
363      end
364      if (dH(R,C)>=PlantRangeArray(i,1)) && (dH(R,C)<=PlantRangeArray(i,2))
365          if ESL(R)>=0
366              if MWSL(R)<C && MESL(R)>=C
367                  Nhd>NewNhd(R,C,Px);
368                  if Px(R,C) <.5
369                      kk=randi([1,length(gdrange1)]);
370                      beta=gdrange1(kk);
371                      Px(R,C)=min(Px(R,C)+sum(beta*Nhd)+beta*(beta>0)*(i==3),PctMax(i)); %this also kills
372                          by a
373
374          else
375              kk=randi([1,length(gdrange2)]);
376              beta=gdrange2(kk);
377              Px(R,C)=min(Px(R,C)+sum(beta*Nhd)+beta*(beta>0)*(i==3),PctMax(i));
378          end
379          else
380              Px(R,C)=0;
381          end
382          %
383          % record elevations for all cells inside the range,
384          % elevation=zero if no popln exists on cell currently
385          if Px(R,C)==0
386              Ph(R,C)=0;
387              elseif Px(R,C)>0
388                  Ph(R,C)=Hstar(R,C,1);
389              elseif Px(R,C)<0 && Px(R,C)=-999
390                  Px(R,C)=0;
391                  Ph(R,C)=0;
392              end
393          end
394      end
395      end
396      end
397      PA(:,:,i)=Px;
398      PHA(:,:,i)=Ph;
399  end
400 end
401 end
402
403
404 %now updating changes in original plant matrices
405 P1(:,:,1)=PA(:,:,1);
406 P2(:,:,1)=PA(:,:,2);
407 P3(:,:,1)=PA(:,:,3);
408 P4(:,:,1)=PA(:,:,4);
409
410 P1(:,:,2)=PHA(:,:,1);
411 P2(:,:,2)=PHA(:,:,2);
412 P3(:,:,2)=PHA(:,:,3);
413 P4(:,:,2)=PHA(:,:,4);
414
```

```

415 %new temp plant matrices removing the -999 values to get an accurate total
416 %of all poplns on cells
417 Pt1=max(P1(:,:,1),0);
418 Pt2=max(P2(:,:,1),0);
419 Pt3=max(P3(:,:,1),0);
420 Pt4=max(P4(:,:,1),0);
421
422 Ptot=Pt1+Pt2+Pt3+Pt4;
423 %Death by Comp
424 fprintf('\n')
425 fprintf('The plants are killing each other!!!')
426 for i =1:size(Hstar,1)
427   for j =1:size(Hstar,2)
428     if Ptot(i,j,1)>MasterMax
429       Px1=Pt1(i,j,1);
430       Px2=Pt2(i,j,1);
431       Px3=Pt3(i,j,1);
432       Px4=Pt4(i,j,1);
433       if Px3==MasterMax
434         P1(i,j,1)=0;
435         P2(i,j,1)=0;
436         P4(i,j,1)=0;
437     elseif (Px3 < MasterMax) && (Px3>0)
438       k=(MasterMax-Px3)/(Px1+Px2+Px4);
439       P1(i,j,1)=Px1*k;
440       P2(i,j,1)=Px2*k;
441       P4(i,j,1)=Px4*k;
442     elseif Px3==0
443       %if Px1>=(k/4) && Px2>=(k/4) && Px3>=(k/4) && Px4>=(k/4)
444       k=(Px1+Px2+Px4)-MasterMax;
445       if Px1>=(k/3) && Px2>=(k/3) && Px4>=(k/3)
446         P1(i,j,1)=Px1-(k/3);
447         P2(i,j,1)=Px2-(k/3);
448         P4(i,j,1)=Px4-(k/3);
449         %Only two are bigger than k/3
450         %%1 2%%
451     elseif Px1>=(k/3) && Px2>=(k/3) && Px4<(k/3)
452       P1(i,j,1)=Px1-(((k/3)+((k/3)-Px4)/2));
453       P2(i,j,1)=Px2-(((k/3)+((k/3)-Px4)/2));
454       P4(i,j,1)=0;
455       %%1 4%%
456     elseif Px1>=(k/3) && Px2<(k/3) && Px4>=(k/3)
457       P1(i,j,1)=Px1-(((k/3)+((k/3)-Px4)/2));
458       P2(i,j,1)=0;
459       P4(i,j,1)=Px4-(((k/3)+((k/3)-Px2)/2));
460       %%2 4%%
461     elseif Px1<(k/3) && Px2>=(k/3) && Px4>=(k/3)
462       P1(i,j,1)=0;
463       P2(i,j,1)=Px2-(((k/3)+((k/3)-Px1)/2));
464       P4(i,j,1)=Px4-(((k/3)+((k/3)-Px1)/2));
465       %Only one is bigger than k/3
466       %%3%%
467     elseif Px1>=(k/3) && Px2<(k/3) && Px4<(k/3)
468       P1(i,j,1)=Px1-((k/3)+((k/3)-Px2)+((k/3)-Px4));
469       P2(i,j,1)=0;
470       P4(i,j,1)=0;

```

```

471          %%2%%
472      elseif Px1<(k/3) && Px2>=(k/3) && Px4<(k/3)
473          P1(i,j,1)=0;
474          P2(i,j,1)=Px2-((k/3)+((k/3)-Px1)+((k/3)-Px4));
475          P4(i,j,1)=0;
476          %%4%%
477      elseif Px1<(k/3) && Px2<(k/3) && Px4>=(k/3)
478          P1(i,j,1)=0;
479          P2(i,j,1)=0;
480          P4(i,j,1)=Px4-((k/3)+((k/3)-Px1)+((k/3)-Px2));
481      end
482      end
483      end
484      end
485  end
486
487
488 %currently run this outside of PlantProcesses
489 for i=1:size(Hstar,1)
490     for j=1:size(Hstar,2)
491         PC1(i,j)=P1(i,j,1)*(P1(i,j,1)>0);
492         PC2(i,j)=P2(i,j,1)*(P2(i,j,1)>0);
493         PC3(i,j)=P3(i,j,1)*(P3(i,j,1)>0);
494         PC4(i,j)=P4(i,j,1)*(P4(i,j,1)>0);
495
496     end
497 end
498 Ptot=PC1+PC2+PC3+PC4;
499
500
501 function Nl>NewNhd(R,C,PAB4)
502     if R<=(size(Hstar,1)-1)
503         R=floor(R);
504         Rp=R+1;
505     else
506         Rp=floor(R);
507     end
508     if R>=2
509         R=floor(R);
510         Rm=R-1;
511     else
512         Rm=floor(R);
513     end
514     if C<=(size(Hstar,2)-1)
515         C=floor(C);
516         Cp=C+1;
517     else
518         Cp=floor(C);
519     end
520     if C>=2
521         C=floor(C);
522         Gm=C-1;
523     else
524         Gm=floor(C);
525     end
526 Nl=zeros(1,8);

```

```

527 % PB4=PA(:,:,i);
528 N1=[PAB4(Rm,Cm),PAB4(Rm,C),PAB4(Rm,Cp),PAB4(R,Cp),PAB4(Rp,Cp),PAB4(Rp,C),PAB4(Rp,Cm),PAB4(R,Cm)];
529 for k=1:8
530 if N1(k)==-999
531 N1(k)=0;
532 elseif N1(k)<0.01
533 N1(k)=0;
534 end
535 end
536 end
537
538 end

```

B.5 Shoreline code

```

1 function [Hstar,MeanBeachWidth,ESL,WSL,MESL,MWSL,OL]=Shoreline03312021(Hstar,delta,L,BchMax)
2 %this function is just to return the eastern shoreline for plant initialization
3 %P4 not permitted to grow east of ESL - (E)astern (S)hore (L)ine
4
5 [n1 n2]=size(Hstar(:,:,1));
6 AL=zeros(n1,1); %AdjascentLength^width of beach
7 OL=zeros(n1,1); %OppositeLocation^innermost reach of beach/index of first cell>BchMax
8 ESL=zeros(n1,1); %EAST shoreline (column value per row);
9 WSL=zeros(n1,1); %formerly "WesternShore"
10 MESL=zeros(n1,1); %formerly "SlineSwamp"
11 MWSL=zeros(n1,1); %formerly "WBdrySwamp"
12
13 beta=zeros([n1 1]); %this gets called but isn't currently used, stores profile slope
14 Beta=zeros([n1 1]); %bruun rule beta
15
16 R=zeros(n1,1);
17 DC=zeros(n1,2);
18
19
20 dH=delta*Hstar(:,:,1); %making new array of Hstar values in terms of meters instead of slabs (ease of use)
21
22 for i=1:n1
23     Rnow=dH(i,:);
24     if Rnow(n2)<0
25         for j1=n2-1:-1:2 %declaring eastern shoreline by looking for first cell with positive elevation west of a
26             %cell with negative elevation
27             if Rnow(j1)>=0 && Rnow(j1+1)<=0 && ESL(i)==0
28                 if Rnow(j1-1)>=0
29                     ESL(i)=j1;
30                 end
31             end
32             if j1==2 && ESL(i)==0
33                 ESL(i)=ESL(i)+1*(Rnow(1)>=0); %special condition for first column - avoid index errors
34             end
35             if ESL(i)>=0 && ESL(i)>=1 %if we found a shoreline (that wasn't in col 1) need to declare AL and OL
36                 DC(i,2)=max(Rnow); %will use max of current row if no cell satisfies being greater than
37                 BchMax
38                 DC(i,1)=find(Rnow==DC(i,2),1,'last');
39                 flag=0;
40                 while flag==0
41                     for j2=j1-1:-1:1 % looking for dune crest starting with shoreline and moving
42                         % west
43                         if Rnow(j2)>=BchMax % if we find a cell >= BchMax
44                             OL(i)=j2;
45                             AL(i)=j1-j2;
46                             flag=1;
47                             break
48                         elseif Rnow(j2)<0 % if we go below water
49                             m=1;
50                             while j2-m>=1
51                                 if Rnow(j2-m)>0
52                                     j2=j2-m; %if we get back above water, change j2 and keep looking for
53                                     swamp/dune crest
54                                 m=1;
55                             end
56                         end
57                     end
58                 end
59             end
60         end
61     end
62 end

```

```

51      elseif Know(j2-m)<=-0.5
52          OL(i)=(j2)+find(Rnow(j2+1:j1)==max(Rnow(j2+1:j1)),1,'last'); % make the dune
53              crest the max height of the positive elevation portion of the island
54          AL(i)=j1-OL(i); %width of beach is shoreline index - the index of max height
55              of subaerial island
56          flag=1;
57          break
58      elseif m==j2-1
59          OL(i)=DC(i,1); %if we search the rest of the row and don't find swamp/dune
60              crest use max(row) as dune crest
61          AL(i)=j1-OL(i);
62          m=j2;
63          flag=1;
64      else
65          m=m+1;
66      end
67
68      end
69      if j2==1 %j2==2
70          OL(i)=DC(i,1); % make the dune crest the max height of the positive elevation portion
71              of the island
72          AL(i)=j1-OL(i); %width of beach is shoreline - the max height of subaerial island
73          flag=1;
74      end
75      elseif j2==1
76          OL(i)=DC(i,1); % make the dune crest the max height of the positive elevation portion of
77              the island
78          AL(i)=j1-OL(i); %width of beach is shoreline - the max height of subaerial island
79          flag=1;
80      end
81      end
82      if OL(i)>0 && AL(i)>0
83          break
84      end
85  end
86 end
87 end
88
89 for ii=1:n1
90 if ESL(ii)^=0
91     Rnow=dH(ii,:);
92     MWSL(ii)=find(Rnow>=-0.5,1,'first');
93     DC(ii)=find(Rnow==max(Rnow),1,'first');
94     SwmpChk=Rnow(MWSL(ii)+1:DC(ii));
95     j=find(SwmpChk>1,1,'first');
96     if isempty(j)==1
97         MESL(ii)=DC(ii);
98     else
99         MESL(ii)=MWSL(ii)+j;
100    end
101 end

```

```
102 end
103
104 MBWfactor=(AL~=0); %calculating changes in beach width - does nothing unless used outside fcn in an image
105 MeanBeachWidth=(sum(AL(MBWfactor))/sum(MBWfactor)); %same
106
107 end
```

B.6 Marine Processes code

```

1 function [Hstar,P3,MeanBeachWidth,ESL,WSL,MESL,MWSL,OL,SLRyrs,MigCnt,MigAccel]=MarineProcesses03312021(Hstar,delta,L,P1,P2,P3,P4,
      BchMax,OW,t,SLRyrs,PCmp,IslandArea,MigCnt,ScaleFactor,MigYr,Ma,MigAccel,MasterMax)
2 alpha=1;
3 AoR=pi/6;
4
5
6 T=t/26;
7 AccelCheck=MigYr*(Ma)^T
8 if floor(AccelCheck)>MigYr
9   Mig=floor(AccelCheck);
10 elseif AccelCheck==0
11   Mig=AccelCheck;
12 else
13   Mig=MigYr;
14 end
15
16 nn=5; %number of rows above and below current row to check plant density when calculating migration
17
18 if isnan(t)==1
19   Tflag=1;
20   t=0;
21 else
22   Tflag=0;
23 end
24
25 test=0;
26 SLR=0.00635; %was for Bruun Rule testing - not currently used
27 Htest=0; %handy in editing to just declare this
28 Ptest=0; %handy in editing to just declare this
29
30 [n1 n2]=size(Hstar(:,:,1));
31 AL=zeros(n1,1); %AdjascentLength^width of beach
32 OL=zeros(n1,1); %OppositeLocation^innermost reach of beach/index of first cell>BchMax
33 ESL=zeros(n1,1); %EAST shoreline (column value per row);
34 WSL=zeros(n1,1); %formerly "WesternShore"
35 MESL=zeros(n1,1); %formerly "SlineSwamp"
36 MWSL=zeros(n1,1); %formerly "WBndrySwamp"
37
38 beta=zeros([n1 1]); %this gets called but isn't currently used, stores profile slope
39 Beta=zeros([n1 1]); %bruun rule beta
40
41 R=zeros(n1,1);
42 DC=zeros(n1,2);
43
44
45 dH=delta*Hstar(:,:,1); %making new array of Hstar values in terms of meters instead of slabs (ease of use)
46
47 for i=1:n1
48   Rnow=dH(i,:);
49   Pnow=P3(i,:1);
50   PHnow=P3(i,:2);
51   if Rnow(n2)<0
52     for j1=n2-1:-1:2 %declaring eastern shoreline by looking for first cell with positive elevation west of a
53       cell with negative elevation

```

```

53      if Rnow(j1)>=0 && Rnow(j1+1)<=0 && ESL(i)==0
54          if Rnow(j1-1)==0
55              ESL(i)=j1;
56          end
57      end
58      if j1==2 && ESL(i)==0
59          ESL(i)=ESL(i)+1*(Rnow(1)>=0);           %special condition for first column - avoid index errors
60      end
61      if ESL(i)==0 && ESL(i)~=0
62          DC(i,2)=max(Rnow);
63          BchMax
64          DC(i,1)=find(Rnow==DC(i,2),1,'last');
65          flag=0;
66          while flag==0
67              for j2=j1-1:-1:1
68                  % looking for dune crest starting with shoreline and moving
69                  % west
70                  if Rnow(j2)>=BchMax
71                      OL(i)=j2;
72                      AL(i)=j1-j2;
73                      flag=1;
74                      break
75                  elseif Rnow(j2)<0
76                      m=1;
77                      while j2-m>=1
78                          if Rnow(j2-m)>0
79                              j2=j2-m;
80                              %if we get back above water, change j2 and keep looking for
81                              % swamp/dune crest
82                              m=1;
83                          elseif Rnow(j2-m)<=-0.5
84                              OL(i)=(j2)+find(Rnow(j2+1:j1)==max(Rnow(j2+1:j1)),1,'last');        % make the dune
85                              crest the max height of the positive elevation portion of the island
86                              AL(i)=j1-OL(i);           %width of beach is shoreline index - the index of max height
87                              of subaerial island
88                              flag=1;
89                              break
90                          elseif m==j2-1
91                              OL(i)=DC(i,1);           %if we search the rest of the row and don't find swamp/dune
92                              crest use max(row) as dune crest
93                          AL(i)=j1-OL(i);
94                          m=j2;
95                          flag=1;
96                      else
97                          m=m+1;
98                      end
99                  end
100                 if j2==1 %j2==2
101                     OL(i)=DC(i,1);           % make the dune crest the max height of the positive elevation portion
102                     of the island
103                     AL(i)=j1-OL(i);           %width of beach is shoreline - the max height of subaerial island
104                     flag=1;
105                 end
106                 elseif j2==1
107                     OL(i)=DC(i,1);           % make the dune crest the max height of the positive elevation portion of
108                     the island
109                     AL(i)=j1-OL(i);           %width of beach is shoreline - the max height of subaerial island

```

```

101           flag=1;
102       end
103       if OL(i)>0 && AL(i)>0
104           break
105       end
106   end
107 end
108 if OL(i)>0 && AL(i)>0
109     break
110 end
111 end
112 end
113 if ESL(i)>1          %if the island has been found in this row
114     for m=0:AL(i)        %removing P3 from the beach
115         j=OL(i)+m;
116         if Pnow(j)>0
117             Pnow(j)=0;
118             PHnow(j)=0;
119         end
120     end
121     P3(i,:,:,1)=Pnow;
122     P3(i,:,:,2)=PHnow;
123 elseif ESL(i)==1      %if shoreline is first cell make OL, AL first cell
124     OL(i)=1;
125     AL(i)=1;
126     if Pnow(1)>0
127         Pnow(1)=0;
128         PHnow(1)=0;
129     end
130 end
131 end
132 end
133
134 MBWfactor=(AL~=0); %calculating changes in beach width - does nothing unless used outside fcn in an image
135 MeanBeachWidth=(sum(AL(MBWfactor))/sum(MBWfactor)); %same
136
137
138
139 %now calculating the foreshore slope and resetting cells
140 cnt=0;
141 DofCi=zeros(n1,1);
142 xdoc=sym('xdoc');
143
144 for i=1:n1
145     if ESL(i)>0
146         cnt=cnt+1;
147         Rnow=dH(i,:);
148         if AL(i)~=0 %if we have a shoreline and the adjacent length is not zero
149             beta(i)=tan(Rnow(OL(i))/AL(i)); %calculate the slope of the shoreline
150             R(i)=1/beta(i);                %part of Bruun rule - unused
151         elseif AL(i)==0
152             beta(i)=.0003;    %if there is a shore that is one cell wide (special condition above) use common shore slope
153             R(i)=1/beta(i);
154         end
155     end
156 end

```

```

157 cnt=0;
158 shortR=0; %for removing NaN and infinity slopes - possible with holes and ponds, but unlikely (pretty sure I debugged this issue)
159 for i=1:n1
160     if ESL(i)>0
161         cnt=cnt+1;
162         shortR(cnt)=R(i);%*(isnan(R(i)==0)); %uncomment this if NaN issue (see above) comes up
163     end
164 end
165 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
166 %%for-Vector-of-Migration-Years%%
167 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
168 %below is for using a vector of predetermined years to trigger migration
169 % YrsPast=sum(SLRyrs(SLRyrs<0)); %any negative years in vector are summed
170 % YrCnt=(t/26)+YrsPast; %current number of years since last migration
171 % if YrCnt==max(SLRyrs(SLRyrs>0)) %if current #yrs is the next number of years in vector of values to trigger
172 % migration
173 % MigChk=1; %trigger migration
174 % kk=find(SLRyrs==max(SLRyrs(SLRyrs>0))); %find that yr value in vector
175 % SLRyrs(kk)=-SLRyrs(kk); %replace with negative year so it will be summed as years past
176 % else
177 % MigChk=0;
178 % end
179 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
180 %%END%%
181 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
182 %%For_Yearly_Migration%%
183 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
184 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
185
186 Plx=zeros(n1,1);
187 if 0==mod(t,26)% && t~=0
188     MigChk=1;
189     if MigChk==1
190         for i=1:n1
191             if i<nn
192                 PlChkArea=PCmp(1:1+nn,: ,1); %plant cover for rows near current row
193                 Plx(i)=mean(PlChkArea(PlChkArea>=0));
194                 if sum(dH(i,: )>=0)==0
195                     MigCnt(i)=MigCnt(i)+Mig;
196                 else
197                     if Plx(i) >= 0.3
198                         MigCnt(i)=MigCnt(i)+round(0.00*Mig); %reduce migration by 70% if nearby weighted plant cover exceeds 50%
199                     elseif Plx(i) >= 0.2 && Plx(i) < 0.3
200                         MigCnt(i)=MigCnt(i)+round(0.3*Mig); %reduce migration by 50% if nearby weighted plant cover exceeds 35%
201                         but not 50%
202                     elseif Plx(i) >= 0.1 && Plx(i) < 0.1
203                         MigCnt(i)=MigCnt(i)+round(0.5*Mig); %reduce migration by 30% if nearby weighted plant cover exceeds 10%
204                         but not 35%
205                 else
206                     MigCnt(i)=MigCnt(i)+Mig; %full effect of migration if nearby plant cover less than 10%
207                 end
208             end
209             if MigCnt(i)>ScaleFactor
210                 %set MigR=1 if using scaled version of
211                 migration

```

```

209     MigR=floor(MigCnt(i)/ScaleFactor);
210     fprintf('\n')
211     fprintf('THE SHORELINE AT ROW %d IS MIGRATING EAST BY %d COLUMNS!',i,MigR)
212     RnowDummy=zeros(1,n2);
213     P1RnowDummy=RnowDummy;
214     P2RnowDummy=RnowDummy;
215     P3RnowDummy=RnowDummy;
216     P4RnowDummy=RnowDummy;
217     RnowDummy(1:n2-MigR)=dH(i,MigR+1:n2);
218     P1RnowDummy(1:n2-MigR)=P1(i,MigR+1:n2);
219     P2RnowDummy(1:n2-MigR)=P1(i,MigR+1:n2);
220     P3RnowDummy(1:n2-MigR)=P1(i,MigR+1:n2);
221     P4RnowDummy(1:n2-MigR)=P1(i,MigR+1:n2);
222     dH(i,1:n2-MigR)=RnowDummy(1:n2-MigR);
223     P1(i,1:n2-MigR)=P1RnowDummy(1:n2-MigR);
224     P2(i,1:n2-MigR)=P1RnowDummy(1:n2-MigR);
225     P3(i,1:n2-MigR)=P1RnowDummy(1:n2-MigR);
226     P4(i,1:n2-MigR)=P1RnowDummy(1:n2-MigR);
227     MigCnt(i)=MigCnt(i)-MigR*ScaleFactor;
228     end
229 elseif nn<i && i<n1-nn
230 if i>2000
231 %    fprintf('oo')
232 %
233 PIChkArea=PCmp(i-nn:i+nn,:); %plant cover for rows near current row
234 Plx(i)=mean(PIChkArea(PIChkArea>=0));
235 if sum(dH(i,:)>=0)==0
236     MigCnt(i)=MigCnt(i)+Mig;
237 else
238     if Plx(i) >= 0.3
239         MigCnt(i)=MigCnt(i)+round(0.00*Mig); %reduce migration by 70% if nearby weighted plant cover exceeds 50%
240     elseif Plx(i) >= 0.2 && Plx(i) < 0.3
241         MigCnt(i)=MigCnt(i)+round(0.3*Mig); %reduce migration by 50% if nearby weighted plant cover exceeds 35%
242             but not 50%
243     elseif Plx(i) >= 0.1 && Plx(i) < 0.2
244         MigCnt(i)=MigCnt(i)+round(0.5*Mig); %reduce migration by 30% if nearby weighted plant cover exceeds 10%
245             but not 35%
246     else
247         MigCnt(i)=MigCnt(i)+Mig; %full effect of migration if nearby plant cover less than 10%
248     end
249 end
250 if MigCnt(i)>ScaleFactor
251 %    MigR=1; %set MigR=1 if using scaled version of
252 %    migration
253 MigR=floor(MigCnt(i)/ScaleFactor);
254 fprintf('\n')
255 fprintf('THE SHORELINE AT ROW %d IS MIGRATING EAST BY %d COLUMNS!',i,MigR)
256 RnowDummy=zeros(1,n2);
257 P1RnowDummy=RnowDummy;
258 P2RnowDummy=RnowDummy;
259 P3RnowDummy=RnowDummy;
260 P4RnowDummy=RnowDummy;
261 RnowDummy(1:n2-MigR)=dH(i,MigR+1:n2);
262 P1RnowDummy(1:n2-MigR)=P1(i,MigR+1:n2);
263 P2RnowDummy(1:n2-MigR)=P1(i,MigR+1:n2);
264 P3RnowDummy(1:n2-MigR)=P1(i,MigR+1:n2);

```

```

262 P4RnowDummy(1:n2-MigR)=P1(i,MigR+1:n2);
263 dH(i,1:n2-MigR)=RnowDummy(1:n2-MigR);
264 P1(i,1:n2-MigR)=PIRnowDummy(1:n2-MigR);
265 P2(i,1:n2-MigR)=PIRnowDummy(1:n2-MigR);
266 P3(i,1:n2-MigR)=PIRnowDummy(1:n2-MigR);
267 P4(i,1:n2-MigR)=PIRnowDummy(1:n2-MigR);
268 MigCnt(i)=MigCnt(i)-MigR*ScaleFactor;
269 end
270 elseif i>n1-nn
271 PIChkArea=PCmp(n1-nn:n1,:,1); %plant cover for nows near current row
272 Plx(i)=mean(PIChkArea(PIChkArea>=0));
273 if sum(dH(i,:)>=0)==0
274     MigCnt(i)=MigCnt(i)+Mig;
275 else
276     if Plx(i) >= 0.5
277         MigCnt(i)=MigCnt(i)+round(0.00*Mig); %reduce migration by 70% if nearby weighted plant cover exceeds 50%
278     elseif Plx(i) >= 0.35 && Plx(i) < 0.5
279         MigCnt(i)=MigCnt(i)+round(0.3*Mig); %reduce migration by 50% if nearby weighted plant cover exceeds 35%
280             but not 50%
281     elseif Plx(i) >= 0.1 && Plx(i) < 0.35
282         MigCnt(i)=MigCnt(i)+round(0.5*Mig); %reduce migration by 30% if nearby weighted plant cover exceeds 10%
283             but not 35%
284     else
285         MigCnt(i)=MigCnt(i)+Mig; %full effect of migration if nearby plant cover less than 10%
286     end
287 end
288 if MigCnt(i)>ScaleFactor
289     %                               MigR=1;                                %set MigR=1 if using scaled version of
290     migration
291     MigR=floor(MigCnt(i)/ScaleFactor);
292     fprintf('\n')
293     fprintf('THE SHORELINE AT ROW %d IS MIGRATING EAST BY %d COLUMNS!',i,MigR)
294 RnowDummy=zeros(1,n2);
295 P1RnowDummy=RnowDummy;
296 P2RnowDummy=RnowDummy;
297 P3RnowDummy=RnowDummy;
298 P4RnowDummy=RnowDummy;
299 RnowDummy(1:n2-MigR)=dH(i,MigR+1:n2);
300 P1RnowDummy(1:n2-MigR)=P1(i,MigR+1:n2);
301 P2RnowDummy(1:n2-MigR)=P1(i,MigR+1:n2);
302 P3RnowDummy(1:n2-MigR)=P1(i,MigR+1:n2);
303 P4RnowDummy(1:n2-MigR)=P1(i,MigR+1:n2);
304 dH(i,1:n2-MigR)=RnowDummy(1:n2-MigR);
305 P1(i,1:n2-MigR)=PIRnowDummy(1:n2-MigR);
306 P2(i,1:n2-MigR)=PIRnowDummy(1:n2-MigR);
307 P3(i,1:n2-MigR)=PIRnowDummy(1:n2-MigR);
308 P4(i,1:n2-MigR)=PIRnowDummy(1:n2-MigR);
309 MigCnt(i)=MigCnt(i)-MigR*ScaleFactor;
310 end
311 end
312 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%END%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
313 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%END%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
314 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%END%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%

```

```

315
316 % *****RESETTING EQUILIBRIUM PROFILE OF SHORELINE HAS BEEN REMOVED FOR THIS VERSION*****
317 % ***see Fix2MarineProcesses02202021 for most recent version of resetting profile ***
318
319 dH=round(dH,1); %need to round to 1 dec. place if redeclared shoreline
320 Hstar(:,1)=(1/delta)*dH; %convert back to slabs when redeclaring Hstar
321
322 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
323 if Tflag==1
324     t=NaN; %reset t if this is initialization MP so it doesn't throw off loop in MainCode
325 end
326
327 end

```